

# LIMITS OF THE WONG-ZAKAI TYPE WITH A MODIFIED DRIFT TERM

HÉCTOR J. SUSSMANN\*

**Abstract.** We study Stratonovich stochastic differential equations driven by an  $m$ -dimensional Wiener process  $W$ , with  $m \geq 2$ . If  $W$  is approximated by processes  $W^\nu$  with more regular sample paths, then it is known that the solutions of the equations driven by the  $W^\nu$  will converge to the solution of the equation driven by  $W$ , provided that the approximations satisfy the conditions of the Wong-Zakai theorem. McShane gave an example showing that, if those conditions are not satisfied, then a different limiting equation can arise. Here we describe a large class of equations, obtained from the original one by suitably modifying the drift term, that can arise as limiting equations by some choice of the sequence  $\{W^\nu\}$ .

**1. Introduction.** Consider a stochastic differential equation

$$(1.1) \quad dx = f_0(x)dt + \sum_{i=1}^m f_i(x)dW_i ,$$

where  $x$  is  $n$ -dimensional,  $W = (W_1, \dots, W_m)$  is a standard  $m$ -dimensional Brownian motion, the vector fields  $f_i$  satisfy appropriate smoothness and growth conditions, and the solutions are always understood to be in the Stratonovich sense.[5]

If we approximate  $W$  by a sequence of processes  $W^\nu$  with more regular (e.g. Lipschitz) sample paths, then the well known Wong-Zakai Approximation Theorem (cf. [9], [10]) says that the solutions  $t \rightarrow X^\nu(t)$  of the corresponding approximating equation

$$(1.2) \quad dx = f_0(x)dt + \sum_{i=1}^m f_i(x)dW_i^\nu ,$$

with some given initial condition  $X^\nu(0) = \bar{X}$ , converge to the solution  $X$  of (1.1) with the same initial condition, *provided that the approximations  $W^\nu$  satisfy some extra conditions*, which always hold if  $m = 1$ , but may fail if  $m > 1$ . McShane gave an example in [4] showing that, for  $m = 2$ , the  $X^\nu$  may indeed fail to converge to  $X$ . In this note we investigate the possible limits that can be obtained by taking more general sequences of approximating processes and show that, by a suitable choice of the approximation, it is possible to make the  $X^\nu$  converge to the solution of an equation

$$(1.3) \quad dx = (f_0(x) + g(x))dt + \sum_{i=1}^m f_i(x)dW_i ,$$

---

\*Mathematics Department, Rutgers University, New Brunswick, New Jersey 08903. Work supported in part by the National Science Foundation under NSF Grant DMS-8902994.

with a different drift term. We will show that  $g$  can be chosen to be an arbitrary element of  $\Lambda$ , where  $\Lambda$  is the linear span of all the Lie brackets of the  $f_i$  for  $i = 1, \dots, m$  that contain at least two factors. The precise statement is given below in Theorem 6.1. Our result is a generalization of Theorem 7.2 of [3], Chapter 6, where it is shown that, by a suitable choice of the approximating sequence, one can produce a drift term which is an arbitrary linear combination of brackets  $[f_i, f_j]$ ,  $i, j > 0$ .

We remark that we only prove almost sure convergence for a fixed  $T$  and a fixed initial condition. With a more careful analysis, one can prove a.s. convergence uniformly in  $t$  for  $t$  in any bounded interval, and convergence of the stochastic flows.

**2. Differential Equations with Inputs.** We let  $C_b^\infty(\mathbb{R}^n, \mathbb{R}^n)$  denote the class of all maps  $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$  of class  $C^\infty$  such that all the partial derivatives  $\frac{\partial^{\alpha_1 + \dots + \alpha_n} f}{\partial x_1^{\alpha_1} \dots \partial x_n^{\alpha_n}}$  of all orders (including order 0) are bounded on  $\mathbb{R}^n$ . (In particular, every  $f \in C_b^\infty(\mathbb{R}^n, \mathbb{R}^n)$  is globally bounded and globally Lipschitz.)

We assume that  $f_0, \dots, f_m \in C_b^\infty(\mathbb{R}^n, \mathbb{R}^n)$ . We let  $\mathcal{U}^m$  denote the space of all locally absolutely continuous functions  $U : [0, \infty) \rightarrow \mathbb{R}^m$  such that  $U(0) = 0$ . If  $U \in \mathcal{U}^m$ , then we write  $u = \dot{U} = \frac{dU}{dt}$ , so  $u \in L_{\text{loc}}^1([0, \infty), \mathbb{R}^m)$ .

Let  $U \in \mathcal{U}^m$ , and write  $u = \dot{U}$ . Write  $U_0(t) \equiv t$ , i.e.  $u_0(t) \equiv 1$ . Then the ordinary differential equation

$$(2.1) \quad \dot{x} = f_0(x) + \sum_{i=1}^m u_i(t) f_i(x) ,$$

can also be written in the form

$$dx = f_0(x) dt + \sum_{i=1}^m f_i(x) dU_i$$

or

$$dx = \sum_{i=0}^m f_i(x) dU_i$$

It is clear that (2.1) satisfies the conditions of the Carathéodory existence and uniqueness theorem. Moreover, since the  $f_i$  are bounded, trajectories do not escape in finite time. So, given any  $a \in [0, \infty)$ ,  $\bar{x} \in \mathbb{R}^n$ , there exists a unique solution  $t \rightarrow x(t)$  of (2.1) such that  $x(a) = \bar{x}$ . For fixed  $b \in [0, \infty)$ , we will use  $\Phi_{b,a}^U$  to denote the map that assigns to each  $\bar{x}$  the value  $x(b)$  of the corresponding solution. That is,  $t \rightarrow \Phi_{t,a}^U(x)$  is the solution of (2.1) that goes through  $x$  when  $t = a$ . Each map  $\Phi_{b,a}^U$  is a  $C^\infty$  diffeomorphism from  $\mathbb{R}^n$  onto  $\mathbb{R}^n$ . Moreover, these diffeomorphisms satisfy  $\Phi_{a,a}^U = \text{identity}$ , and  $\Phi_{c,b}^U \Phi_{b,a}^U = \Phi_{c,a}^U$  for all  $a, b, c \in [0, \infty)$ .

We now define the *iterated integrals*  $\int_a^b u_I$ , where  $I = (i_1, \dots, i_r)$  is an arbitrary member of  $\mathcal{I}(m)$ , the space of all finite sequences of indices  $i \in \{0, \dots, m\}$ . (We will write  $|I|$  for the *length* of  $I$ , i.e. the number  $r$ . When  $|I| = 1$ , so  $I = (i)$  for some  $i$ , we will just write  $\int_a^b u_i$  instead of  $\int_a^b u_{(i)}$ . The empty sequence  $\emptyset$  is a member of  $\mathcal{I}(m)$ .) The definition is recursive: we let  $\int_a^b u_I = 1$  if  $I = \emptyset$ , and for a general  $I$  we write  $I = (i, I')$ , and define  $\int_a^b u_I$  to be equal to  $\int_a^b u_i(t)(\int_a^t u_{I'})dt$ .

We will also write  $U_I(b, a)$  for  $\int_a^b u_I$ . Notice that the identity  $U_I(b, a) = U_i(b) - U_i(a)$  holds when  $|I| = 1$ ,  $I = (i)$ , but no similar formula is true when  $|I| \neq 1$ , since in that case the additivity property  $U_I(c, a) = U_I(c, b) + U_I(b, a)$  does not hold in general.

