

action and  $X$  a real-valued random

$X]$ .

ple 2.4.7) of the discounted price  
-paying stock as the smallest  $\mathbb{Q}$ -  
 $\rangle_+\}_{n \geq 0}$  to prove that the price of an  
the same as that of a European call

### 3 Brownian motion

#### Summary

Our discrete models are only a crude approximation to the way in which stock markets actually move. A better model would be one in which stock prices can change at any instant. As early as 1900 Bachelier, in his thesis 'La théorie de la spéculation', proposed Brownian motion as a model of the fluctuations of stock prices. Even today it is the building block from which we construct the basic reference model for a continuous time market. Before we can proceed further we must leave finance to define and construct Brownian motion.

Our first approach will be to continue the heuristic of §2.6 by considering Brownian motion as an 'infinitesimal' random walk in which smaller and smaller steps are taken at ever more frequent time intervals. This will lead us to a natural definition of the process. A formal construction, due to Lévy, will be given in §3.2, but this can safely be omitted. Next, §3.3 establishes some facts about the process that we shall require in later chapters. This material too can be skipped over and referred back to when it is used.

Just as discrete parameter martingales play a key rôle in the study of random walks, so for Brownian motion we shall use continuous time martingale theory to simplify a number of calculations; §3.4 extends our definitions and basic results on discrete parameter martingales to the continuous time setting.

#### 3.1 Definition of the process

The easiest way to think about Brownian motion is as an 'infinitesimal random walk' and that is often how it arises in applications, so to motivate the formal definition we first study simple random walks.

A characteri-  
sation of  
simple ran-  
dom walks

We declared in Example 2.3.7 that the stochastic process  $\{S_n\}_{n \geq 0}$  is a simple random walk under the measure  $\mathbb{P}$  if  $S_n = \sum_{i=1}^n \xi_i$  where the  $\xi_i$  can take only the values  $\{-1, +1\}$  and are independent and identically distributed under  $\mathbb{P}$ . We concentrate

on the *symmetric* case when

$$\mathbb{P}[\xi_i = -1] = \frac{1}{2} = \mathbb{P}[\xi_i = +1].$$

This process is often motivated as a model of the gains from repeated plays of a fair game. For example, suppose I play a game with a friend in which each play is equivalent to flipping a fair coin. If it comes up heads I pay her a dollar, otherwise she pays me a dollar. For each  $n$ ,  $S_n$  models my net gain after  $n$  plays.

Recall from Exercise 13 of Chapter 2 that  $\mathbb{E}[S_n] = 0$  and  $\text{var}(S_n) = n$ .

**Lemma 3.1.1**  $\{S_n\}_{n \geq 0}$  is a  $\mathbb{P}$ -martingale (with respect to the natural filtration) and

$$\text{cov}(S_n, S_m) = n \wedge m.$$

**Proof:** We checked in Example 2.3.7 that  $\{S_n\}_{n \geq 0}$  is a  $\mathbb{P}$ -martingale. It remains to calculate the covariance.

$$\begin{aligned} \text{cov}(S_n, S_m) &= \mathbb{E}[S_n S_m] - \mathbb{E}[S_n] \mathbb{E}[S_m] \\ &= \mathbb{E}[\mathbb{E}[S_n S_m | \mathcal{F}_{m \wedge n}]] \quad (\text{tower property}) \\ &= \mathbb{E}[S_{m \wedge n} \mathbb{E}[S_{m \vee n} | \mathcal{F}_{m \wedge n}]] \\ &= \mathbb{E}[S_{m \wedge n}^2] \quad (\text{martingale property}) \\ &= \text{var}(S_{m \wedge n}) = m \wedge n. \end{aligned}$$

As a result of the independence of the random variables  $\{\xi_i\}_{i \geq 1}$ , if  $0 \leq i \leq j \leq l$ , then  $S_j - S_i$  is independent of  $S_l - S_k$ . More generally, if  $0 \leq i_1 \leq i_2 \leq \dots \leq i_r$  and  $0 \leq j_1 \leq j_2 \leq \dots \leq j_r$  are two increasing sequences of integers such that  $j_r - i_r = l - k = m$ , then  $S_{j_r} - S_{i_r}$  and  $S_{j_1} - S_{i_1}$  are independent. Moreover, if  $j - i = l - k = m$ , then  $S_j - S_i$  and  $S_l - S_k$  both have the same distribution as  $S_m$ .

**Notation:** For two random variables  $X$  and  $Y$  we write

$$X \stackrel{\mathcal{D}}{=} Y$$

to mean that  $X$  and  $Y$  have the same distribution.

We also write  $X \sim N(\mu, \sigma^2)$  to mean that  $X$  is normally distributed with mean  $\mu$  and variance  $\sigma^2$ .

Combining the observations above we have

**Lemma 3.1.2** Under the measure  $\mathbb{P}$  the process  $\{S_n\}_{n \geq 0}$  has stationary, independent increments.

Lemmas 3.1.1 and 3.1.2 are actually enough to *characterise* symmetric simple random walks.

$$[\xi_i = +1].$$

the gains from repeated plays of a  
with a friend in which each play is  
heads I pay her a dollar, otherwise  
net gain after  $n$  plays.

$$S_n] = 0 \text{ and } \text{var}(S_n) = n.$$

with respect to the natural filtration)

$$\wedge m.$$

$n \geq 0$  is a  $\mathbb{P}$ -martingale. It remains to

$$\mathbb{E}[S_m]$$

]] (tower property)

$$[\mathcal{F}_{m \wedge n}]$$

(martingale property)

$$\wedge n.$$

Rescaling  
random  
walks

Definition of  
Brownian  
motion

□

variables  $\{\xi_i\}_{i \geq 1}$ , if  $0 \leq i \leq j \leq k \leq$   
generally, if  $0 \leq i_1 \leq i_2 \leq \dots \leq i_n,$   
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cess  $\{S_n\}_{n \geq 0}$  has stationary, indepen-

Recall that we want to think of Brownian motion as an infinitesimal random walk. In terms of our gambling game, the time interval between plays is  $\delta t$  and the stake is  $\delta x$  say, and we are thinking of both of these as 'tending to zero'. In order to obtain a non-trivial limit, there has to be a relationship between  $\delta t$  and  $\delta x$ . To see what this must be, we use the Central Limit Theorem (stated in §2.6). In our setting,  $\mu = \mathbb{E}[\xi_i] = 0$  and  $\sigma^2 = \text{var}(\xi_i) = 1$ . Thus, taking  $\delta t = 1/n$  and  $\delta x = 1/\sqrt{n}$ ,

$$\mathbb{P}\left[\frac{S_n}{\sqrt{n}} \leq x\right] \rightarrow \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-y^2/2} dy \text{ as } n \rightarrow \infty.$$

More generally,

$$\mathbb{P}\left[\frac{S_{[nt]}}{\sqrt{n}} \leq x\right] \rightarrow \int_{-\infty}^x \frac{1}{\sqrt{2\pi t}} e^{-y^2/2t} dy \text{ as } n \rightarrow \infty,$$

where  $[nt]$  denotes the integer part of  $nt$  (Exercise 1). For the limiting process, at time  $t$  our net gain since time zero will be normally distributed with mean zero and variance  $t$ .

Just as in our definition of a discrete time stochastic process, to define a continuous time stochastic process  $\{X_t\}_{t \geq 0}$  (formally) requires a probability triple  $(\Omega, \mathcal{F}, \mathbb{P})$  such that  $X_t$  is  $\mathcal{F}$ -measurable for all  $t$ . However, as in the discrete case, we shall rarely specify  $\Omega$  explicitly.

Heuristically, passage to the limit in the random walk suggests that the following is a reasonable definition of Brownian motion.

