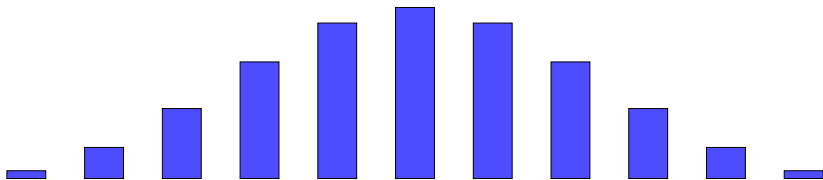


# Equality cases of Alexandrov–Fenchel inequality are not in PH

Swee Hong Chan

joint with Igor Pak



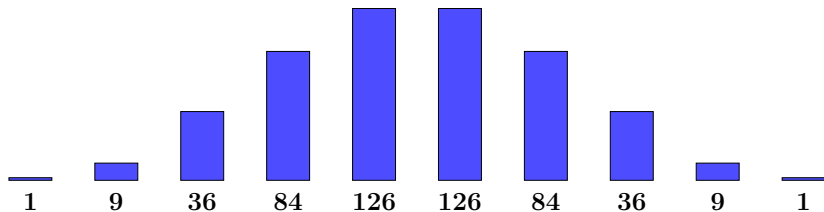
## Log-concavity

A sequence  $a_1, \dots, a_n \in \mathbb{R}_{\geq 0}$  is **log-concave** if

$$a_k^2 \geq a_{k+1} a_{k-1} \quad (1 < k < n).$$

Log-concavity (and positivity) implies **unimodality**:

$a_1 \leq \dots \leq a_m \geq \dots \geq a_n$  for some  $1 \leq m \leq n$ .



## Example: binomial coefficients

$$a_k = \binom{n}{k} = \frac{n!}{k!(n-k)!} \quad k = 0, 1, \dots, n.$$

This sequence is **log-concave** because

$$\frac{a_k^2}{a_{k+1} a_{k-1}} = \frac{\binom{n}{k}^2}{\binom{n}{k+1} \binom{n}{k-1}} = \left(1 + \frac{1}{k}\right) \left(1 + \frac{1}{n-k}\right),$$

which is greater than 1.

## Example: forests of a graph

$a_k$  = number of forests with  $k$  edges of graph  $G$ .

**Forest** is a subset of edges of  $G$  that has no cycles.

**Log-concavity** was conjectured for all **matroids** (Mason '72), and was proved through **combinatorial Hodge theory** (Huh '15).



$G$



forest



not forest



spanning tree

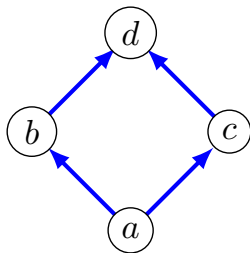
Log-concavity has been observed in different areas of mathematics and proved through different methods.

Today we focus on log-concavity that arises from **Convex Geometry**.

# **Stanley's poset inequality**

## Partially ordered sets

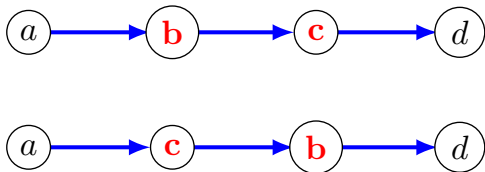
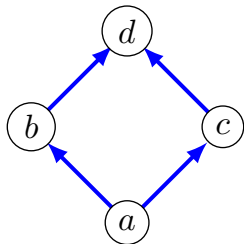
A poset  $\mathcal{P}$  is a set  $X$  with a partial order  $\prec$  on  $X$ .



We write  $n := |X|$ .

# Linear extension

A linear extension  $L$  is a complete order of  $\prec$ .



We write  $L(x) = k$  if  $x$  is  $k$ -th smallest in  $L$ .



## Stanley's (poset) inequality: simple form

Fix  $x \in \mathcal{P}$ .

$N(k) :=$  number of linear extensions with  $L(x) = k$ .

### Theorem (Stanley '81)

For  $k \geq 1$ ,

$$N(k)^2 \geq N(k+1)N(k-1).$$

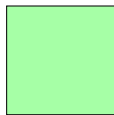
The inequality was initially conjectured by Chung-Fishburn-Graham, and was proved using Aleksandrov-Fenchel inequality for mixed volumes.