We are interested in the derivatives of  $U_I(t, s)$  with respect to both variables  $t$  and  $s$ . Define

$$u_I^{+,s}(t) = \frac{\partial}{\partial t} U_I(t, s)$$

and

$$u_I^{-,t}(s) = -\frac{\partial}{\partial s} U_I(t, s).$$

Then  $\int_a^b u_I = \int_a^b u_I^{+,a}(t) dt = \int_a^b u_I^{-,b}(s) ds$ . The functions  $u_I^{+,a}(t)$ ,  $u_I^{-,b}(s)$  are equal, respectively, to

$$(2.2) \quad u_{i_1}(t) \int_a^t \int_a^{t_1} \dots \int_a^{t_{k-2}} u_{i_2}(t_1) \dots u_{i_k}(t_{k-1}) dt_{k-1} \dots dt_1$$

and

$$(2.3) \quad u_{i_k}(s) \int_s^b \int_{t_{k-1}}^b \dots \int_{t_2}^b u_{i_1}(t_1) \dots u_{i_{k-1}}(t_{k-1}) dt_{k-1} \dots dt_1.$$

if  $I = (i_1, \dots, i_k) \in \mathcal{I}(m)$ .

Now suppose that  $\varphi$  is a scalar- or vector-valued function of class  $C^\infty$ . Write  $f_i \varphi$  to denote the result of applying  $f_i$  to  $\varphi$  as a first-order differential operator, i.e.  $(f_i \varphi)(x) = \lim_{h \rightarrow 0} \frac{1}{h} (\varphi(x + h f_i(x)) - \varphi(x))$ . More generally, if  $I = (i_1, \dots, i_r) \in \mathcal{I}(m)$ , we write  $f_I = f_{i_1} f_{i_2} \dots f_{i_r}$ . Then (2.1) implies the equation

$$(2.4) \quad \varphi(\Phi_{t,a}^U(x)) = \varphi(x) + \sum_{i=0}^m \int_a^t u_i(s) (f_i \varphi)(\Phi_{s,a}^U(x)) ds,$$

which is the  $k = 0$  case of the general formula

$$(2.5) \quad \varphi(\Phi_{t,a}^U(x)) = \sum_{|I| \leq k} U_I(t, a) (f_I \# \varphi)(x) + R_{k,t,a,U,\varphi,f}(x)$$

where, for any multiindex  $I = (i_1, \dots, i_r)$ , we use  $I^\#$  to denote the reversed multiindex, i.e.  $I^\# = (i_r, \dots, i_1)$ , and the remainder  $R_{k,t,a,U,\varphi,f}(x)$  is given by

$$(2.6) \quad R_{k,t,a,U,\varphi,f}(x) = \sum_{|I|=k+1} \int_a^t u_I^{-,t}(s) (f_{I^\#} \varphi)(\Phi_{s,a}^U(x)) ds .$$

It is easy to see that (2.5) is actually true for all  $k$ . (The proof is by induction, using repeated integrations by parts.) A particularly important choice of  $\varphi$  is  $\varphi = E^n$ , where  $E^n : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the identity map. In that case, (2.5) becomes

$$(2.7) \quad \Phi_{t,a}^U(x) = \sum_{|I| \leq k} U_I(t,a) E_I^f(x) + R_{k,t,a,U,E^n,f}(x)$$

where  $E_I^f = f_{I^\#} E^n$ , and

$$(2.8) \quad R_{k,t,a,U,E^n,f}(x) = \sum_{|I|=k+1} \int_a^t u_I^{-,t}(s) E_I^f(\Phi_{s,a}^U(x)) ds .$$

We remark that all the vector-valued functions  $E_I^f$  belong to  $C_b^\infty(\mathbb{R}^n, \mathbb{R}^n)$ .

**3. Stochastic Ordinary Inputs.** Now assume that  $(\Omega, \mathcal{F}, P)$  is a probability space, and  $\{\mathcal{F}_t\}$  is an increasing family of sub- $\sigma$ -fields of  $\mathcal{F}$ . An  $m$ -dimensional *ordinary input process* (OIP) on  $(\Omega, \mathcal{F}, P)$  is a stochastic process  $U = \{U(t) : t \geq 0\}$  such that all the sample paths  $t \rightarrow U(t)(\omega)$ ,  $\omega \in \Omega$ , belong to  $\mathcal{U}^m$ . In that case, the derivative  $\dot{U}$ , the iterated integrals, the solutions of (2.1), and all the other  $U$ -dependent objects introduced above are well defined for each  $\omega \in \Omega$ .

As usual, we call a process  $U$  *adapted* if  $U(t)$  is  $\mathcal{F}_t$ -measurable for each  $t$ . However, it is also useful to define a weaker concept, namely, that of a  $\pi$ -adapted process, where  $\pi$  is a partition of  $[0, \infty)$ . Precisely, we define a *partition* of  $[0, \infty)$  to be an infinite sequence  $\pi = \{t_j\}_{j=0}^\infty$  such that  $0 = t_0 < t_1 < t_2 < \dots$  and  $\lim_{j \rightarrow \infty} t_j = \infty$ . The *mesh*  $|\pi|$  of a partition  $\pi$  is the number  $\sup\{t_j - t_{j-1} : j = 1, 2, \dots\}$ . If  $\pi$  is a partition, then we call  $U$   $\pi$ -adapted to  $\{\mathcal{F}_t\}$  if, for every  $j$ ,  $U(t)$  is  $\mathcal{F}_{t_j}$ -measurable whenever  $t \leq t_j$ .

Now suppose that  $\pi = \{t_j\}_{j=0}^\infty$  is a partition of  $[0, \infty)$  and  $U$  is a  $\pi$ -adapted  $m$ -dimensional OIP. Let  $k > 0$  be an integer, and let  $C \in \mathbb{R}$ ,  $C > 0$ . We will say that  $U$  belongs to the class  $OIP(m, k, C, \pi)$  if  $U$  satisfies the following three bounds

$$(3.1) \quad |\mathbb{E}(U_I(t_j, t_{j-1})) / \mathcal{F}_{t_{j-1}}| \leq C(t_j - t_{j-1}) ,$$

$$(3.2) \quad \mathbb{E}(U_I(t_j, t_{j-1})^2 / \mathcal{F}_{t_{j-1}}) \leq C(t_j - t_{j-1}) ,$$

and

$$(3.3) \quad |\mathbb{E}(U_I(t, t_{j-1})^2)/\mathcal{F}_{t_{j-1}}| \leq C ,$$

for all choices of  $I \in \mathcal{I}(m)$  such that  $|I| \leq k$ , all  $j \in \{1, 2, 3, \dots\}$ , and all  $t \in [t_{j-1}, t_j]$ , as well as the bound

$$(3.4) \quad |u_I^{-,t}(s)| \leq C$$

for all  $I \in \mathcal{I}(m)$  such that  $|I| = k+1$  and all  $s, t$  such that  $t_{j-1} \leq s \leq t \leq t_j$  for some  $j$ .

If  $U \in OIP(m, k, C, \pi)$  and  $1 \leq |I|, |J| \leq k$ , then it follows from the Schwartz inequality for conditional expectations that

$$(3.5) \quad |\mathbb{E}(U_I(t_j, t_{j-1})U_J(t_j, t_{j-1}))/\mathcal{F}_{t_{j-1}}| \leq C(t_j - t_{j-1}) .$$

We now define  $D_I(f) = \sup\{|x - y|^{-1} \|E_I^f(x) - E_I^f(y)\| : x, y \in \mathbb{R}^n, x \neq y\}$ , and let  $D = D(k, f) = \max\{D_I(f) : 1 \leq |I| \leq k+1\}$ .

**LEMMA 3.1.** *For every  $k, m, f, C$  there exist constants  $K, \mu$ , depending only on  $k, m, D$  and  $C$ , but not on the particular choice of  $U, X, Y, f$  or  $\pi$ , with the property that, whenever  $\pi = \{t_j\}_{j=0}^\infty$  is a partition of  $[0, \infty)$ , and  $U$  is a process in  $OIP(m, k, C, \pi)$ , then the bound*

$$\|\Phi_{t_j, t_{j-1}}^U(X) - \Phi_{t_j, t_{j-1}}^U(Y)\|_{L^2} \leq (1 + Ke^{\mu|\pi|}(t_j - t_{j-1}))\|X - Y\|_{L^2}$$

holds whenever  $X, Y : \Omega \rightarrow \mathbb{R}^n$  are  $\mathcal{F}_{t_{j-1}}$ -measurable and square-integrable.