**Definition 3.1.3 (Brownian motion)** A real-valued stochastic process  $\{W_t\}_{t \geq 0}$  is a  $\mathbb{P}$ -Brownian motion (or a  $\mathbb{P}$ -Wiener process) if for some real constant  $\sigma$ , under  $\mathbb{P}$ ,

- 1 for each  $s \geq 0$  and  $t > 0$  the random variable  $W_{t+s} - W_s$  has the normal distribution with mean zero and variance  $\sigma^2 t$ ,
- 2 for each  $n \geq 1$  and any times  $0 \leq t_0 \leq t_1 \leq \dots \leq t_n$ , the random variables  $\{W_{t_r} - W_{t_{r-1}}\}$  are independent,
- 3  $W_0 = 0$ ,
- 4  $W_t$  is continuous in  $t \geq 0$ .

**Remarks:** Conditions 1 and 2 ensure that, like its discrete counterpart, Brownian motion has stationary independent increments.

Condition 3 is a convention. Brownian motion started from  $x$  can be obtained as  $\{x + W_t\}_{t \geq 0}$ .

In a certain sense condition 4 is a consequence of the first three, but we should like to insist once and for all that all paths that our Brownian motion can follow are continuous. □

The parameter  $\sigma^2$  is known as the *variance* parameter. By scaling of the  $n$  distribution it is immediate that  $\{W_{t/\sigma}\}_{t \geq 0}$  is a Brownian motion with variance parameter one.

**Definition 3.1.4**     *The process with  $\sigma^2 = 1$  is called standard Brownian motion.*

**Assumption:** Unless otherwise stated we shall always assume that  $\sigma^2 = 1$

Combining conditions 1 and 2 of Definition 3.1.3, we can write down the *transition probabilities* of standard Brownian motion.

$$\begin{aligned} \mathbb{P}[W_{t_n} \leq x_n | W_{t_i} = x_i, 0 \leq i \leq n-1] &= \mathbb{P}[W_{t_n} - W_{t_{n-1}} \leq x_n - x_{n-1}] \\ &= \int_{-\infty}^{x_n - x_{n-1}} \frac{1}{\sqrt{2\pi(t_n - t_{n-1})}} \exp\left(-\frac{u^2}{2(t_n - t_{n-1})}\right) du \end{aligned}$$

**Notation:** We write  $p(t, x, y)$  for the *transition density*

$$p(t, x, y) = \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{(x - y)^2}{2t}\right).$$

This is the probability density function of the random variable  $W_{t+s}$  conditioned on  $W_s = x$ .

For  $0 = t_0 \leq t_1 \leq t_2 \leq \dots \leq t_n$ , writing  $x_0 = 0$ , the joint probability density function of  $W_{t_1}, \dots, W_{t_n}$  can also be written down explicitly as

$$f(x_1, \dots, x_n) = \prod_{j=1}^n p(t_j - t_{j-1}, x_{j-1}, x_j).$$

The joint distributions of  $W_{t_1}, \dots, W_{t_n}$  for each  $n \geq 1$  and all  $t_1, \dots, t_n$  are the *finite dimensional distributions* of the process.

The following analogue of Lemma 3.1.1 is immediate.

**Lemma 3.1.5**     *For any  $s, t > 0$ ,*

- 1  $\mathbb{E}[W_{t+s} - W_s | \{W_r\}_{0 \leq r \leq s}] = 0,$
- 2  $\text{cov}(W_s, W_t) = s \wedge t.$

In fact since the multivariate normal distribution is determined by its mean and covariances and normally distributed random variables are independent if and

parameter. By scaling of the normal  
a Brownian motion with variance

called standard Brownian motion.

will always assume that  $\sigma^2 = 1$ .

l.3, we can write down the transition

$$\frac{1}{\sqrt{2\pi(t_n - t_{n-1})}} \exp\left(-\frac{u^2}{2(t_n - t_{n-1})}\right) du.$$

ition density

$$\left(\frac{(x - y)^2}{2t}\right).$$

random variable  $W_{t+s}$  conditional on  
 $x_0 = 0$ , the joint probability density  
own explicitly as

$$-t_{j-1}, x_{j-1}, x_j).$$

h  $n \geq 1$  and all  $t_1, \dots, t_n$  are called  
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immediate.

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variables are independent if and only

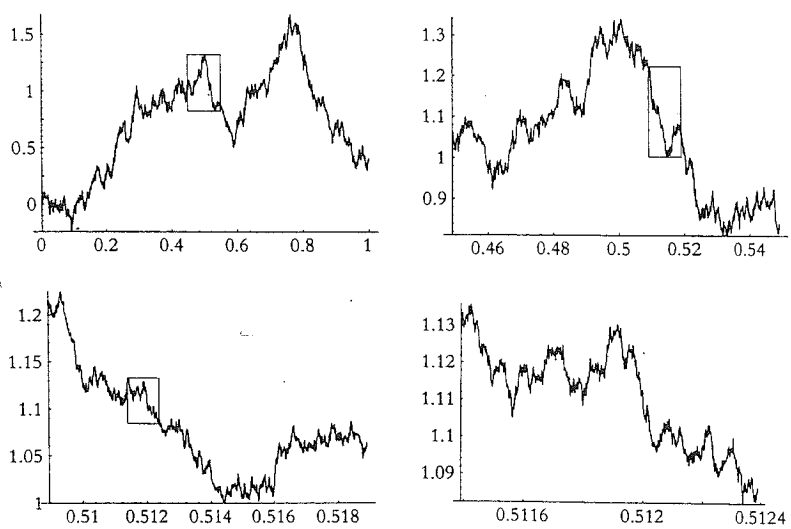


Figure 3.1 Zooming in on Brownian motion.

if their covariances are zero, this, combined with continuity of paths, characterises standard Brownian motion.

Behaviour of  
Brownian  
motion

Just because the sample paths of Brownian motion are continuous, it does not mean that they are nice in any other sense. In fact the behaviour of Brownian motion is distinctly odd. Here are just a few of its strange behavioural traits.

- 1 Although  $\{W_t\}_{t \geq 0}$  is continuous everywhere, it is (with probability one) differentiable nowhere.
- 2 Brownian motion will eventually hit any and every real value no matter how large, or how negative. No matter how far above the axis, it will (with probability one) be back down to zero at some later time.
- 3 Once Brownian motion hits a value, it immediately hits it again *infinitely* often (and will continue to return after arbitrarily large times).
- 4 It doesn't matter what scale you examine Brownian motion on, it looks just the same. Brownian motion is a fractal.

Exercise 9 shows that the process cannot be differentiable at  $t = 0$ . We shall discuss some properties related to the hitting probabilities in §3.3 and in Exercise 8. The scaling alluded to in our last comment is formally proved in Proposition 3.3.7. It is really a consequence of the construction of the process. Figure 3.1 illustrates the result for a particular realisation of a Brownian path.

That such a bizarre process actually *exists* is far from obvious and so it is to this that we turn our attention in the next section.

### 3.2 Lévy's construction of Brownian motion

We have hinted that Brownian motion can be obtained as a limit of random walk. However, rather than chasing the technical details of the random walk construction in this section we present an alternative construction due to Lévy. This can be obtained by readers willing to take existence of the process on trust.

A polygonal approximation.

The idea is that we can simply produce a path of Brownian motion by a polygonal interpolation. We require just one calculation.

**Lemma 3.2.1** Suppose that  $\{W_t\}_{t \geq 0}$  is standard Brownian motion. Condition on  $W_{t_1} = x_1$ , the probability density function of  $W_{t_1/2}$  is

$$p_{t_1/2}(x) \triangleq \sqrt{\frac{2}{\pi t_1}} \exp\left(-\frac{1}{2} \left(\frac{(x - \frac{1}{2}x_1)^2}{t_1/4}\right)\right).$$

In other words, the conditional distribution is a normally distributed random variable with mean  $x_1/2$  and variance  $t_1/4$ . The proof is Exercise 11.

**The construction:** Without loss of generality we take the range of  $t$  to be  $[0, 1]$ . Let the construction builds (inductively) a polygonal approximation to the Brownian motion from a countable collection of *independent* normally distributed random variables with mean zero and variance one. We index them by the dyadic points of  $[0, 1]$ , a generic variable being denoted by  $\xi(k2^{-n})$  where  $n \in \mathbb{N}$  and  $k \in \{0, 1, \dots, 2^n\}$ .