## Mixed volumes: dimension 2

For convex bodies  $K, L \subseteq \mathbb{R}^2$ ,

$$\text{Vol}(aK+bL) = V(K, K)a^2 + V(L, L)b^2 + 2V(K, L)ab$$

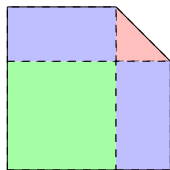
is a quadratic polynomial in  $a, b \geq 0$ .



$K$



$L$



$K + L$

Coefficients  $V(K, K)$ ,  $V(L, L)$ ,  $V(K, L)$   
are mixed volumes.

## Mixed volumes: dimension $m$

### Theorem (Minkowski '03)

For *convex* bodies  $C_1, \dots, C_m \subseteq \mathbb{R}^m$ , the function

$$(\lambda_1, \dots, \lambda_m) \mapsto \text{Vol}(\lambda_1 C_1 + \dots + \lambda_m C_m)$$

is a *homogeneous polynomial* in  $\lambda_1, \dots, \lambda_m \geq 0$ .

**Mixed volume**  $V(C_1, \dots, C_m)$  is  $\frac{1}{m!}$  of the coefficient of  $\lambda_1 \cdots \lambda_m$  in the polynomial expansion of  $\text{Vol}(\lambda_1 C_1 + \dots + \lambda_m C_m)$ .

## Alexandrov-Fenchel (AF) inequality

Theorem (Alexandrov '37, Fenchel '36)

For convex bodies  $A, B, C_1, \dots, C_{m-2} \subseteq \mathbb{R}^m$ ,

$$V^*(A, B)^2 \geq V^*(A, A) V^*(B, B),$$

where  $V^*(A, B) := V(A, B, C_1, \dots, C_{m-2})$ .

Stanley's inequality  $N(k)^2 \geq N(k+1)N(k-1)$

follows by substituting  $A, B, C_1, \dots, C_{m-2}$  with  
slices of **order polytopes** of the poset.

## Proof of Stanley's inequality

For poset  $\mathcal{P}$ , the **order polytope** is

$$\mathcal{O}(\mathcal{P}) := \{ \mathbf{t} \in [0, 1]^{\mathcal{P}} \mid t_y \leq t_z \text{ if } y \prec z \text{ in } \mathcal{P} \}.$$

For  $x \in \mathcal{P}$ , the slices are:

$$K := \{ \mathbf{t} \in \mathcal{O}(\mathcal{P}) \mid t_x = 0 \},$$

$$L := \{ \mathbf{t} \in \mathcal{O}(\mathcal{P}) \mid t_x = 1 \}.$$

Let  $n := |\mathcal{P}|$ , and set

$$A := K, \quad B := L,$$

$$C_1, \dots, C_{n-3} := \underbrace{K, \dots, K}_{n-k-1}, \underbrace{L, \dots, L}_{k-2}.$$

## Proof of Stanley's inequality

Then

$$V^*(A, B) = \frac{1}{(n-1)!} N(k), \quad V^*(A, A) = \frac{1}{(n-1)!} N(k-1),$$

$$V^*(B, B) = \frac{1}{(n-1)!} N(k+1).$$

Thus

$$V^*(A, B)^2 \geq V^*(A, A) V^*(B, B) \quad (\text{AF})$$

implies

$$N(k)^2 \geq N(k+1) N(k-1) \quad (\text{Stanley}).$$

## Stanley's (poset) inequality: true form

Fix  $d \geq 0$ ,  $x, y_1, \dots, y_d \in \mathcal{P}$  and  $\ell_1, \dots, \ell_d \in \mathbb{N}$ .

$N_d(k) :=$  number of linear extensions with  
 $L(x) = k, \quad L(y_i) = \ell_i \quad \text{for } i \in [d].$

### Theorem (Stanley '81)

For  $k \geq 1$ ,

$$N_d(k)^2 \geq N_d(k+1) N_d(k-1).$$

But an elementary/combinatorial proof of Stanley's inequality remains elusive.