**PROOF.** Throughout this proof, we will use the notation  $\mathcal{E}(X, Y)$  to denote  $\mathcal{E}(X) - \mathcal{E}(Y)$ , whenever  $\mathcal{E}$  is some expression that depends on  $X$ . Write  $a = t_{j-1}$ ,  $b = t_j$ , and use  $\mathbb{E}_a$  to denote conditional expectation with respect to  $\mathcal{F}_a$ . Let  $a \leq t \leq b$ . Using (2.7), we get

$$(3.6) \quad \begin{aligned} \Phi_{t,a}^U(X, Y) &= X - Y + \sum_{1 \leq |I| \leq k} U_I(t, a) E_I^f(X, Y) \\ &\quad + R_{k,t,a,U,E^n,f}(X, Y) . \end{aligned}$$

Using the bound  $\|E_I^f(x, y)\| \leq D\|x - y\|$ , we get

$$\begin{aligned} \mathbb{E}(U_I(t, a)^2 \|E_I^f(X, Y)\|^2) &= \mathbb{E}(\|E_I^f(X, Y)\|^2 \cdot \mathbb{E}_a(U_I(t, a)^2)) \\ &\leq C^2 D^2 \mathbb{E}(\|X - Y\|^2) , \end{aligned}$$

so that

$$(3.7) \quad \|U_I(t, a) \cdot E_I^f(X, Y)\|_{L^2} \leq CD\|X - Y\|_{L^2}$$

if  $1 \leq |I| \leq k$ . Similarly, if  $|I| = k+1$ , we have

$$(3.8) \quad \|u_I^{-,t}(s) \cdot E_I^f(\Phi_{s,a}^U(X, Y))\| \leq CD\|\Phi_{s,a}^U(X, Y)\|$$

pointwise, so

$$(3.9) \quad \|u_I^{-,t}(s) \cdot E_I^f(\Phi_{s,a}^U(X, Y))\|_{L^2} \leq CD \|\Phi_{s,a}^U(X, Y)\|_{L^2}.$$

Since  $R_{k,t,a,U,E^n,f}(X, Y) = \sum_{|I|=k+1} \int_a^t u_I^{-,t}(s) \cdot E_I^f(\Phi_{s,a}^U(X, Y)) ds$ , we find

$$(3.10) \quad \|R_{k,t,a,U,E^n,f}(X, Y)\|_{L^2} \leq \mu \int_a^t \|\Phi_{s,a}^U(X, Y)\|_{L^2} ds,$$

where  $\mu = (m+1)^{k+1}CD$ . Combining (3.6), (3.7) and (3.10), we get

$$(3.11) \quad \|\Phi_{t,a}^U(X, Y)\|_{L^2} \leq (1 + \nu CD) \|X - Y\|_{L^2} + \mu \int_a^t \|\Phi_{s,a}^U(X, Y)\|_{L^2} ds,$$

where  $\nu = m+1 + (m+1)^2 + \dots + (m+1)^k = \frac{(m+1)^{k+1} - m - 1}{m}$ .

Gronwall's inequality then yields

$$(3.12) \quad \|\Phi_{t,a}^U(X, Y)\|_{L^2} \leq (1 + \nu CD) e^{\mu|\pi|} \|X - Y\|_{L^2}.$$

If we now use (3.10) again, with  $t = b$ , together with (3.12), we get

$$(3.13) \quad \|R_{k,b,a,U,E^n,f}(X, Y)\|_{L^2} \leq \mu(1 + \nu CD) e^{\mu|\pi|} (b - a) \|X - Y\|_{L^2}.$$

Using (3.6) with  $t = b$ , we can write  $\Phi_{b,a}^U(X, Y) = A + B$ , where  $A = X - Y + \sum_{1 \leq |I| \leq k} U_I(b, a)(E_I^f(X, Y))$  and  $B = R_{k,b,a,U,E^n,f}(X, Y)$ . We have already estimated  $\|B\|_{L^2}$  in (3.13). To get a bound for  $\|A\|_{L^2}$  write

$$(3.14) \quad \begin{aligned} \|A\|^2 &= \|X - Y\|^2 + 2 \sum_{1 \leq |I| \leq k} U_I(b, a) \langle X - Y, E_I^f(X, Y) \rangle \\ &+ 2 \sum_{1 \leq |I|, |J| \leq k} U_I(b, a) U_J(b, a) \langle E_I^f(X, Y), E_J^f(X, Y) \rangle. \end{aligned}$$

Then

$$(3.15) \quad \begin{aligned} \mathbb{E}_a(\|A\|^2) &= \|X - Y\|^2 + 2 \sum_{1 \leq |I| \leq k} \mathbb{E}_a(U_I(b, a)) \langle X - Y, E_I^f(X, Y) \rangle \\ &+ 2 \sum_{1 \leq |I|, |J| \leq k} \mathbb{E}_a(U_I(b, a) U_J(b, a)) \langle E_I^f(X, Y), E_J^f(X, Y) \rangle, \end{aligned}$$

so that

$$(3.16) \quad \mathbb{E}_a(\|A\|^2) \leq (1 + (2\nu CD + \nu^2 CD^2)(b - a)) \|X - Y\|^2.$$

Taking expectations, we get

$$(3.17) \quad \mathbb{E}(\|A\|^2) \leq (1 + (2\nu CD + \nu^2 CD^2)(b - a)) \mathbb{E}(\|X - Y\|^2),$$

so that

$$(3.18) \quad \|A\|_{L^2} \leq (1 + (\nu CD + \frac{1}{2}\nu^2 CD^2)(b-a))\|X - Y\|_{L^2}.$$

Combining (3.18) with the bound for  $B$ , we get

$$(3.19) \quad \|\Phi_{b,a}^U(X) - \Phi_{b,a}^U(Y)\|_{L^2} \leq (1 + Ke^{\mu|\pi|}(b-a))\|X - Y\|_{L^2},$$

with  $K = \nu CD + \frac{1}{2}\nu^2 CD^2 + \mu(1 + \nu CD)$ . ■

**4. The Chen-Fliess Series.** It is clear from the preceding considerations that it is important to be able to analyze sums of the form

$$\sum_{1 \leq |I| \leq k} U_I(b, a)(f_{I\#}\varphi)(x).$$

To compute such expressions, we use the formalism of the *Chen-Fliess series* (cf. [2], [6], [7], [8]).

If  $\mathcal{X}$  is a nonempty set, we use  $\hat{\mathbf{A}}(\mathcal{X})$  to denote the algebra of *non-commutative formal power series* in  $\mathcal{X}$ , i.e. the set of all infinite linear combinations  $\sum_{M \in \mathcal{M}(\mathcal{X})} s_M M$ , where  $\mathcal{M}(\mathcal{X})$  is the set of all *monomials* in  $\mathcal{X}$ , that is, the set of all finite sequences of elements of  $\mathcal{X}$ . The length of a monomial is its *degree*. Monomials are multiplied by just concatenating them, and then the product of two elements of  $\hat{\mathbf{A}}(\mathcal{X})$  is well defined. The empty sequence is a monomial of degree 0, and is denoted by 1. Then  $1.S = S.1 = S$  for all  $S \in \hat{\mathbf{A}}(\mathcal{X})$ . A linear combination of monomials of degree  $k$  is said to be *homogeneous of degree  $k$* , and the set of all such combinations is denoted by  $\mathbf{A}^k(\mathcal{X})$ . Clearly, every  $S \in \hat{\mathbf{A}}(\mathcal{X})$  has a unique decomposition  $S = \sum_{k=0}^{\infty} H_k(S)$  as a sum of homogeneous components. If we regard  $\hat{\mathbf{A}}(\mathcal{X})$  as a Lie algebra, with the bracket defined by  $[S, T] = ST - TS$ , then the Lie subalgebra of  $\hat{\mathbf{A}}(\mathcal{X})$  generated by  $\mathcal{X}$  is denoted by  $\mathbf{L}(\mathcal{X})$  and its elements are known as *Lie polynomials* in  $\mathcal{X}$ . Those  $S \in \hat{\mathbf{A}}(\mathcal{X})$  all whose homogeneous components  $H_k(S)$  are in  $\mathbf{L}(\mathcal{X})$  are known as *Lie series* in  $\mathcal{X}$ , and the set of all such series is denoted by  $\hat{\mathbf{L}}(\mathcal{X})$ . The *order*  $\omega(S)$  of a series  $S \in \hat{\mathbf{A}}(\mathcal{X})$  is the smallest  $k$  such that the  $k$ -th homogeneous component of  $S$  is  $\neq 0$ . (If  $S = 0$  then  $\omega(S)$  is defined to be  $+\infty$ .) An infinite sum  $S_1 + S_2 + S_3 + \dots$  of series in  $\hat{\mathbf{A}}(\mathcal{X})$  such that  $\omega(S_j) \rightarrow \infty$  as  $j \rightarrow \infty$  is convergent in an obvious way since, for each  $k$ ,  $H_k(S_j) = 0$  for all but finitely many  $j$ 's. In particular, the exponential  $e^S$ , and the logarithm  $\log(1 + S)$  are well defined by the usual power series if  $\omega(S) \geq 1$ . If  $S$  is a Lie series then  $\omega(S) \geq 1$ , so  $e^S$  and  $\log(1 + S)$  are defined. The elements of the form  $e^S$ , with  $S \in \hat{\mathbf{L}}(\mathcal{X})$ , are known as *exponential Lie series* in  $\mathcal{X}$ .