The induction begins with

$$X_1(t) = t\xi(1).$$

Thus  $X_1$  is a linear function on  $[0, 1]$ .

The  $n$ th process,  $X_n$ , is linear in each interval  $[(k-1)2^{-n}, k2^{-n}]$ , is continuous in  $t$  and satisfies  $X_n(0) = 0$ . It is thus determined by the values  $\{X_n(k2^{-n}), 1, \dots, 2^n\}$ .

**The inductive step:** We take

$$X_{n+1}(2k2^{-(n+1)}) = X_n(2k2^{-(n+1)}) = X_n(k2^{-n}).$$

We now determine the appropriate value for  $X_{n+1}((2k-1)2^{-(n+1)})$ . Condition on  $X_{n+1}(2k2^{-(n+1)}) - X_{n+1}((2k-1)2^{-(n+1)})$ , Lemma 3.2.1 tells us that

$$X_{n+1}((2k-1)2^{-(n+1)}) - X_{n+1}(2k2^{-(n+1)})$$

should be normally distributed with mean

$$\frac{1}{2} \left( X_{n+1}(2k2^{-(n+1)}) - X_{n+1}((2k-1)2^{-(n+1)}) \right)$$

and variance  $2^{-(n+2)}$ .

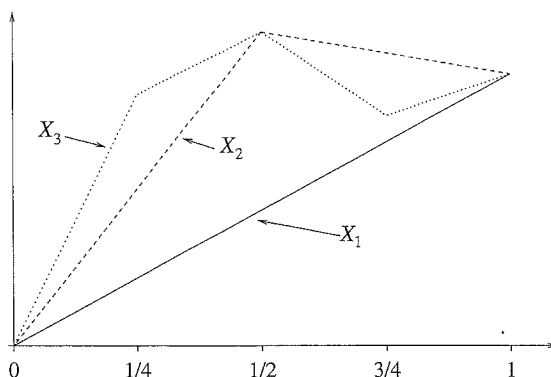


Figure 3.2 Lévy's sequence of polygonal approximations to Brownian motion.

Now if  $X \sim N(0, 1)$ , then  $aX + b \sim N(b, a^2)$  and so we take

$$\begin{aligned} X_{n+1} \left( (2k-1)2^{-(n+1)} \right) - X_{n+1} \left( (k-1)2^{-n} \right) \\ = 2^{-(n/2+1)} \xi \left( (2k-1)2^{-(n+1)} \right) \\ + \frac{1}{2} \left( X_{n+1} \left( 2k2^{-(n+1)} \right) - X_{n+1} \left( 2(k-1)2^{-(n+1)} \right) \right). \end{aligned}$$

In other words

$$\begin{aligned} X_{n+1} \left( (2k-1)2^{-(n+1)} \right) &= \frac{1}{2} X_n \left( (k-1)2^{-n} \right) \\ &\quad + \frac{1}{2} X_n \left( k2^{-n} \right) + 2^{-(n/2+1)} \xi \left( (2k-1)2^{-(n+1)} \right) \\ &= X_n \left( (2k-1)2^{-(n+1)} \right) \\ &\quad + 2^{-(n/2+1)} \xi \left( (2k-1)2^{-(n+1)} \right), \end{aligned} \quad (3.1)$$

where the last equality follows by linearity of  $X_n$  on  $[(k-1)2^{-n}, k2^{-n}]$ .

The construction is illustrated in Figure 3.2.

Convergence  
to Brownian  
motion

Brownian motion will be the process constructed by letting  $n$  increase to infinity. To check that it exists we need some technical lemmas. The proofs are adapted from Knight (1981).

#### Lemma 3.2.2

$$\mathbb{P} \left[ \lim_{n \rightarrow \infty} X_n(t) \text{ exists for } 0 \leq t \leq 1 \text{ uniformly in } t \right] = 1.$$

**Proof:** Notice that  $\max_t |X_{n+1}(t) - X_n(t)|$  will be attained at a vertex, that is for

$t \in \{(2k-1)2^{-(n+1)} : k = 1, 2, \dots, 2^n\}$  and using (3.1)

$$\begin{aligned} & \mathbb{P} \left[ \max_t |X_{n+1}(t) - X_n(t)| \geq 2^{-n/4} \right] \\ &= \mathbb{P} \left[ \max_{1 \leq k \leq 2^n} \xi((2k-1)2^{-(n+1)}) \geq 2^{n/4+1} \right] \\ &\leq 2^n \mathbb{P}[\xi(1) \geq 2^{n/4+1}]. \end{aligned}$$

Now using the result of Exercise 7 (with  $t = 1$ ), for  $x > 0$

$$\mathbb{P}[\xi(1) \geq x] \leq \frac{1}{x\sqrt{2\pi}} e^{-x^2/2},$$

and combining this with the fact that

$$\exp(-2^{(n/2+1)}) < 2^{-2n+2},$$

we obtain that for  $n \geq 4$

$$2^n \mathbb{P}[\xi(1) \geq 2^{n/4+1}] \leq \frac{2^n}{2^{n/4+1}} \frac{1}{\sqrt{2\pi}} \exp(-2^{(n/2+1)}) \leq \frac{2^n}{2^{n/4+1}} 2^{-2n+2} <$$

Consider now for  $k > n \geq 4$

$$\mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \geq 2^{-n/4+3} \right] = 1 - \mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \leq 2^{-n/4+3} \right]$$

and

$$\begin{aligned} & \mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \leq 2^{-n/4+3} \right] \\ &\geq \mathbb{P} \left[ \sum_{j=n}^{k-1} \max_t |X_{j+1}(t) - X_j(t)| \leq 2^{-n/4+3} \right] \\ &\geq \mathbb{P} \left[ \max_t |X_{j+1}(t) - X_j(t)| \leq 2^{-j/4}, j = n, \dots, k-1 \right] \\ &\geq 1 - \sum_{j=n}^{k-1} 2^{-j} \geq 1 - 2^{-n+1}. \end{aligned}$$

Finally we have that

$$\mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \geq 2^{-n/4+3} \right] \leq 2^{-n+1},$$

for all  $k \geq n$ . The events on the left are increasing (since the maximum increase by the addition of a new vertex) so

$$\mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \geq 2^{-n/4+3} \text{ for some } k > n \right] \leq 2^{-n+1}.$$

In particular, for  $\epsilon > 0$ ,

$$\lim_{n \rightarrow \infty} \mathbb{P}[\text{For some } k > n \text{ and } t \leq 1, |X_k(t) - X_n(t)| \geq \epsilon] = 0,$$

which proves the lemma.



sing (3.1)

$$2^{-(n+1)} \geq 2^{n/4+1}$$

), for  $x > 0$

$$\frac{1}{\sqrt{2\pi}} e^{-x^2/2},$$

$$\leq 2^{-2n+2},$$

$$2^{-(n/2+1)} \leq \frac{2^n}{2^{n/4+1}} 2^{-2n+2} < 2^{-n}.$$

$$\mathbb{P} \left[ \max_t |X_k(t) - X_n(t)| \leq 2^{-n/4+3} \right]$$

opping  
mes

$$|t| \leq 2^{-n/4+3} \leq 2^{-j/4}, j = n, \dots, k-1$$

$$2^{-n/4+3} \leq 2^{-n+1},$$

reasing (since the maximum can only

$$\text{for some } k > n \leq 2^{-n+1}.$$

$$|X_k(t) - X_n(t)| \geq \epsilon = 0,$$

□

To complete the proof of existence of the Brownian motion, we must check the following.

