

### Brief notes on homotopy of paths in the complex plane

Let  $\alpha(t), \beta(t), t \in [0, 1]$  be two continuous paths from  $z_0$  to  $z_1$  which lie in an connected open set  $\Omega$ . We say that they are homotopic if there exists a continuous function  $H(t, u) : [0, 1] \times [0, 1] \rightarrow \Omega$  such that  $H(t, 0) = \alpha(t), H(t, 1) = \beta(t), H(0, u) = z_0, H(1, u) = z_1$ . Intuitively, the homotopy deforms the path  $\alpha$  to the path  $\beta$ , leaving the endpoints  $z_0, z_1$  fixed.

We write  $\alpha \sim \beta$  to indicate homotopy, which is an equivalence relation among paths. We will have need of the constant path  $1_p$  at a point  $p$ , given by never moving from the start  $p$ , as well as the opposite path  $\alpha_-(t) = \alpha(1 - t)$ . Paths can be composed when the end of the first is the start of the second, to give a path  $\gamma\alpha$  parameterized by  $\alpha(2t)$  for  $t \in [0, 1/2]$  and  $\gamma(2t - 1)$  for  $t \in [1/2, 1]$ . Intuitively, we traverse  $\alpha$  to it's end and then follow  $\gamma$ .

Homotopy respects equivalence classes and composition in the sense that  $\alpha \sim \beta, \gamma \sim \eta$  implies  $\gamma\alpha \sim \eta\beta$ , as one sees immediately by composing the homotopy functions in the obvious way.

If  $\alpha$  starts at  $z_0$  and goes to  $z_1$  then  $\alpha_-\alpha \sim 1_{z_0}$  via the homotopy

$$H(t, u) = \begin{cases} \alpha(2t) & \text{if } 0 \leq 2t \leq (1 - u) \\ \alpha(1 - u) & \text{if } (1 - u) \leq 2t \leq u + 1 \\ \alpha(2 - 2t) & \text{if } u + 1 \leq 2t \leq 2 \end{cases}$$

while  $\alpha\alpha_- = 1_{z_1}$ . Intuitively we travel out the path  $\alpha$  to  $\alpha(1 - u)$ , rest there a bit, and then slide back to  $\alpha(0)$ .

We have  $\alpha\alpha_- \sim 1_{\alpha(1)}, \alpha_-\alpha \sim 1_{\alpha(0)}, \alpha 1_{\alpha(0)} \sim \alpha, 1_{\alpha(1)}\alpha \sim \alpha$ . This gives the set of homotopy classes of paths in  $\Omega$  a structure that allows composition of certain paths, right and left identity elements under composition of homotopy classes and left and right inverses to a path up to homotopy.

Let  $\alpha, \beta$  be two paths with initial point  $z_0$  and terminal point  $z_1$ . Then  $\alpha \sim \beta$  if and only if  $\alpha\beta_- \sim 1_{z_1}$ , so questions of homotopy of paths can be reduced to the study of closed paths.

We can relate the study of closed paths at points  $p$  to those at point  $q$  by letting  $\eta$  be a path from  $p$  to  $q$ . If  $\alpha$  is a closed path at  $p$ , then  $\eta\alpha\eta_-$  is a closed path at  $q$ . In particular if every closed path at  $q$  is homotopic to  $1_q$  then  $\eta\alpha\eta_- \sim 1_q$  so that  $\alpha \sim \eta_-1_q\eta \sim 1_p$  and hence every closed path at  $q$  is homotopic to a constant path at  $q$ .

Let  $\Omega$  be star shaped with center  $z_0$  and let  $\alpha$  be a closed path at  $z_0$ . The homotopy  $H(t, u) = uz_0 + (1 - u)\alpha(t)$  has image in  $\Omega$  since the set is star shaped, and gives  $\alpha \sim 1_{z_0}$ . By the discussion in the previous paragraphs we then have that any closed path at the point  $p \in \Omega$  is homotopic to  $1_p$ , so that any two paths in a star shaped set with the same initial and terminal points are homotopic.