Given an input  $U \in \mathcal{U}^m$ , we can consider the differential equation

$$(4.1) \quad \dot{S}(t) = S(t)(X_0 + u_1(t)X_1 + \dots + u_m(t)X_m),$$

where  $u_i = \dot{U}_i$  and  $X_0, \dots, X_m$  are formal noncommutative indeterminates. We can regard  $S$  as evolving in the algebra  $\hat{\mathbf{A}}(X_0, \dots, X_m)$  of noncommutative formal power series in the  $m+1$  indeterminates  $X_0, \dots, X_m$ . (That is,  $\hat{\mathbf{A}}(X_0, \dots, X_m)$  is the set of all formal infinite sums  $S = \sum_{I \in \mathcal{I}(m)} s_I X_I$ , where, if  $I = (i_1, \dots, i_r)$ ,  $r > 0$ , we define  $X_I = X_{i_1} X_{i_2} \dots X_{i_r}$ , and we let  $X_\emptyset = 1$ .) If we solve (4.1) with initial condition  $S(a) = 1$ , then the solution is given by

$$(4.2) \quad S(t) = \sum_{I \in \mathcal{I}(m)} U_I(t, a) X_{I^\#} .$$

We can also consider (4.1) as evolving in  $\mathbf{A}_k(X_0, \dots, X_m)$ , the free nilpotent associative algebra of order  $k$  in  $X_0, \dots, X_m$ , i.e. the set of all sums  $S = \sum_{I \in \mathcal{I}(m), |I| \leq k} s_I X_I$ , where monomials are multiplied in the usual way, and every monomial of degree  $> k$  is set equal to zero. In this case, the solution is given by

$$(4.3) \quad S(t) = \sum_{I \in \mathcal{I}(m), |I| \leq k} U_I(t, a) X_{I^\#} .$$

The value at  $b$  of this solution will be denoted by  $S_{k,a,b}(U)$ , or  $S_{k,a,b}(u)$ , and referred to as the *Chen-Fliess series of  $U$  from  $a$  to  $b$ , truncated at order  $k$* . Formula (4.3) shows that  $S_{k,a,b}(U)$  is just a way of coding all the iterated integrals  $U_I(b, a)$ ,  $|I| \leq k$ , into one algebraic expression.

It is clear that, if a function  $t \rightarrow S(t)$  is a solution of (4.2), and  $Q \in \mathbf{A}_k(X_0, \dots, X_m)$ , then  $t \rightarrow QS(t)$  is also a solution. In particular, if  $a < b < c$ , then  $t \rightarrow S_{k,a,t}(U)$  and  $t \rightarrow S_{k,a,b}(U)S_{k,b,t}(U)$  are both solutions, whose values at  $t = b$  coincide. Hence the identity

$$(4.4) \quad S_{k,a,c}(U) = S_{k,a,b}(U)S_{k,b,c}(U)$$

holds in  $\mathbf{A}_k(X_0, \dots, X_m)$ . Notice that, when  $k = 1$ , Formula (4.4) just amounts to the statement that  $U_I(c, a) = U_I(c, b) + U_I(b, a)$  whenever  $|I| = 1$ , i.e. to the property that the integral is additive with respect to the interval. So (4.4) can be viewed as a generalization to high-order iterated integrals of the additivity property.

We will need the *Campbell-Hausdorff formula* (CHF), cf. [1]. To state the CHF, let  $A, B$  be indeterminates. The CHF then says that

$$(4.5) \quad e^A e^B = e^{A+B+\frac{1}{2}[A,B]+C(A,B)} ,$$

where  $C \in \hat{\mathbf{L}}(A, B)$  is a Lie series in  $A, B$  of order 3. Naturally, if  $S, T \in \hat{\mathbf{L}}(X_0, \dots, X_m)$ , we can plug them into (4.5) and get  $e^S e^T = e^{S+T+\frac{1}{2}[S,T]+C(S,T)}$ , so in particular the set of Lie series is closed under multiplication. A similar formula holds in  $\mathbf{L}_k(X_0, \dots, X_m)$  (where  $\mathbf{L}_k(X_0, \dots, X_m)$  is the truncated version of  $\hat{\mathbf{L}}(X_0, \dots, X_m)$ , i.e. the Lie subalgebra of  $\mathbf{A}_k(X_0, \dots, X_m)$  generated by the  $X_i$ ), and in this case the series  $C(S, T)$  is actually a finite sum.



**5. Construction of Approximating Processes.** We now fix  $m$  and define, for each  $k$ , each formal bracket  $B = [X_{i_1}, [\dots, [X_{i_{r-1}}, X_{i_r}] \dots]]$ ,  $i_j \in \{1, \dots, m\}$  for  $j = 1, \dots, r$ , each interval  $[a, b] \subset [0, \infty)$ , and each real number  $\tau > 0$ , two controls  $u(B, a, b, \pm, \tau) : [a, b] \rightarrow \mathbb{R}^m$ , such that

$$(5.1) \quad S_{k,a,b}(u(B, a, b, \pm, \tau)) = e^{(b-a)X_0 \pm \tau^r B + Z(B, a, b, \pm, \tau)},$$

where  $Z(B, a, b, \pm, \tau) = P_B^\pm((b-a)X_0, \tau X_1, \dots, \tau X_m)$ , and  $P_B^\pm$  are Lie polynomials of order  $\geq 2$  in indeterminates  $Y_0, \dots, Y_m$ , that do not contain monomials in  $Y_1, \dots, Y_m$  of degree  $\leq r$  (i.e.  $P_B^\pm$  are such that  $\omega(P_B^\pm) \geq 2$  and  $\omega(P_B^\pm(0, Y_1, \dots, Y_m)) > r$ ).

The  $u(B, a, b, \pm, \tau) : [a, b] \rightarrow \mathbb{R}^m$  are constructed inductively as follows. Assume first that  $r = 1$ , so  $B = X_i$  for some  $i \in \{1, \dots, m\}$ . Then (writing  $u(i, a, b, \pm, \tau)$  instead of  $u(X_i, a, b, \pm, \tau)$ ) we define  $u(i, a, b, \pm, \tau)$  to be the control whose  $i$ -th component is constant and equal to  $\pm \frac{\tau}{b-a}$ , while all the other components are zero. Now assume that  $u(B', a, b, \pm, \tau)$  has been defined whenever  $B'$  has degree  $r-1$ . Pick  $B$  of degree  $r$ , and write  $B = [X_i, B']$ . Divide the interval  $I = [a, b]$  into four equal subintervals  $I_j = [t_{j-1}, t_j]$ ,  $j = 1, \dots, 4$ , where we let  $t_j = a + j\delta$ , for  $j = 0, \dots, 4$ , with  $\delta = \frac{1}{4}(b-a)$ . Then define  $u(B, a, b, +, \tau)$  to be equal to  $u(i, t_0, t_1, +, \tau)$  on  $I_1$ , to  $u(B', t_1, t_2, +, \tau)$  on  $I_2$ , to  $u(i, t_2, t_3, -, \tau)$  on  $I_3$ , and to  $u(B', t_3, t_4, -, \tau)$  on  $I_4$ . Having defined  $u(B, a, b, +, \tau)$ , we construct  $u(B, a, b, -, \tau)$  by “changing sign and reversing time,” that is, by letting  $u(B, a, b, -, \tau)(t) = -u(B, a, b, +, \tau)(a+b-t)$  for  $a \leq t \leq b$ .

