

Dr. Z.'s Calc4 Lecture 21 Handout:

The Case of Repeated Roots When Solving Homogeneous Linear Systems with Constant Coefficients

By Doron Zeilberger

It sometimes happens that when we try to find solutions of homog. systems of linear diff. eqs. with constant coefficients, of the form

$$\mathbf{x}(t) = \mathbf{v} e^{rt} \quad ,$$

where  $\mathbf{v}$  is a **CONSTANT** vector and  $r$  is some number, and follow the procedure of Lecture 19, trying to find the eigenvalues of the matrix  $\mathbf{P}$ , the characteristic equation has **repeated roots**.

For each such repeated eigenvalue  $r$ , we can get at least one eigenvector,  $\mathbf{v}$  and we immediately get **one** fundamental solution. If it is repeated  $k$  times, and we get a basis of  $k$  independent eigenvectors, then it is exactly as before. But if there are fewer we have to proceed as follows.

We will only consider double roots in this class. If  $r$  is a double eigenvalue with **one**-dimensional eigenspace, i.e., up to constant multiples, we have **one** eigenvector, let's call it  $\mathbf{v}$ , then **one** fundamental solution is

$$\mathbf{x}_1(t) = \mathbf{v} e^{rt} \quad .$$

To find another one,  $\mathbf{x}_2(t)$ , we try out the **template**

$$\mathbf{x}_2(t) = \mathbf{v} t e^{rt} + \mathbf{u} e^{rt} \quad ,$$

for some **yet to be determined** vector  $\mathbf{u}$ .

We have

$$\mathbf{x}'_2(t) = \mathbf{v} r t e^{rt} + \mathbf{v} e^{rt} + r \mathbf{u} e^{rt} \quad ,$$

Since we want

$$\mathbf{x}'_2(t) = \mathbf{P} \mathbf{x}_2(t) \quad ,$$

we have

$$r \mathbf{v} t e^{rt} + \mathbf{v} e^{rt} + r \mathbf{u} e^{rt} = \mathbf{P} (\mathbf{v} t e^{rt} + \mathbf{u} e^{rt})$$

But  $r \mathbf{v} = \mathbf{P} \mathbf{v}$ , so

$$\mathbf{v} e^{rt} = (\mathbf{P} - r \mathbf{I}) \mathbf{u} e^{rt} \quad .$$

Dividing by  $e^{rt}$  we get a vector equation for the vector  $\mathbf{u}$ :

$$(\mathbf{P} - r \mathbf{I}) \mathbf{u} = \mathbf{v} \quad .$$

**Problem 21.1**

Find the general solution of the system

$$\mathbf{x}'(t) = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix} \mathbf{x}(t) \quad .$$

**Step 1.** Write down the matrix of coefficients, and set-up the **characteristic equation**.

$$\mathbf{P} = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix}$$
$$\det \begin{pmatrix} 3-r & -4 \\ 1 & -1-r \end{pmatrix} = 0 \quad .$$

**Step 2.** Compute the determinant, and solve the characteristic equation, finding the eigenvalues.

$$(3-r)(-1-r) - (-4)(1) = 0 \quad ,$$
$$(r-3)(r+1) + 4 = 0$$
$$r^2 - 2r - 3 + 4 = 0 \quad ,$$
$$r^2 - 2r + 1 = 0 \quad .$$
$$(r-1)^2 = 0 \quad .$$

So we have a **repeated** eigenvalue  $r = 1$ .

**Step 3.** Find the eigenvector (or eigenvectors) corresponding to that root.

$$\begin{pmatrix} 3-r & -4 \\ 1 & -1-r \end{pmatrix} \quad .$$

becomes

$$\begin{pmatrix} 3-1 & -4 \\ 1 & -1-1 \end{pmatrix} = \begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \quad .$$

We have to find a vector  $(a_1, a_2)^T$  such that

$$\begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \quad .$$

Spelling it out:

$$2a_1 - 4a_2 = 0 \quad , \quad a_1 - 2a_2 = 0 \quad .$$

These two equations are multiple of each other, so it is enough to consider one of them, so let's pick the second, that is simpler. We have  $a_1 = 2a_2$ . So taking  $a_2 = 1$  we get that  $a_1 = 2$ .

So an eigenvector corresponding to  $r = 1$  is  $\mathbf{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ .

So **one** fundamental solution is

$$\mathbf{x}_1(t) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t$$

Since we have only **one** (linearly independent) eigenvector, we must find **u**.

**Step 4.** Putting  $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}$  we have to solve

$$\begin{pmatrix} 2 & -4 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix} .$$

Spelling it out, we have to solve

$$2u_1 - 4u_2 = 2 \quad , \quad u_1 - 2u_2 = 1 \quad .$$

Note that the second equation is a multiple of the first, and there are infinitely many answers, so let's put  $u_2 = 0$ ,  $u_1 = 1$ . and we get  $\mathbf{u} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ .

(**Note:** We could have taken anything for  $u_2$ , it is just simplest to take  $u_2 = 0$ .)

So a second fundamental solution is

$$\mathbf{x}_2(t) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} te^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \quad .$$

**Finally, the general solution** is  $\mathbf{x}(t) = c_1\mathbf{x}_1(t) + c_2\mathbf{x}_2(t)$  where  $c_1, c_2$  are arbitrary constants, so the general solution is

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t + c_2 \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} te^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right)$$

**Ans. to 21.1:**  $\mathbf{x}(t) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t + c_2 \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} te^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right) \quad .$

### **Problem 21.2**

Solve the initial value system

$$\mathbf{x}'(t) = \begin{pmatrix} 3 & -4 \\ 1 & -1 \end{pmatrix} \mathbf{x}(t) \quad , \quad \mathbf{x}(0) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad .$$

**Steps 1-4.** Find the general solution exactly as in Problem 21.1.

$$\mathbf{x}(t) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t + c_2 \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} te^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right)$$

**Step 5:** Plug in  $t = 0$  (or, in general  $t = t_0$ , if the initial condition is not at 0).

$$\mathbf{x}(0) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^0 + c_2 \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} 0 \cdot e^0 + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^0 \right) = c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

**Step 6:** Set it equal to the vector  $\mathbf{x}(0)$  given by the problem,

$$\begin{pmatrix} 2c_1 + c_2 \\ c_1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad ,$$

and spelled-out:

$$2c_1 + c_2 = 1 \quad , \quad c_1 = 1 \quad ,$$

and solve for  $c_1, c_2$ .

Here  $c_1 = 1$  and  $c_2 = -1$ .

**Step 7.** Go back to the general solution and enter the  $c_1, c_2$  that you just found.

$$\begin{aligned} \mathbf{x}(t) &= \mathbf{x}(t) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t - \left( \begin{pmatrix} 2 \\ 1 \end{pmatrix} t e^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right) \\ &= e^t \begin{pmatrix} 1 - 2t \\ 1 - t \end{pmatrix} \end{aligned}$$

**Ans. to Problem 21.2 :**  $\mathbf{x}(t) = e^t \begin{pmatrix} 1 - 2t \\ 1 - t \end{pmatrix}$  or

$$x_1(t) = (-2t + 1)e^t \quad , \quad x_2(t) = (-t + 1)e^t.$$