**Lemma 3.2.3** *Let  $X(t) = \lim_{n \rightarrow \infty} X_n(t)$  if the limit exists uniformly and 0 otherwise. Then  $X(t)$  satisfies the conditions of Definition 3.1.3 (for  $t$  restricted to  $[0, 1]$ ).*

**Proof:** By construction, the properties 1–3 of Definition 3.1.3 hold for the approximation  $X_n(t)$  restricted to  $T_n = \{k2^{-n}: k = 0, 1, \dots, 2^n\}$ . Since we don't change  $X_k$  on  $T_n$  for  $k > n$ , the same must be true for  $X$  on  $\bigcup_{n=1}^{\infty} T_n$ . A uniform limit of continuous functions is continuous, so condition 4 holds and now by approximation of any  $0 \leq t_1 \leq t_2 \leq \dots \leq t_n \leq 1$  from within the dense set  $\bigcup_{n=1}^{\infty} T_n$  we see that in fact all four properties hold without restriction for  $t \in [0, 1]$ . □

### 3.3 The reflection principle and scaling

Having proved that Brownian motion actually exists, we now turn to some calculations. These will amount to no more than a small bag of tricks for us to call upon in later chapters. There are many texts devoted exclusively to Brownian motion where the reader can gain a more extensive repertoire.

By its very construction, Brownian motion has no memory. That is, if  $\{W_t\}_{t \geq 0}$  is a Brownian motion and  $s \geq 0$  is any fixed time, then  $\{W_{t+s} - W_s\}_{t \geq 0}$  is also a Brownian motion, independent of  $\{W_r\}_{0 \leq r \leq s}$ . What is also true is that for certain random times,  $T$ , the process  $\{W_{T+t} - W_T\}_{t \geq 0}$  is again a standard Brownian motion and is independent of  $\{W_s: 0 \leq s \leq T\}$ . We have already encountered such random times in the context of discrete parameter martingales.

**Definition 3.3.1** *A stopping time  $T$  for the process  $\{W_t\}_{t \geq 0}$  is a random time such that for each  $t$ , the event  $\{T \leq t\}$  depends only on the history of the process up to and including time  $t$ .*

In other words, by observing the Brownian motion up until time  $t$ , we can determine whether or not  $T \leq t$ .

We shall encounter stopping times only in the context of *hitting times*. For fixed  $a$ , the hitting time of level  $a$  is defined by

$$T_a = \inf\{t \geq 0 : W_t = a\}.$$

We take  $T_a = \infty$  if  $a$  is never reached. It is easy to see that  $T_a$  is a stopping time since, by continuity of the paths,

$$\{T_a \leq t\} = \{W_s = a \text{ for some } s, 0 \leq s \leq t\},$$

which depends only on  $\{W_s, 0 \leq s \leq t\}$ . Notice that, again by continuity, if  $T_a < \infty$ , then  $W_{T_a} = a$ .

Just as for random walks, an example of a random time that is *not* a stopping time is the *last* time that the process hits some level.

The  
reflection  
principle

Not surprisingly, there is often much to be gained from exploiting the symmetry inherent in Brownian motion. As a warm-up we calculate the distribution of  $T_a$ .

**Lemma 3.3.2** *Let  $\{W_t\}_{t \geq 0}$  be a  $\mathbb{P}$ -Brownian motion started from  $W_0 = 0$  and  $a > 0$ ; then*

$$\mathbb{P}[T_a < t] = 2\mathbb{P}[W_t > a].$$

**Proof:** If  $W_t > a$ , then by continuity of the Brownian path,  $T_a < t$ . Moreover,  $T_a$  is a stopping time,  $\{W_{t+T_a} - W_{T_a}\}_{t \geq 0}$  is a Brownian motion, so, by symmetry,  $\mathbb{P}[W_t - W_{T_a} > 0 | T_a < t] = 1/2$ . Thus

$$\begin{aligned} \mathbb{P}[W_t > a] &= \mathbb{P}[T_a < t, W_t - W_{T_a} > 0] \\ &= \mathbb{P}[T_a < t] \mathbb{P}[W_t - W_{T_a} > 0 | T_a < t] \\ &= \frac{1}{2} \mathbb{P}[T_a < t]. \end{aligned}$$

A more refined version of this idea is the following.

**Lemma 3.3.3 (The reflection principle)** *Let  $\{W_t\}_{t \geq 0}$  be a standard Brownian motion and let  $T$  be a stopping time. Define*

$$\tilde{W}_t = \begin{cases} W_t, & t \leq T, \\ 2W_T - W_t, & t > T; \end{cases}$$

*then  $\{\tilde{W}_t\}_{t \geq 0}$  is also a standard Brownian motion.*

Notice that if  $T = T_a$ , then the operation  $W_t \mapsto \tilde{W}_t$  amounts to reflecting the path after the first hitting time on  $a$  in the line  $x = a$  (see Figure 3.3). We prove the general form of the reflection principle here. Instead we put it into The following result will be the key to pricing certain *barrier options* in Chapter 4.

**Lemma 3.3.4 (Joint distribution of Brownian motion and its maximum)** *Let  $M_t = \max_{0 \leq s \leq t} W_s$ , the maximum level reached by Brownian motion in the time interval  $[0, t]$ . Then for  $a > 0$ ,  $a \geq x$  and all  $t \geq 0$ ,*

$$\mathbb{P}[M_t \geq a, W_t \leq x] = 1 - \Phi\left(\frac{2a - x}{\sqrt{t}}\right),$$

where

$$\Phi(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-u^2/2} du$$

*is the standard normal distribution function.*

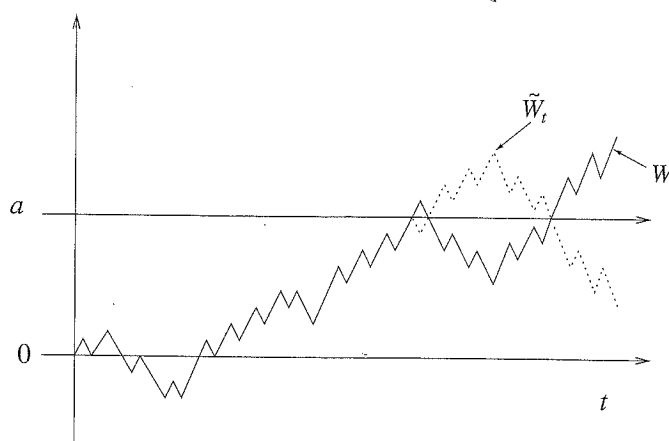


Figure 3.3 The reflection principle when  $T = T_a$ .

**Proof:** Notice that  $M_t \geq 0$  and is non-decreasing in  $t$  and if, for  $a > 0$ ,  $T_a$  is defined to be the first hitting time of level  $a$ , then  $\{M_t \geq a\} = \{T_a \leq t\}$ . Taking  $T = T_a$  in the reflection principle, for  $a \geq 0$ ,  $a \geq x$  and  $t \geq 0$ ,

$$\begin{aligned} \mathbb{P}[M_t \geq a, W_t \leq x] &= \mathbb{P}[T_a \leq t, W_t \leq x] \\ &= \mathbb{P}[T_a \leq t, 2a - x \leq \tilde{W}_t] \\ &= \mathbb{P}[2a - x \leq \tilde{W}_t] \\ &= 1 - \Phi\left(\frac{2a - x}{\sqrt{t}}\right). \end{aligned}$$

In the third equality we have used the fact that if  $\tilde{W}_t \geq 2a - x$  then necessarily  $\{\tilde{W}_s\}_{s \geq 0}$ , and consequently  $\{W_s\}_{s \geq 0}$ , has hit level  $a$  before time  $t$ .  $\square$

For pricing a perpetual American put option in Chapter 6 we shall use the following result.

**Proposition 3.3.5** Set  $T_{a,b} = \inf\{t \geq 0 : W_t = a + bt\}$ , where  $T_{a,b}$  is taken to be infinite if no such time exists. Then for  $\theta > 0$ ,  $a > 0$  and  $b \geq 0$

$$\mathbb{E}[\exp(-\theta T_{a,b})] = \exp\left(-a\left(b + \sqrt{b^2 + 2\theta}\right)\right).$$

**Proof:** We defer the proof of the special case  $b = 0$  until Proposition 3.4.9 when we shall have powerful martingale machinery to call upon. Here, assuming that result, we deduce the general result.