With this definition of the  $u(B, a, b, \pm, \tau)$ , we now show by induction on  $r$  that the Chen-Fliess series of  $u(B, a, b, \pm, \tau)$  satisfies the desired properties. Consider first the case  $r = 1$ . In this case, it is obvious that

$$(5.2) \quad S_{k,a,b}(u(i, a, b, \pm, \tau)) = e^{(b-a)X_0 \pm \tau X_i}.$$

Now assume that the desired property holds for  $r-1$ . Let  $B$  be of degree  $r$ , and write  $B = [X_i, B']$ . In view of (4.4), we have

$$(5.3) \quad S_{k,a,b}(u(B, a, b, +, \tau)) = S_1 S_2 S_3 S_4,$$

where  $S_j = S_{k,t_{j-1},t_j}(u(B_j, t_{j-1}, t_j, \theta_j, \tau))$ ,  $B_1 = B_3 = X_i$ ,  $B_2 = B_4 = B'$ ,  $\theta_1 = \theta_2 = +$ ,  $\theta_3 = \theta_4 = -$ . Then  $S_1 = e^{\delta X_0 + \tau X_i}$  and  $S_3 = e^{\delta X_0 - \tau X_i}$ , where  $\delta = \frac{b-a}{4}$ . By the inductive hypothesis, we have

$$S_2 = e^{\delta X_0 + \tau^{r-1} B' + R^+} \quad \text{and} \quad S_4 = e^{\delta X_0 - \tau^{r-1} B' + R^-},$$

where  $R^\pm = P_{B'}^\pm(\delta X_0, \tau X_1, \dots, \tau X_m)$ , and the  $P_{B'}^\pm$  are Lie polynomials in  $Y_0, \dots, Y_m$  such that  $\omega(P_{B'}^\pm) \geq 2$  and  $\omega(P_{B'}^\pm(0, Y_1, \dots, Y_m)) \geq r$ .

We now repeatedly apply the CHF. (In our case, all the Lie series occurring in the computation are actually Lie polynomials, because we are working in a nilpotent algebra.) We get  $S_1 S_2 = e^{Z^+}$ ,  $S_3 S_4 = e^{Z^-}$ , where

$$(5.4) \quad Z^\pm = 2\delta X_0 \pm \tau X_i \pm \tau^{r-1} B' + \frac{1}{2} \tau^r [X_i, B] + Q^\pm,$$

$$(5.5) \quad S_{k,a,b}(u(B, a, b, +, \tau)) = S_1 S_2 S_3 S_4 = e^{(b-a)X_0 + \tau^r[X_i, B] + Q} ,$$

$$Q^\pm = R^\pm \pm \frac{1}{2} \delta \tau^{r-1} [X_0, B'] \pm \frac{1}{2} \delta \tau [X_i, X'_0] + \frac{1}{2} \delta [X_0, R^\pm]$$

$$(5.6) \quad \pm \frac{1}{2} \tau^r [X_i, R^\pm] + C(\delta X_0 \pm \tau X_i, \delta X_0 \pm \tau^{r-1} B' + R^\pm) ,$$

$$(5.7) \quad Q = Q^+ + Q^- + \frac{1}{2} [Z^+, Z^-] + C(Z^+, Z^-) .$$

It is clear that  $Q$  is a Lie polynomial in  $\delta X_0, \tau X_1, \dots, \tau X_m$ , i.e.  $Q = P_B^+(\delta X_0, \tau X_1, \dots, \tau X_m)$  for some Lie polynomial in  $Y_0, \dots, Y_m$ . Moreover,  $P_B^+$  clearly has order  $\geq 2$ . We must now show that  $\omega(P_B^+(0, Y_1, \dots, Y_m)) > r$ . That is, we must show that, if we plug in  $\delta = 0$  in  $Q$ , then the resulting expression is divisible by  $\tau^{r+1}$ . It is easy to see that, in the right-hand side of (5.7), the only possible terms of degree  $\leq r$  in  $\tau$  must come from the sum  $Q^+ + Q^-$ . Using (5.6), we conclude immediately that such terms can only arise from the sum  $P_{B'}^+(0, \tau X_1, \dots, \tau X_m) + P_{B'}^-(0, \tau X_1, \dots, \tau X_m)$ . So our conclusion will follow if we show that this sum vanishes, i.e. that  $P_{B'}^+(0, Y_1, \dots, Y_m) + P_{B'}^-(0, Y_1, \dots, Y_m) = 0$ . This in turn follows from the equality  $\tilde{S}_2 \tilde{S}_4 = 1$ , where the  $\tilde{S}_j$  are the series obtained from the  $S_j$  by setting  $X_0 = 0$ . These series can be computed by setting  $X_0 = 0$  in (4.1) and then solving on the intervals  $[t_{j-1}, t_j]$  with input  $u(B, a, b, \pm, \tau)$ . If we let  $\hat{S}_j$  denote the corresponding solutions with initial condition  $\hat{S}_j(t_{j-1}) = 1$ , then  $\tilde{S}_j = \hat{S}_j(t_j)$ . By translation invariance, we have  $\tilde{S}_2 = S_+(\delta)$ ,  $\tilde{S}_4 = S_-(\delta)$ , where  $S_\pm$  is the solution of (4.1) on  $[0, \delta]$ , with input  $u(B', 0, \delta, \pm, \tau)$  and initial condition  $S_\pm(0) = 1$ . Since, as explained above,  $u(B', a, b, -, \tau)$  is obtained from  $u(B', a, b, +, \tau)$  by changing sign and reversing time, it follows easily that  $S_-(\delta) = S_+(\delta)^{-1}$ , completing the proof of our conclusion.

We record for future use the trivial fact that

$$(5.8) \quad |u(B, a, b, \pm, \tau)_i| \leq \frac{4^{r-1} \tau}{b-a} .$$

We now let  $g \in \Lambda$ , so we can write  $g = \sum_{\mu=1}^p g_\mu B_\mu(f)$ , where the  $B_\mu$  are Lie brackets of the form

$$[X_{i_1}^\mu, [\dots, [X_{i_{r(\mu)-1}}^\mu, X_{i_{r(\mu)}}^\mu] \dots]], \quad i_k^\mu \in \{1, \dots, m\} ,$$

$r(\mu) \geq 2$ , and  $B_\mu(f)$  is the vector field obtained by plugging in  $f_i$  for  $X_i$  for each  $i$ . We assume, without loss of generality, that all the numbers  $g_\mu$  are nonzero.

We now let  $(\Omega, \mathcal{F}, P)$  be a probability space and  $\{\mathcal{F}_t\}$  be a filtration as above. Let  $W = (W_1, \dots, W_m)$  be an  $m$ -dimensional standard Wiener

process on  $(\Omega, \mathcal{F}, P)$  that has continuous sample paths and is adapted to  $\{\mathcal{F}_t\}$ , in the sense that  $W_t$  is  $\mathcal{F}_t$ -measurable and  $W_t - W_s$  is independent from  $\mathcal{F}_s$  whenever  $s < t$ . For each integer  $\nu = 1, 2, \dots$  we let  $\pi_\nu$  be the partition  $\{t_j^\nu\}_{j=0}^\infty$ , where  $t_j^\nu = j2^{-\nu}$ . We write  $\Delta W_i(j, \nu) = W_i(j2^{-\nu}) - W_i((j-1)2^{-\nu})$ .