## **Equality conditions**



## When is equality achieved?

### Question (Alexandrov '37)

*When does  $AF$  inequality achieve equality?*

### Quote (Alexandrov '37)

*“Serious difficulties occur in determining the conditions for equality to hold in  $AF$  inequality.”*

## When is equality achieved?

### Quote (Gardner '02)

*If inequalities are **silver** currency in mathematics, those that come along with precise equality conditions are **gold**.*

### Example (Isoperimetric problem)

*Among all closed curves in the plane of **fixed perimeter**, the curve that **maximizes** the **area** of its enclosed region is the **circle**.*

## (Informal) answer for convex polytopes

### Theorem (Shenfeld-van Handel '23)

Let  $A, B, C_1, \dots, C_{m-2}$  be *convex polytopes*. Then

$$V^*(A, B)^2 = V^*(A, A) V^*(B, B)$$

*arises from a combination of three mechanisms:*

- *Translation and scaling;*
- *Relative positions of normal cones of boundaries of  $C_1, \dots, C_{m-2}$ ;*
- *Relative positions of affine hulls of  $C_1, \dots, C_{m-2}$ .*

The key takeaway is the equality condition of AF inequality is extremely complicated.

The key takeaway is the equality condition of AF inequality is extremely complicated.

We can in fact prove this statement rigorously by using **Complexity Theory**.

## Complexity theory perspective

Consider the decision problem:

Input: **unimodular polytopes**  $A, B, C_1, \dots, C_{m-2}$ ;

Output: - YES if  $V^*(A, B)^2 = V^*(A, A) V^*(B, B)$ ;

- NO if  $V^*(A, B)^2 > V^*(A, A) V^*(B, B)$ .

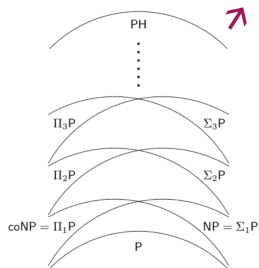
**Theorem (C.–Pak '24)**

*This decision problem **cannot be solved** in **polynomial time**, unless **NP = coNP**.*

## A stronger result

### Theorem (C.–Pak '24)

*This decision problem **does not belong** to the **polynomial hierarchy (PH)**, unless **PH collapses**.*



Thus the **geometric description** of **AF equality** must be **computationally intractable**.

## Back to posets

Consider the decision problem:

Input: poset  $\mathcal{P}$ ,  $x, y_1, \dots, y_d \in \mathcal{P}$ ,  $\ell_1, \dots, \ell_d \in \mathbb{N}$ .

Output: - YES if  $N_d(k)^2 = N_d(k+1) N_d(k-1)$ ;

- NO if  $N_d(k)^2 > N_d(k+1) N_d(k-1)$ .

### Theorem (C.–Pak '24)

*This decision problem **does not belong** to the **polynomial hierarchy (PH)**, unless **PH collapses**.*



## Application of main result

An injection  $f : A \rightarrow B$  is **combinatorial** if both  $f$  and  $f^{-1}$  are poly-time computable.

### Corollary (C.–Pak '24)

There is *no combinatorial injective proof* for *Stanley's inequality*

$$N_d(k)^2 \geq N_d(k+1) N_d(k-1)$$

*unless PH collapses.*

# THANK YOU!

Preprint: [www.arxiv.org/abs/2309.05764](http://www.arxiv.org/abs/2309.05764)

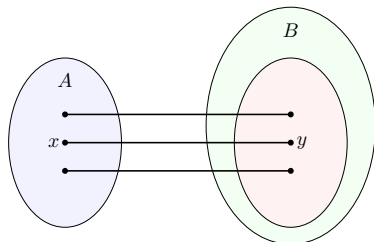
Webpage: [www.math.rutgers.edu/~sc2518/](http://www.math.rutgers.edu/~sc2518/)

Email: [sweehong.chan@rutgers.edu](mailto:sweehong.chan@rutgers.edu)

## Combinatorial injection

An injection  $f : A \rightarrow B$  is **combinatorial** if

- Given  $x \in A$ , the image  $f(x)$  is computable in  $\text{poly}(|x|)$  steps;
- Given  $y \in B$ , it takes  $\text{poly}(|y|)$  steps **to decide if  $y$  is in image of  $f$** ; and if so, the pre-image  $f^{-1}(y)$  is computable in  $\text{poly}(|y|)$  steps.