Fix  $\theta > 0$ , and for  $a > 0$ ,  $b \geq 0$ , set

$$\psi(a, b) = \mathbb{E}\left[e^{-\theta T_{a,b}}\right].$$

andom time that is *not* a stopping time

ained from exploiting the symmetry  
e calculate the distribution of  $T_a$ .

n motion started from  $W_0 = 0$  and let

$W_t > a]$ .

ownian path,  $T_a < t$ . Moreover, since  
Brownian motion, so, by symmetry,

$$-W_{T_a} > 0]$$

$$W_t - W_{T_a} > 0 | T_a < t]$$

$\square$

wing.

$\{W_t\}_{t \geq 0}$  be a standard Brownian mo-

$$t \leq T,$$

$$, \quad t > T;$$

tion.

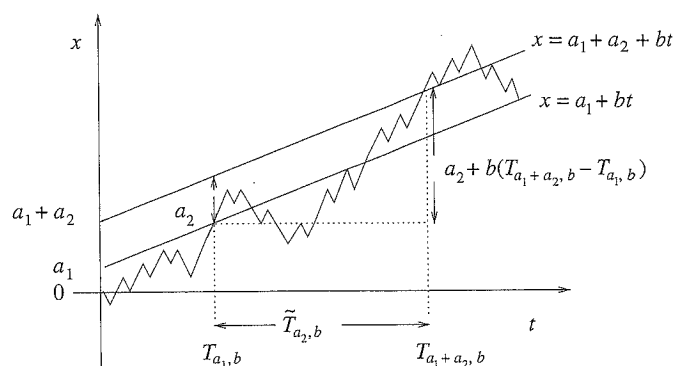
$\rightarrow \tilde{W}_t$  amounts to reflecting the portion  
e line  $x = a$  (see Figure 3.3). We don't  
iple here. Instead we put it into action.  
; certain barrier options in Chapter 6.

tion and its maximum) Let  $M_t =$   
Brownian motion in the time interval

$$- \Phi\left(\frac{2a - x}{\sqrt{t}}\right),$$

$$= e^{-u^2/2} du$$

$\pi$



**Figure 3.4** In the notation of Proposition 3.3.5,  $T_{a_1+a_2,b} = T_{a_1,b} + \tilde{T}_{a_2,b}$  where  $\tilde{T}_{a_2,b}$  has the same distribution as  $T_{a_2,b}$ .

Now take any two values for  $a$ ,  $a_1$  and  $a_2$  say, and notice (see Figure 3.4) that

$$T_{a_1+a_2,b} = T_{a_1,b} + (T_{a_1+a_2,b} - T_{a_1,b}) \stackrel{D}{=} T_{a_1,b} + \tilde{T}_{a_2,b},$$

where  $\tilde{T}_{a_2,b}$  is independent of  $T_{a_1,b}$  and has the same distribution as  $T_{a_2,b}$ . In words,

$$\psi(a_1 + a_2, b) = \psi(a_1, b)\psi(a_2, b),$$

and this implies that

$$\psi(a, b) = e^{-k(b)a},$$

for some function  $k(b)$ .

Since  $b \geq 0$ , the process must hit level  $a$  before it can hit the line  $a + b$  use this to break  $T_{a,b}$  into two parts; see Figure 3.5. Writing  $f_{T_a}$  for the probability density function of the random variable  $T_a$  and conditioning on  $T_a$ , we obtain

$$\begin{aligned} \psi(a, b) &= \int_0^\infty f_{T_a}(t) \mathbb{E} \left[ e^{-\theta T_{a,b}} \mid T_a = t \right] dt \\ &= \int_0^\infty f_{T_a}(t) e^{-\theta t} \mathbb{E} \left[ e^{-\theta T_{b,b}} \right] dt \\ &= \int_0^\infty f_{T_a}(t) e^{-\theta t} e^{-k(b)bt} dt \\ &= \mathbb{E} \left[ e^{-(\theta + k(b)b)T_a} \right] \\ &= \exp \left( -a\sqrt{2(\theta + k(b)b)} \right). \end{aligned}$$

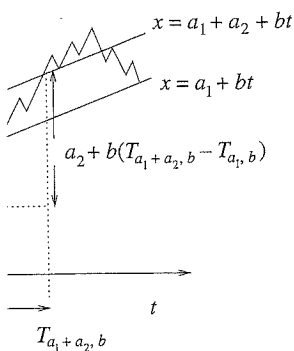
We now have two expressions for  $\psi(a, b)$ . Equating them gives

$$k^2(b) = 2\theta + 2k(b)b.$$

Since for  $\theta > 0$  we must have  $\psi(a, b) \leq 1$ , we choose

$$k(b) = b + \sqrt{b^2 + 2\theta},$$

which completes the proof.



$t_{1,b} + \tilde{T}_{a_2,b}$  where  $\tilde{T}_{a_2,b}$  has the same

and notice (see Figure 3.4) that

$$T_{a_1,b} \stackrel{\mathcal{D}}{=} T_{a_1,b} + \tilde{T}_{a_2,b},$$

he same distribution as  $T_{a_2,b}$ . In other

$$1, b)\psi(a_2, b),$$

$$-k(b)a,$$

before it can hit the line  $a + bt$ . We are 3.5. Writing  $f_{T_a}$  for the probability of conditioning on  $T_a$ , we obtain

$$\left[ e^{-\theta T_{a,b}} \mid T_a = t \right] dt$$

$$-\theta t \mathbb{E} \left[ e^{-\theta T_{bt,b}} \right] dt$$

$$-\theta t e^{-k(b)bt} dt$$

$$b)T_a]$$

$$\overline{(\theta + k(b)b)}.$$

quating them gives

$$2k(b)b.$$

ve choose

$$b^2 + 2\theta,$$

**Figure 3.5** In the notation of Proposition 3.3.5,  $T_{a,b} = T_a + \tilde{T}_{bT_a,b}$  where  $\tilde{T}_{bT_a,b}$  has the same distribution as  $T_{bT_a,b}$ .

**Definition 3.3.6** For a real constant  $\mu$ , we refer to the process  $W_t^\mu = W_t + \mu t$  as a Brownian motion with drift  $\mu$ .

In the notation above,  $T_{a,b}$  is the first hitting time of the level  $a$  by a Brownian motion with drift  $-b$ .

transformation We conclude this section with the following useful result.

nd scaling  
f Brownian  
motion

**Proposition 3.3.7**

If  $\{W_t\}_{t \geq 0}$  is a standard Brownian motion, then so are

- 1  $\{cW_{t/c^2}\}_{t \geq 0}$  for any real  $c$ ,
- 2  $\{tW_{1/t}\}_{t \geq 0}$  where  $tW_{1/t}$  is taken to be zero when  $t = 0$ ,
- 3  $\{W_s - W_{s-t}\}_{0 \leq t \leq s}$  for any fixed  $s \geq 0$ .

**Proof:** The proofs of 1–3 are similar. For example in the case of 2, it is clear that  $tW_{1/t}$  has continuous sample paths (at least for  $t > 0$ ) and that for any  $t_1, \dots, t_n$ , the random variables  $\{t_1 W_{1/t_1}, \dots, t_n W_{1/t_n}\}$  have a multivariate normal distribution. We must just check that the covariance takes the right form, but

$$\mathbb{E}[sW_{1/s}tW_{1/t}] = st\mathbb{E}[W_{1/s}W_{1/t}] = st\left(\frac{1}{s} \wedge \frac{1}{t}\right) = s \wedge t,$$

and the proof is complete.  $\square$

### 3.4 Martingales in continuous time

Just as in discrete time, the notion of a martingale plays a key rôle in our continuous time models.

Recall that in discrete time, a sequence  $X_0, X_1, \dots, X_n$  for which  $\mathbb{E}[X_r]$  for each  $r$  is a martingale with respect to the filtration  $\{\mathcal{F}_n\}_{n \geq 0}$  and a probability measure  $\mathbb{P}$  if

$$\mathbb{E}[X_r | \mathcal{F}_{r-1}] = X_{r-1} \quad \text{for all } r \geq 1.$$

We can make entirely analogous definitions in continuous time.