Using the  $u(B, a, b, \pm, \tau)$  defined above, we will construct for each  $\nu$  a  $\pi_\nu$ -adapted input process  $U^\nu$ . We define  $U^\nu$  by specifying its derivative  $u^\nu = \dot{U}^\nu$ . Divide the interval  $I_j^\nu = [(j-1)2^{-\nu}, j2^{-\nu}]$  into two equal subintervals  $I_j^{\nu,-}, I_j^{\nu,+}$ . On  $I_j^{\nu,-}$ , we let the component  $u_i^\nu$  be equal to  $2^{\nu+1}\Delta W_i(j, \nu)$  if  $|\Delta W_i(j, \nu)| \leq 2^{-\frac{2\nu}{5}}$ , and to zero otherwise. (It then follows, in particular, that  $|u_i^\nu(t)| \leq 2^{1+\frac{3\nu}{5}}$ .) On  $I_j^{\nu,+}$  we proceed as follows. Let

$$\alpha_\mu = \frac{|g_\mu|}{|g_1| + \dots + |g_p|},$$

so that  $0 < \alpha_\mu$  and  $\alpha_1 + \dots + \alpha_p = 1$ . Divide  $I_j^{\nu,+}$  into intervals  $I_j^{\nu,+, \mu}$ ,  $\mu = 1, \dots, p$ , of length  $\alpha_\mu 2^{-\nu-1}$ . If  $I_j^{\nu,+, \mu} = [a(j, \nu, \mu), b(j, \nu, \mu)]$ , then we let  $u^\nu$  be equal to  $u(B_\mu, a(j, \nu, \mu), b(j, \nu, \mu), \pm, \tau_{\mu, \nu})$ , where the sign is  $+$  or  $-$  depending on whether  $g_\mu$  is  $> 0$  or  $< 0$ , and the number  $\tau_{\mu, \nu}$  is chosen so that  $\tau_{\mu, \nu}^{r(\mu)} = |g_\mu| 2^{-\nu}$ .

Then, if we apply (5.8) to the controls  $u_i^\nu$  on an interval  $I_j^{\nu,+, \mu}$ , we get  $|u_i^\nu(t)| \leq \alpha_\mu^{-1} 2^{\nu+1} 4^{r(\mu)-1} |g_\mu|^{\frac{1}{r(\mu)}} 2^{-\frac{\nu}{r(\mu)}}$ . We now pick  $k \geq 3$  such that  $r(\mu) \leq k$  for all  $\mu$ . We then have the pointwise inequality

$$(5.9) \quad |u_i^\nu(t)| \leq \kappa 2^{\rho\nu},$$

where  $\kappa = 2 \max(1, \max\{\alpha_\mu^{-1} 4^{r(\mu)-1} |g_\mu|^{\frac{1}{r(\mu)}} : \mu = 1, \dots, p\})$  and  $\rho = \frac{k-1}{k}$ . (This has just been shown to be true on  $I_j^{\nu,+}$ , but it clearly holds on  $I_j^{\nu,-}$  as well, since (a)  $\kappa \geq 2$  and (b)  $\rho \geq \frac{3}{5}$ , because  $k \geq 3$ .)

We let  $I_j^{\nu,-} = [a(j, \nu, 0), b(j, \nu, 0)]$ . Then it is easy to see that

$$(5.10) \quad S_{k, a(j, \nu, \mu), b(j, \nu, \mu)}(U^\nu) = e^{2^{-\nu-1} X_0 + \sum_{i=1}^m \tilde{\Delta} W_i(j, \nu) X_i}$$

if  $\mu = 0$ , where  $\tilde{\Delta} W_i(j, \nu) = \chi_{\nu, j, i} \Delta W_i(j, \nu)$ , and  $\chi_{\nu, j, i}$  is the indicator function of the set  $\tilde{B}_{\nu, j, i} = \{\omega \in \Omega : |\Delta W_i(j, \nu)| \leq 2^{-\frac{2\nu}{5}}\}$ . If  $\mu > 0$ , we have

$$(5.11) \quad S_{k, a(j, \nu, \mu), b(j, \nu, \mu)}(U^\nu) = e^{\alpha_\mu 2^{-\nu-1} X_0 + g_\mu 2^{-\nu} B_\mu + \dots},$$

where “ $\dots$ ” denotes a Lie polynomial whose coefficients are bounded by a fixed constant times  $2^{-\theta\nu}$ , where  $\theta = \frac{k+1}{k}$ . From this, using the Campbell-Hausdorff formula, we conclude that

$$(5.12) \quad S_{k, (j-1)2^{-\nu}, j2^{-\nu}}(U^\nu) = e^{2^{-\nu} X_0 + \sum_{i=1}^m \tilde{\Delta} W_i(j, \nu) X_i + 2^{-\nu} G + \dots},$$

where  $G = \sum_{i=1}^p g_\mu B_\mu$ .

Notice that, since  $2^{\frac{\nu}{2}} \Delta W_i(j, \nu)$  is normalized Gaussian, we have

$$(5.13) \quad P(\tilde{B}_{\nu,j,i}) \geq 1 - \sqrt{\frac{2}{\pi}} 2^{-\frac{\nu}{10}} e^{-2^{\frac{\nu}{5}-1}}$$

so that, for any fixed  $T > 0$ , if we let  $\mathcal{B}_{T,N}$  be the event that  $\chi_{\nu,j,i} = 1$  for all  $i, j, \nu$  such that  $i \in \{1, \dots, m\}$ ,  $j 2^{-\nu} \leq T$ , and  $\nu \geq N$ , then we have  $P(\mathcal{B}_{T,N}) \geq 1 - T \sqrt{\frac{2}{\pi}} \sum_{\nu=N}^{\infty} 2^{\frac{9\nu}{10}} e^{-2^{\frac{\nu}{5}-1}}$ , so that  $P(\mathcal{B}_{T,N}) \rightarrow 1$  as  $N \rightarrow \infty$ .

We will need the following technical result:

LEMMA 5.1. *The process  $U^\nu$  is in OIP( $m, k, C, \pi_\nu$ ), where  $C$  is a fixed constant, independent of  $\nu$ .*

PROOF. The iterated integrals  $U_I^\nu(t_j^\nu, t_{j-1}^\nu)$  for  $1 \leq |I| \leq k$  can be obtained from the Chen-Fliess series (5.12) by computing the exponential. Since  $|\tilde{\Delta} W_i(j, \nu)| \leq 2^{-\frac{2\nu}{5}}$ , it is clear that all the coefficients of  $S_{k,(j-1)2^{-\nu},j2^{-\nu}}(U^\nu) - 1$  (i.e. all the  $U_I^\nu(t_j^\nu, t_{j-1}^\nu)$  with  $1 \leq |I| \leq k$ ) are pointwise bounded by a fixed constant times  $2^{-\frac{2\nu}{5}}$ , so that (3.3) holds. Moreover, it follows from (5.12) that

$$(5.14) \quad \begin{aligned} S_{k,(j-1)2^{-\nu},j2^{-\nu}}(U^\nu) &= 1 + \sum_{i=1}^m \tilde{\Delta} W_i(j, \nu) X_i \\ &+ \sum_{i,i'=1}^m \tilde{\Delta} W_i(j, \nu) \tilde{\Delta} W_{i'}(j, \nu) X_i X_{i'} + \dots, \end{aligned}$$

where “...” denotes a finite sum of terms that are bounded by a fixed constant times  $2^{-\nu}$ . So the conditions of (3.1) and (3.2) will be trivially verified if we show that, if we let  $A$  be any of the variables  $V_i = \tilde{\Delta} W_i(j, \nu)$  or  $V_{ij} = \tilde{\Delta} W_i(j, \nu) \tilde{\Delta} W_{i'}(j, \nu)$ , then  $|\mathbb{E}(A)|$  and  $\mathbb{E}(A^2)$  are both bounded by a constant times  $2^{-\nu}$ . (Since  $A$  is independent from  $\mathcal{F}_{t_{j-1}^\nu}$ , we can compute true expectations instead of conditional ones.) And these bounds follow trivially from the fact that  $V_i = 2^{-\nu/2} H_i$ , where the  $H_i$  are obtained by symmetrically truncating normalized Gaussian random variables. This completes the proof that the bounds (3.1), (3.2), (3.3) hold.