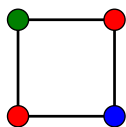
## Complexity class P

$P := \left\{ \begin{array}{l} \text{Decision problems solvable by } \text{deterministic} \\ \text{Turing machine in } \text{polynomial} \text{ time} \end{array} \right\}$

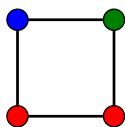
### Example

*Check if a given 3-coloring of a graph  $G$  is proper.*

This can be solved in  $O(n^2)$  time by checking the color of endpoints of every edge.



YES

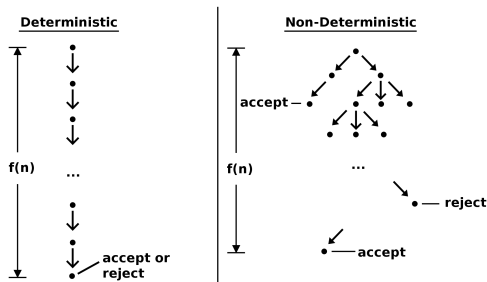


NO

# Complexity class NP

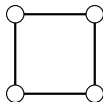
NP := { Decision problems solvable by **nondeterministic** Turing machine in **polynomial** time }

- Can split into many parallel **branches**;
- Output 'YES' if **one of the branches** said 'YES';
- Output 'NO' if **all branches** said 'NO'.

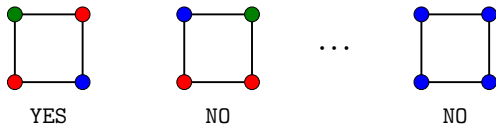


## Complexity class NP: example

**Problem:** Check if graph  $G$  has a proper 3-coloring.



Each branch corresponds to checking if a particular 3-coloring of  $G$  is proper.

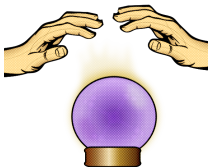


Output to this example is 'YES'.

# Turing machine with an oracle

At each step, this machine can either:

- Perform usual **nondeterministic** Turing machine operation; or
- Ask an **oracle** that is able to answer any instance of a given computational problem.

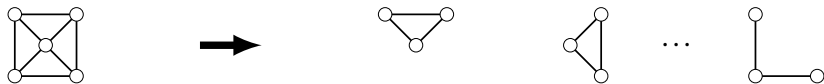


## Turing machine with an oracle: example

**Problem:** Check if there is an induced subgraph of  $G$  of size  $\lceil n/2 \rceil$  that is not 3-colorable.

**Oracle:** Can check if a graph is 3-colorable.

Each branch of the machine corresponds to an induced subgraph of  $G$  of size  $\lceil n/2 \rceil$ .



For every branch, **oracle** checks if subgraph is 3-colorable.



## Complexity class $\Sigma_i^P$

The first two classes are

$$\Sigma_0^P := P; \quad \Sigma_1^P := NP.$$

For  $i \geq 1$ , the class  $\Sigma_i^P := NP^{\Sigma_{i-1}^P}$  is

{ Decision problems solvable by **nondeterministic** Turing machine in **polynomial** time  
with an **oracle** for problem from  $\Sigma_{i-1}^P$ . }

Note that

$$\Sigma_0^P \subseteq \Sigma_1^P \subseteq \Sigma_2^P \subseteq \Sigma_3^P \subseteq \dots$$

# Polynomial hierarchy (PH)

Polynomial hierarchy is the union of all  $\Sigma_i^P$ 's,

$$\text{PH} := \bigcup_{i=0}^{\infty} \Sigma_i^P.$$

## Conjecture

*Polynomial hierarchy does not collapse,*

$$\Sigma_0^P \subsetneq \Sigma_1^P \subsetneq \Sigma_2^P \subsetneq \Sigma_3^P \subsetneq \dots$$

- $\Sigma_0^P = \Sigma_1^P$  is equivalent to  $P = NP$ .
- $\Sigma_1^P = \Sigma_2^P$  is equivalent to  $NP = \text{coNP}$ .