**Filtrations** **Definition 3.4.1** *Let  $\mathcal{F}$  be a  $\sigma$ -field. We call  $\{\mathcal{F}_t\}_{t \geq 0}$  a filtration if*

- 1  $\mathcal{F}_t$  is a sub- $\sigma$ -field of  $\mathcal{F}$  for all  $t$ , and
- 2  $\mathcal{F}_s \subseteq \mathcal{F}_t$  for  $s < t$ .

As in the discrete setting we are primarily concerned with the *natural* filtration  $\{\mathcal{F}_t^X\}_{t \geq 0}$ , associated with a stochastic process  $\{X_t\}_{t \geq 0}$ . As before,  $\mathcal{F}_t^X$  encodes information generated by the stochastic process  $X$  on the interval  $[0, t]$ . If  $A \in \mathcal{F}_t^X$  if, based upon observations of the trajectory  $\{X_s\}_{0 \leq s \leq t}$ , it is possible to decide whether or not  $A$  has occurred.

**Notation:** If the value of a stochastic variable  $Z$  can be completely determined given observations of the trajectory  $\{X_s\}_{0 \leq s \leq t}$  then we write

$$Z \in \mathcal{F}_t^X.$$

More than one process can be measurable with respect to the same filtration.

**Definition 3.4.2** *If  $\{Y_t\}_{t \geq 0}$  is a stochastic process such that we have  $Y_t \in \mathcal{F}_t^X$  for all  $t \geq 0$ , then we say that  $\{Y_t\}_{t \geq 0}$  is adapted to the filtration  $\{\mathcal{F}_t^X\}_{t \geq 0}$ .*

**Example 3.4.3**

- 1 *The stochastic process*

$$Z_t = \int_0^t X_s ds$$

*is adapted to  $\{\mathcal{F}_t^X\}_{t \geq 0}$ .*

- 2 *The process  $M_t = \max_{0 \leq s \leq t} W_s$  is adapted to the filtration  $\{\mathcal{F}_t^W\}_{t \geq 0}$ .*
- 3 *The stochastic process  $Z_t \triangleq W_{t+1}^2 - W_t^2$  is not adapted to the filtration generated by  $\{W_t\}_{t \geq 0}$ .*

Notice that just as in the discrete world we have divorced the rôles of the stochastic process and the probability measure. Thus a process may be a Brownian motion under the probability measure  $\mathbb{P}$ , but the same process may not be a Brownian motion under a different measure  $\mathbb{Q}$ .

**Martingales** **Definition 3.4.4** *Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space with filtration  $\{\mathcal{F}_t\}_{t \geq 0}$  and a family  $\{M_t\}_{t \geq 0}$  of random variables on this space with  $\mathbb{E}[|M_t|] < \infty$  for all  $t$*

$X_1, \dots, X_n$  for which  $\mathbb{E}[|X_r|] < \infty$   
filtration  $\{\mathcal{F}_n\}_{n \geq 0}$  and a probability

for all  $r \geq 1$ .  
continuous time.

$\{\mathcal{F}_t\}_{t \geq 0}$  a filtration if

concerned with the *natural* filtration,  
 $\{X_t\}_{t \geq 0}$ . As before,  $\mathcal{F}_t^X$  encodes the  
process  $X$  on the interval  $[0, t]$ . That is  
trajectory  $\{X_s\}_{0 \leq s \leq t}$ , it is possible to

variable  $Z$  can be completely deter-  
 $\{X_s\}_{0 \leq s \leq t}$  then we write

with respect to the same filtration.

process such that we have  $Y_t \in \mathcal{F}_t^X$  for  
the filtration  $\{\mathcal{F}_t^X\}_{t \geq 0}$ .

$\int_0^t \dots ds$

the filtration  $\{\mathcal{F}_t^W\}_{t \geq 0}$ .  
adapted to the filtration generated by

we divorced the rôles of the stochastic  
process may be a Brownian motion  
the process not be a Brownian motion

probability space with filtration  $\{\mathcal{F}_t\}_{t \geq 0}$ . A  
space with  $\mathbb{E}[|M_t|] < \infty$  for all  $t \geq 0$  is

a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale if it is adapted to  $\{\mathcal{F}_t\}_{t \geq 0}$  and for any  $s \leq t$ ,

$$\mathbb{E}^{\mathbb{P}}[M_t | \mathcal{F}_s] = M_s.$$

By restricting the conditions to  $t \in [0, T]$ , we define martingales parametrised by  $[0, T]$ .

Generally we shall be sloppy about specifying the filtration. In all of our examples there will be a Brownian motion around and it will be implicit that the filtration is that generated by the Brownian motion.

A more general notion is that of local martingale.

**Definition 3.4.5** A process  $\{X_t\}_{t \geq 0}$  is a local  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale if there is a sequence of  $\{\mathcal{F}_t\}_{t \geq 0}$ -stopping times  $\{T_n\}_{n \geq 1}$  such that  $\{X_{t \wedge T_n}\}_{t \geq 0}$  is a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale for each  $n$  and

$$\mathbb{P}\left[\lim_{n \rightarrow \infty} T_n = \infty\right] = 1.$$

All martingales are local martingales but the converse is false. It is because of this distinction that we impose boundedness conditions in many of our results of Chapter 4.

**Lemma 3.4.6** Let  $\{W_t\}_{t \geq 0}$  generate the filtration  $\{\mathcal{F}_t\}_{t \geq 0}$ . If  $\{W_t\}_{t \geq 0}$  is a standard Brownian motion under the probability measure  $\mathbb{P}$ , then

- 1  $W_t$  is a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale,
- 2  $W_t^2 - t$  is a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale,
- 3

$$\exp\left(\sigma W_t - \frac{\sigma^2}{2}t\right)$$

is a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale, called an exponential martingale.

**Proof:** The proofs are all rather similar. For example, consider  $M_t = W_t^2 - t$ . Evidently  $\mathbb{E}[|M_t|] < \infty$ . Now

$$\begin{aligned} \mathbb{E}\left[W_t^2 - W_s^2 \mid \mathcal{F}_s\right] &= \mathbb{E}\left[(W_t - W_s)^2 + 2W_s(W_t - W_s) \mid \mathcal{F}_s\right] \\ &= \mathbb{E}\left[(W_t - W_s)^2 \mid \mathcal{F}_s\right] + 2W_s \mathbb{E}\left[(W_t - W_s) \mid \mathcal{F}_s\right] \\ &= t - s. \end{aligned}$$

Thus

$$\begin{aligned} \mathbb{E}\left[W_t^2 - t \mid \mathcal{F}_s\right] &= \mathbb{E}\left[W_t^2 - W_s^2 + W_s^2 - (t - s) - s \mid \mathcal{F}_s\right] \\ &= (t - s) + W_s^2 - (t - s) - s = W_s^2 - s. \end{aligned}$$

□

Optional  
stopping

What we should really like is the continuous time analogue of the Optional Stopping Theorem. In general, we have to be a little careful (see Exercise 17 for why we go wrong). Problems arise if the sample paths of our martingale are not sufficiently 'nice'. In all our examples the stochastic process will have càdlàg sample paths.

**Definition 3.4.7** *The function  $f : \mathbb{R} \rightarrow \mathbb{R}$  is càdlàg if it is right continuous and has left limits.*

In particular, continuous functions are automatically càdlàg (continues à gauche).

**Theorem 3.4.8 (Optional Stopping Theorem)** *If  $\{M_t\}_{t \geq 0}$  is a càdlàg martingale with respect to the probability measure  $\mathbb{P}$  and the filtration  $\{\mathcal{F}_t\}_{t \geq 0}$  and if  $\tau_1$  and  $\tau_2$  are two stopping times such that  $\tau_1 \leq \tau_2 \leq K$  where  $K$  is a finite real number,*

$$\mathbb{E}[|M_{\tau_2}|] < \infty$$

and

$$\mathbb{E}[M_{\tau_2} | \mathcal{F}_{\tau_1}] = M_{\tau_1}, \quad \mathbb{P}\text{-a.s.}$$

**Remarks:**

- 1 The term 'a.s.' (almost surely) means with ( $\mathbb{P}$ -) probability one.
- 2 Notice in particular that if  $\tau$  is a bounded stopping time then  $\mathbb{E}[M_\tau] = \mathbb{E}[M_0]$

Brownian  
hitting time  
distribution

Just as in the discrete case the Optional Stopping Theorem will be a powerful tool. We illustrate by calculating the moment generating function for the hitting time  $T_a$  of level  $a$  by Brownian motion. (This result was essential to our proof of Proposition 3.3.5.)