As for (3.4), recall that the components  $u_i^\nu(t)$  satisfy (5.9). Since every integration over an interval of length  $\leq 2^{-\nu}$  improves the bound by a factor of  $2^{-\nu}$ , we conclude that a  $k$ -th order iterated integral of  $u^\nu$  is bounded by  $\kappa^k 2^{(\rho-1)k\nu}$ , i.e. by  $\kappa^k 2^{-\nu}$ . So

$$(5.15) \quad |(u^\nu)_I^{-,t}(s)| \leq \kappa^{k+1} 2^{(\rho-1)\nu},$$

and (3.4) holds, since  $\rho < 1$ . ■

It is clear from our construction that  $U^\nu(j2^{-\nu}) = W(j2^{-\nu})$  on  $\mathcal{B}_{T,N}$ , if  $j2^{-\nu} \leq T$ . In view of (5.9), we have  $\|U^\nu(t) - U^\nu(j2^{-\nu})\| \leq c2^{-\frac{\nu}{k}}$  pointwise, where  $c$  is a fixed constant. Since  $P(\mathcal{B}_{T,N}) \rightarrow 1$  as  $N \rightarrow \infty$ , and  $W$  has continuous sample paths, it follows that

$$(5.16) \quad P(\lim_{\nu \rightarrow \infty} (\sup \{\|W(t) - U^\nu(t)\| : 0 \leq t \leq T\}) = 0) = 1$$

for every  $T > 0$ , so the  $U^\nu$  are indeed approximations of  $W$ .

**6. Proof of Convergence.** We now fix an  $\mathcal{F}_0$ -measurable square-integrable initial condition  $\bar{X} : \Omega \rightarrow \mathbb{R}^n$ , and let  $t \rightarrow X(t)$  denote the Stratonovich solution of (1.3) such that  $X(0) = \bar{X}$ . Also, let  $W^\nu$  denote the ordinary input process such that  $W^\nu(t_j^\nu) = W(t_j^\nu)$  for all  $j$ , and  $W^\nu$  is linear on the intervals  $[t_{j-1}^\nu, t_j^\nu]$  of the partition  $\pi_\nu$ . Let  $w^\nu = \tilde{W}^\nu$ . Define  $\tilde{w}^\nu$  to be the result of truncating  $w^\nu$  as before, i.e. let  $\tilde{w}_i^\nu = w_i^\nu$  on  $[t_{j-1}^\nu, t_j^\nu]$  if on that interval  $|w_i^\nu| \leq 2^{-\frac{2\nu}{s}}$ , and otherwise let  $\tilde{w}_i^\nu = 0$ . We then let  $\tilde{W}^\nu$  be the integral of  $\tilde{w}^\nu$ .

It is clear that both  $W^\nu$  and  $\tilde{W}^\nu$  are  $\pi_\nu$ -adapted OIP's. Moreover, the  $\tilde{W}^\nu$  are in  $OIP(m, k, C, \pi_\nu)$  for a fixed  $C$ , independent of  $\nu$ , provided that  $k \geq 2$ . (The proof is analogous to, but easier than that of Lemma 5.1.) It is then easy to see that

$$(6.1) \quad S_{k,(j-1)2^{-\nu},j2^{-\nu}}(\tilde{W}^\nu) = e^{2^{-\nu}X_0 + \sum_{i=1}^m \tilde{\Delta}W_i(j,\nu)X_i}.$$

We now want to consider the maps  $\Phi_{a,b}^U$  defined for an OIP  $U$ , using the equation  $dx = (f_0(x) + g(x))dt + \sum_{i=1}^m f_i(x)dU_i$  instead of (2.1). We will use  $\hat{\Phi}_{a,b}^U$  to denote these maps, so as to avoid any confusion with the  $\Phi_{a,b}^U$  that are associated to (2.1).

**THEOREM 6.1.** *Let  $(\Omega, \mathcal{F}, P)$  be a probability space endowed with a filtration  $\{\mathcal{F}_t\}$ . Let  $W$  be an  $m$ -dimensional standard Wiener process with respect to  $\{\mathcal{F}_t\}$ . Let  $f_0, \dots, f_m \in C_b^\infty(\mathbb{R}^n, \mathbb{R}^n)$ , let  $\Lambda_0$  be the Lie algebra of vector fields generated by  $f_1, \dots, f_m$ , and let  $\Lambda = [\Lambda_0, \Lambda_0]$ . Let  $g \in \Lambda$ . Let  $\bar{X} \in L^2((\Omega, \mathcal{F}_0, P); \mathbb{R}^n)$ , and let  $t \rightarrow X(t)$  be the Stratonovich solution of (1.3) with  $X(0) = \bar{X}$ . Let  $\{U^\nu\}$  be the ordinary input processes constructed in §5. Then, for every  $T > 0$ ,*

$$(6.2) \quad \Phi_{T,0}^{U^\nu}(\bar{X}) \rightarrow X(T) \quad \text{a.s.} \quad \text{as} \quad \nu \rightarrow \infty.$$

**PROOF.** Lemma 3.1 gives us estimates

$$(6.3) \quad \|\Phi_{t_j^\nu, t_{j-1}^\nu}^{U^\nu}(X) - \Phi_{t_j^\nu, t_{j-1}^\nu}^{U^\nu}(Y)\|_{L_2} \leq (1 + K2^{-\nu})\|X - Y\|_{L^2},$$

$$(6.4) \quad \|\hat{\Phi}_{t_j^\nu, t_{j-1}^\nu}^{\tilde{W}^\nu}(X) - \hat{\Phi}_{t_j^\nu, t_{j-1}^\nu}^{\tilde{W}^\nu}(Y)\|_{L_2} \leq (1 + K2^{-\nu})\|X - Y\|_{L^2},$$

valid for all  $\nu, j$ , and all square-integrable  $\mathcal{F}_{t_{j-1}^\nu}$ -measurable  $X, Y$ . (The exponential factor that occurs in the formula of Lemma 3.1 is bounded independently of  $\nu$ , since  $|\pi_\nu| \leq 1$  for all  $\nu$ .)

Write  $X_j^\nu = \hat{\Phi}_{t_{j,0}^\nu}^{\tilde{W}^\nu}(\bar{X})$ ,  $Y_j^\nu = \Phi_{t_{j,0}^\nu}^{U^\nu}(\bar{X})$ , and  $Z_j^\nu = X_j^\nu - Y_j^\nu$ . Then  $X_j^\nu = \hat{\Phi}_{t_{j,t_{j-1}^\nu}^\nu}^{\tilde{W}^\nu}(X_{j-1}^\nu)$  and  $Y_j^\nu = \Phi_{t_{j,t_{j-1}^\nu}^\nu}^{U^\nu}(Y_{j-1}^\nu)$ , and therefore  $Z_j^\nu = A_j^\nu - B_j^\nu$ , where

$$\begin{aligned} A_j^\nu &= \hat{\Phi}_{t_{j,t_{j-1}^\nu}^\nu}^{\tilde{W}^\nu}(X_{j-1}^\nu) - \hat{\Phi}_{t_{j,t_{j-1}^\nu}^\nu}^{\tilde{W}^\nu}(Y_{j-1}^\nu) \\ B_j^\nu &= \hat{\Phi}_{t_{j,t_{j-1}^\nu}^\nu}^{\tilde{W}^\nu}(Y_{j-1}^\nu) - \Phi_{t_{j,t_{j-1}^\nu}^\nu}^{U^\nu}(Y_{j-1}^\nu) . \end{aligned}$$

From (6.4) we get the bound  $\|A_j^\nu\|_{L^2} \leq (1 + K2^{-\nu})\|Z_{j-1}^\nu\|_{L^2}$ .

We now estimate  $B_j^\nu$ . Let  $\hat{f} = f_0 + g$ ,  $\hat{f} = (\hat{f}_0, f_1, \dots, f_m)$ . Write  $a = t_{j-1}^\nu$ ,  $b = t_j^\nu$ . We pick  $k \geq \max(3, r(1), \dots, r(p))$ , and apply (2.7) for  $f$  with  $U = U^\nu$ , and for  $\hat{f}$  with  $U = \tilde{W}^\nu$ , and let  $t = b$ . We get

$$(6.5) \quad \Phi_{b,a}^{U^\nu}(x) = \sum_{|I| \leq k} U_I^\nu(b, a) E_I^f(x) + R_{k,b,a,U^\nu,E^n,f}(x) ,$$

$$(6.6) \quad \hat{\Phi}_{b,a}^{\tilde{W}^\nu}(x) = \sum_{|I| \leq k} \tilde{W}_I^\nu(b, a) E_I^{\hat{f}}(x) + R_{k,b,a,\tilde{W}^\nu,E^n,\hat{f}}(x) .$$

In view of (5.15), plus the analogous bound for  $\tilde{W}^\nu$ , and (2.8), the remainders  $R_{k,b,a,U^\nu,E^n,f}(x)$ ,  $R_{k,b,a,\tilde{W}^\nu,E^n,\hat{f}}(x)$  are bounded by a fixed constant times  $2^{-\theta\nu}$ . (Recall that  $\theta = 1 + \frac{1}{k}$ .) Moreover, we have

$$(6.7) \quad \sum_{|I| \leq k} U_I^\nu(b, a) E_I^f(x) = (S_{k,a,b}(U^\nu)(f)E^n)(x) ,$$

$$(6.8) \quad \sum_{|I| \leq k} \tilde{W}_I^\nu(b, a) E_I^{\hat{f}}(x) = (S_{k,a,b}(\tilde{W}^\nu)(\hat{f})E^n)(x) ,$$

where, for a noncommutative polynomial  $P$  in the  $X_i$ ,  $P(f)$  denotes the partial differential operator obtained by plugging in the  $f_i$  for the  $X_i$ . Using “...” to denote terms that are bounded by a fixed constant times  $2^{-\theta\nu}$ , we have

$$\begin{aligned} S_{k,a,b}(U^\nu) &= 1 + (b - a)(X_0 + G) + V + \dots , \\ S_{k,a,b}(\tilde{W}^\nu) &= 1 + (b - a)X_0 + V + \dots , \end{aligned}$$

where  $V = \sum_{i=1}^m \tilde{\Delta} W_i(j, \nu) X_i + \sum_{i,i'=1}^m \tilde{\Delta} W_i(j, \nu) \tilde{\Delta} W_{i'}(j, \nu) X_i X_{i'}$ , so that

$$\begin{aligned} \sum_{|I| \leq k} U_I^\nu(b, a) E_I^f(x) &= x + (b - a)(f_0(x) + g(x)) + V(f)(x) + \dots , \\ \sum_{|I| \leq k} \tilde{W}_I^\nu(b, a) E_I^{\hat{f}}(x) &= x + (b - a)\hat{f}_0(x) + V(f)(x) + \dots , \end{aligned}$$

with  $V(f) = \sum_{i=1}^m \tilde{\Delta} W_i(j, \nu) f_i + \sum_{i,i'=1}^m \tilde{\Delta} W_i(j, \nu) \tilde{\Delta} W_{i'}(j, \nu) f_i f_{i'} E^n$ .

Since  $\hat{f}_0 = f_0 + g$ , we conclude that  $\|B_j^\nu\| \leq \gamma 2^{-\theta\nu}$  pointwise, where  $\gamma$  is a fixed constant.

Therefore  $\|Z_j^\nu\|_{L^2} \leq (1 + K 2^{-\nu}) \|Z_{j-1}^\nu\|_{L^2} + \gamma 2^{-\theta\nu}$ . From this it follows easily by induction on  $j$  that  $\|Z_j^\nu\|_{L^2} \leq j e^{j K 2^{-\nu}} \gamma 2^{-\theta\nu}$ , i.e.

$$(6.9) \quad \|\hat{\Phi}_{T,0}^{\bar{W}^\nu}(\bar{X}) - \Phi_{T,0}^{U^\nu}(\bar{X})\|_{L^2} \leq \gamma T e^{KT} 2^{-\frac{\nu}{k}},$$

if  $T = t_j^\nu = j 2^{-\nu}$ . Actually, (6.9) holds for arbitrary  $T$ , with the factor  $\gamma T$  replaced by  $\gamma(T + \lambda)$  for some fixed  $\lambda > 0$ . (To see this, let  $t_{j-1}^\nu \leq T < t_j^\nu$ , and notice that (2.4) (for  $U = U^\nu$ ,  $\varphi = E^n$ ) together with (5.9) imply the pointwise bound  $\|\Phi_{T,t_{j-1}}^{U^\nu}(x) - x\| \leq \text{constant} \cdot 2^{-\frac{\nu}{k}}$ . A similar bound holds for  $\hat{\Phi}_{T,t_{j-1}}^{\bar{W}^\nu}(\cdot)$ .)

It follows from (6.9) that  $\hat{\Phi}_{T,0}^{\bar{W}^\nu}(\bar{X}) - \Phi_{T,0}^{U^\nu}(\bar{X}) \rightarrow 0$  almost surely. On the set  $\mathcal{B}_{T,N}$ ,  $\hat{\Phi}_{T,0}^{\bar{W}^\nu}(\bar{X}) = \hat{\Phi}_{T,0}^{W^\nu}(\bar{X})$  for sufficiently large  $\nu$ . Since  $P(\cup_N \mathcal{B}_{T,N}) = 1$ , we conclude that  $\hat{\Phi}_{T,0}^{\bar{W}^\nu}(\bar{X}) - \Phi_{T,0}^{W^\nu}(\bar{X}) \rightarrow 0$  almost surely. Finally,  $\hat{\Phi}_{T,0}^{W^\nu}(\bar{X})$  converges a.s. to  $X(T)$  by the Wong-Zakai theorem. So (6.2) holds. ■

## REFERENCES

- [1] N. Bourbaki, *Groupes et Algèbres de Lie*, Éléments de Mathématique, Fascicule XXXVII, Chap. II et III, Hermann, Paris, 1972.
- [2] M. Fliess, *Réalisation locale des systèmes non linéaires, algèbres de Lie filtrées transitives et séries génératrices non commutatives*, Invent. Math. **71**, 1983, p. 521-537.
- [3] N. Ikeda and S. Watanabe, *Stochastic Differential Equations and Diffusion Processes*, North-Holland, 1981.
- [4] E. J. McShane, *On the use of stochastic differentials in models of random processes*, Proc. Sixth Berkeley Symp. Math. Statist. Prob. **3**, 1972, p. 263-294.
- [5] R. L. Stratonovich, *A new form of representation of stochastic integrals and equations*, SIAM J. Control, 1966, p. 362-371.
- [6] H. J. Sussmann, *Lie brackets and local controllability: a sufficient condition for scalar input systems*, SIAM J. Control and Optimization **21**, 1983, p. 686-713.
- [7] H. J. Sussmann, *A general theorem on local controllability*, SIAM J. Control and Optimization **25**, 1987, p. 158-194.
- [8] H. J. Sussmann, *Exponential Lie series and the discretization of stochastic differential equations*, in "Stochastic Differential Systems, Stochastic Control and Applications," W. H. Fleming and P. L. Lions Eds., I.M.A. vols. in Math. and its Apps. No. 10, Springer-Verlag, 1988, p. 563-582.
- [9] E. Wong and M. Zakai, *On the relationship between ordinary and stochastic differential equations and applications to stochastic problems in control theory*, Proc. Third IFAC Congress, 1966, paper 3B.
- [10] E. Wong and M. Zakai, *Riemann-Stieltjes approximations of stochastic integrals*, Z. Wahrscheinlichkeitstheorie und Verw. Gebiete **12**, 1969, p. 87-97.