**Proposition 3.4.9** *Let  $\{W_t\}_{t \geq 0}$  be a Brownian motion and let  $T_a = \inf\{s : W_s = a\}$  (or infinity if that set is empty). Then for  $\theta > 0$ ,*

$$\mathbb{E}[e^{-\theta T_a}] = e^{-\sqrt{2\theta}|a|}.$$

**Proof:** We assume that  $a \geq 0$ . (The case  $a < 0$  follows by symmetry.) We would like to apply the Optional Stopping Theorem to the martingale

$$M_t = \exp\left(\sigma W_t - \frac{1}{2}\sigma^2 t\right)$$

and the random time  $T_a$ , but we encounter a familiar obstacle. We cannot apply the Theorem directly to  $T_a$  as it may not be bounded. Instead we take  $\tau_1 = 0$  and  $\tau_2 = T_a \wedge n$ . This gives us that

$$\mathbb{E}[M_{T_a \wedge n}] = 1.$$



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If  $\{M_t\}_{t \geq 0}$  is a càdlàg martingale  
the filtration  $\{\mathcal{F}_t\}_{t \geq 0}$  and if  $\tau_1$  and  $\tau_2$   
where  $K$  is a finite real number, then

:  $\infty$

,  $\mathbb{P}$ -a.s.

) probability one.  
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o the martingale

$-\frac{1}{2}\sigma^2 t$

a familiar obstacle. We *cannot* apply  
ounded. Instead we take  $\tau_1 = 0$  and

$= 1$ .

So

$$1 = \mathbb{E}[M_{T_a \wedge n}] = \mathbb{E}[M_{T_a \wedge n} | T_a < n] \mathbb{P}[T_a < n] + \mathbb{E}[M_{T_a \wedge n} | T_a > n] \mathbb{P}[T_a > n]. \quad (3.2)$$

Now, by Lemma 3.3.2 and the result of Exercise 7,

$$\mathbb{P}[T_a < n] \rightarrow 1 \quad \text{as } n \rightarrow \infty.$$

Also, if  $T_a < \infty$ ,  $\lim_{n \rightarrow \infty} M_{T_a \wedge n} = M_{T_a}$ , whereas if  $T_a = \infty$ ,  $W_t \leq a$  for all  $t$  and so  $\lim_{n \rightarrow \infty} M_{T_a \wedge n} = 0$ . Letting  $n \rightarrow \infty$  in equation (3.2) then yields

$$\mathbb{E}[M_{T_a}] = 1.$$

Taking  $\sigma^2 = 2\theta$  completes the proof. □

ominated  
onvergence  
theorem

Arguments of this type are often simplified by an application of the Dominated Convergence Theorem.

**Theorem 3.4.10 (Dominated Convergence Theorem)** Let  $\{Z_n\}_{n \geq 1}$  be a sequence of random variables with  $\lim_{n \rightarrow \infty} Z_n = Z$ . If there is a random variable  $Y$  with  $|Z_n| < Y$  for all  $n$  and  $\mathbb{E}[Y] < \infty$ , then

$$\mathbb{E}[Z] = \lim_{n \rightarrow \infty} \mathbb{E}[Z_n].$$

In the proof of Proposition 3.4.9, since

$$0 \leq M_{T_a \wedge n} = \exp\left(\sigma W_{T_a \wedge n} - \frac{1}{2}\sigma^2 (T_a \wedge n)\right) \leq \exp(\sigma a),$$

we could take the constant  $e^{\sigma a}$  as the dominating random variable  $Y$ .

### Exercises

- 1 Suppose that  $\{S_n\}_{n \geq 0}$  is a symmetric simple random walk under  $\mathbb{P}$ . Show that

$$\mathbb{P}\left[\frac{S_{[nt]}}{\sqrt{n}} \leq x\right] \rightarrow \int_{-\infty}^x \frac{1}{\sqrt{2\pi t}} \exp\left(-\frac{y^2}{2t}\right) dy$$

as  $n \rightarrow \infty$  where  $[nt]$  is the integer part of  $nt$ .

- 2 Let  $Z$  be normally distributed with mean zero and variance one under the measure  $\mathbb{P}$ . What is the distribution of  $\sqrt{t}Z$ ? Is the process  $X_t = \sqrt{t}Z$  a Brownian motion?
- 3 Suppose that  $W_t$  and  $\tilde{W}_t$  are independent Brownian motions under the measure  $\mathbb{P}$  and let  $\rho \in [-1, 1]$  be a constant. Is the process  $X_t = \rho W_t + \sqrt{1 - \rho^2} \tilde{W}_t$  a Brownian motion?

- 4 Let  $\{W_t\}_{t \geq 0}$  be standard Brownian motion under the measure  $\mathbb{P}$ . Which following are  $\mathbb{P}$ -Brownian motions?
- (a)  $\{-W_t\}_{t \geq 0}$ ,
  - (b)  $\{cW_{t/c^2}\}_{t \geq 0}$ , where  $c$  is a constant,
  - (c)  $\{\sqrt{t}W_1\}_{t \geq 0}$ ,
  - (d)  $\{W_{2t} - W_t\}_{t \geq 0}$ .

Justify your answers.

- 5 Suppose that  $X$  is normally distributed with mean  $\mu$  and variance  $\sigma^2$ . Calculate

$$\mathbb{E}[e^{\theta X}]$$

and hence evaluate  $\mathbb{E}[X^4]$ .

- 6 Prove Lemma 3.4.6.3.

- 7 Prove that if  $\{W_t\}_{t \geq 0}$  is standard Brownian motion under  $\mathbb{P}$  then, for  $x > 0$ ,

$$\mathbb{P}[W_t \geq x] = \int_x^\infty \frac{1}{\sqrt{2\pi t}} e^{-y^2/2t} dy \leq \frac{\sqrt{t}}{x\sqrt{2\pi}} e^{-x^2/2t}.$$

[Hint: Integrate by parts.]

- 8 Let  $\{W_t\}_{t \geq 0}$  be standard Brownian motion under  $\mathbb{P}$ . Let  $Z = \sup_t W_t$ . Evidently any  $c > 0$ ,  $cZ$  has the same distribution as  $Z$ . Deduce that, with probability  $Z \in \{0, \infty\}$ . Let  $p = \mathbb{P}[Z = 0]$ . By conditioning on the event  $\{W_1 \leq 0\}$ , prove

$$\mathbb{P}[Z = 0] \leq \mathbb{P}[W_1 \leq 0] \mathbb{P}[Z = 0],$$

and hence  $p = 0$ . Deduce that

$$\mathbb{P}\left[\sup_t W_t = +\infty, \inf_t W_t = -\infty\right] = 1.$$

- 9 Deduce from the result of Exercise 8 and the result of Proposition 3.3.7.2 that

$$\mathbb{P}[\text{For each } \epsilon > 0, \exists s, t \leq \epsilon \text{ such that } W_s < 0 < W_t] = 1.$$

Deduce that if  $\{W_t\}_{t \geq 0}$  is differentiable at zero, then the derivative must be zero hence  $|W_t| \leq t$  for all sufficiently small  $t$ . By considering  $\tilde{W}_s \triangleq sW_{1/s}$ , arrive at a contradiction and deduce that Brownian motion is *not* differentiable at zero.

- 10 Brownian motion is not going to be adequate as a stock market model. It has constant mean, whereas the stock of a company usually grows at some rate if only due to inflation. Moreover, it may be too 'noisy' (that is the variance increments may be bigger than those observed for the stock) or not noisy enough. We can scale to change the 'noisiness' and we can artificially introduce a drift, but this still won't be a good model. Here is one reason why. Suppose that  $\{W_t\}_{t \geq 0}$  is standard Brownian motion under  $\mathbb{P}$ . Define a new process  $\{S_t\}_{t \geq 0}$  by  $S_t = \mu t + \sigma W_t$  where  $\sigma > 0$  and  $\mu \in \mathbb{R}$  are constants. Show that for all values of  $\sigma > 0$ ,  $\mu \in \mathbb{R}$  and  $T > 0$  there is a positive probability that  $S_T$  is negative.

under the measure  $\mathbb{P}$ . Which of the

- 11 Suppose that  $\{W_t\}_{t \geq 0}$  is standard Brownian motion. Prove that conditional on  $W_{t_1} = x_1$ , the probability density function of  $W_{t_1/2}$  is

$$\sqrt{\frac{2}{\pi t_1}} \exp\left(-\frac{1}{2} \left(\frac{(x - \frac{1}{2}x_1)^2}{t_1/4}\right)\right).$$

- 12 Let  $\{W_t\}_{t \geq 0}$  be standard Brownian motion under  $\mathbb{P}$ . Let  $T_a$  be the 'hitting time of level  $a$ ', that is

$$T_a = \inf\{t \geq 0 : W_t = a\}.$$

Then we proved in Proposition 3.4.9 that

$$\mathbb{E}[\exp(-\theta T_a)] = \exp(-a\sqrt{2\theta}).$$

Use this result to calculate

- (a)  $\mathbb{E}[T_a]$ ,  
(b)  $\mathbb{P}[T_a < \infty]$ .

- 13 Let  $\{W_t\}_{t \geq 0}$  denote standard Brownian motion under  $\mathbb{P}$  and define  $\{M_t\}_{t \geq 0}$  by

$$M_t = \max_{0 \leq s \leq t} W_s.$$

Suppose that  $x \geq a$ . Calculate

- (a)  $\mathbb{P}[M_t \geq a, W_t \geq x]$ ,  
(b)  $\mathbb{P}[M_t \geq a, W_t \leq x]$ .

- 14 Let  $\{W_t\}_{t \geq 0}$  be standard Brownian motion under  $\mathbb{P}$ . Let  $T_{a,b}$  denote the hitting time of the sloping line  $a + bt$ . That is,

$$T_{a,b} = \inf\{t \geq 0 : W_t = a + bt\}.$$

We proved in Proposition 3.3.5 that for  $\theta > 0$ ,  $a > 0$  and  $b \geq 0$

$$\mathbb{E}[\exp(-\theta T_{a,b})] = \exp\left(-a\left(b + \sqrt{b^2 + 2\theta}\right)\right).$$

The aim of this question is to calculate the distribution of  $T_{a,b}$ , without inverting the Laplace transform. In what follows,  $\phi(x) = \Phi'(x)$  and

$$\Phi(x) = \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{y^2}{2}\right) dy.$$

- (a) Find  $\mathbb{P}[T_{a,b} < \infty]$ .  
(b) Using the fact that  $sW_{1/s}$  has the same distribution as  $W_s$ , show that

$$\mathbb{P}[T_{a,b} \leq t] = \mathbb{P}[W_s \geq as + b \text{ for some } s \text{ with } 1/t \leq s < \infty].$$

mean  $\mu$  and variance  $\sigma^2$ . Calculate

tion under  $\mathbb{P}$  then, for  $x > 0$ ,

$$2t dy \leq \frac{\sqrt{t}}{x\sqrt{2\pi}} e^{-x^2/2t}.$$

ler  $\mathbb{P}$ . Let  $Z = \sup_t W_t$ . Evidently, for  $Z$ . Deduce that, with probability one, ing on the event  $\{W_1 \leq 0\}$ , prove that

$$0] \mathbb{P}[Z = 0],$$

$$t = -\infty] = 1.$$

result of Proposition 3.3.7.2 that

$$\text{that } W_s < 0 < W_t = 1.$$

, then the derivative must be zero and considering  $\tilde{W}_s \triangleq sW_{1/s}$ , arrive at a on is *not* differentiable at zero.

te as a stock market model. First, it ompany usually grows at some rate, oo 'noisy' (that is the variance of the d for the stock) or not noisy enough. e can artificially introduce a drift, but reason why. Suppose that  $\{W_t\}_{t \geq 0}$  is ew process  $\{S_t\}_{t \geq 0}$  by  $S_t = \mu t + \sigma W_t$  hat for all values of  $\sigma > 0$ ,  $\mu \in \mathbb{R}$  and negative.

(c) By conditioning on the value of  $W_{1/t}$ , use the previous part to show that

$$\mathbb{P}[T_{a,b} \leq t] = \int_{-\infty}^{b+a/t} \mathbb{P}[T_{b-x+a/t,a} < \infty] \phi(\sqrt{t}x) dx + 1 - \Phi\left(\frac{a+b}{\sqrt{t}}\right)$$

(d) Substitute for the probability in the integral and deduce that

$$\mathbb{P}[T_{a,b} \leq t] = e^{-2ab} \Phi\left(\frac{bt-a}{\sqrt{t}}\right) + 1 - \Phi\left(\frac{a+bt}{\sqrt{t}}\right).$$

15 Let  $\{W_t\}_{t \geq 0}$  be standard Brownian motion under the measure  $\mathbb{P}$  and let  $\mathcal{F}_t$  denote its natural filtration. Which of the following are  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale

- (a)  $\exp(\sigma W_t)$ ,
- (b)  $cW_t/c^2$ , where  $c$  is a constant,
- (c)  $tW_t - \int_0^t W_s ds$ .

16 Let  $\{\mathcal{F}_t\}_{0 \leq t \leq T}$  denote the natural filtration associated to a standard  $\mathbb{P}$ -Brownian motion,  $\{W_t\}_{0 \leq t \leq T}$ . The result of Lemma 3.4.6.3 can be rewritten as

$$\mathbb{E}\left[\exp\left(\sigma W_t - \frac{1}{2}\sigma^2 t\right); A\right] = \exp\left(\sigma W_s - \frac{1}{2}\sigma^2 s\right) \mathbf{1}_A, \quad \text{for all } A \in \mathcal{F}_t.$$

Use differentiation under the integral sign to provide another proof that  $\{W_t^2 - t\}$  is a  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingale and show that the following are also  $(\mathbb{P}, \{\mathcal{F}_t\}_{t \geq 0})$ -martingales:

- (a)  $W_t^3 - 3tW_t$ ,
- (b)  $W_t^4 - 6tW_t^2 + 3t^2$ .

17 Let  $(\Omega, \mathcal{F}, \mathbb{P})$  be a probability space. Suppose that the real random variable  $T : \Omega \rightarrow \mathbb{R}$  is uniformly distributed on  $[0, 1]$  under the measure  $\mathbb{P}$ . Define  $\{X_t\}_{t \geq 0}$  by

$$X_t(\omega) = \begin{cases} 1, & T(\omega) = t, \\ 0, & T(\omega) \neq t. \end{cases}$$

Check that  $\{X_t\}_{t \geq 0}$  is a  $\mathbb{P}$ -martingale with respect to its own filtration. Conditional expectation is only unique to within a random variable that is surely zero.]

Show that  $T$  is a stopping time for which the Optional Stopping Theorem fails.

18 As before, let  $T_a, T_b$  denote the first hitting times of levels  $a$  and  $b$  respectively of a  $\mathbb{P}$ -Brownian motion,  $\{W_t\}_{t \geq 0}$ , but now  $W_0$  is not necessarily zero (see the remark after Definition 3.1.3). Prove that if  $a < x < b$  then

$$\mathbb{P}[T_a < T_b | W_0 = x] = \frac{(b-x)}{(b-a)}.$$

[Hint: Mimic the proof of the corresponding result for random walk, cf. Proposition 2.4.4.]

19 Using the notation of Exercise 18, let  $T = T_a \wedge T_b$ . Prove that if  $a < 0 < b$  then

$$\mathbb{E}[T | W_0 = 0] = -ab.$$