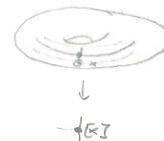


Recall from last time

Theorem If  $G$  a Lie group acts on  $M$  smoothly, freely, and properly,  
 $M/G$  is a manifold &  $\pi: M \rightarrow M/G$  is smooth.



Corollary 1 If a closed immersed Lie subgroup  $H \subset G$  is a manifold w/ a smooth transitive action of  $G$ ,

Corollary 2 A closed immersed Lie subgroup  $H \subset G$  is embedded in  $G$ .

Corollary 3 If  $G$  acts on  $M$  smoothly & properly, the orbits  $Gx$  are regular submanifolds diffeomorphic to  $G/G_x \hookrightarrow \text{stabilizer}$ .

$$\text{eg } S^{n-1} \cong O(n)/O(n-1)$$

$$\mathbb{R}\mathbb{P}^{n-1} \cong O(n)/O(1) \times O(n-1)$$

$$S^{2n-1} \cong U(n)/U(n-1)$$

$$\mathbb{C}\mathbb{P}^{n-1} \cong U(n)/U(1) \times U(n-1)$$

$$S^{4n-1} \cong Sp(n)/Sp(n-1)$$

$$\mathbb{H}\mathbb{P}^{n-1} \cong Sp(n)/Sp(k) \times Sp(n-k)$$

Example For  $0 < k < n \in \mathbb{N}$ ,  $G_k \mathbb{R}^n = \{\text{linear subspaces of dim } k \text{ in } \mathbb{R}^n\}$   
Any orthonormal basis for  $U \in G_k \mathbb{R}^n$  can be extended to an ONB for  $\mathbb{R}^n \Rightarrow O(n)$  acts transitively on  $G_k \mathbb{R}^n$ .

If  $U = \text{Span}\{e_1, \dots, e_k\}$ ,  $G_U = \left\{ \begin{pmatrix} * & & & \\ \hline & 0 & & \\ & & * & \\ & & & * \end{pmatrix} \in O(n) \right\} \subset O(k) \times O(n-k)$

$$\hookrightarrow \text{Gr}_k(\mathbb{R}^n) \cong O(n)/O(k) \times O(n-k)$$

$$\text{Gr}_k \mathbb{C}^n \cong U(n)/U(k) \times U(n-k)$$

$$\text{Gr}_k \mathbb{H}^n \cong Sp(n)/Sp(k) \times Sp(n-k)$$

### The Low-Dimensional Coincidences

Recall we have

$$1 \longrightarrow SO(n) \longrightarrow O(n) \xrightarrow{\sim} O(1) \longrightarrow 1$$

\$1 \cong \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}\$

\$SO(n)\$

\$\begin{matrix} \downarrow & \downarrow \\ \mathbb{Z}/2\mathbb{Z} & \end{matrix}\$

Splits but not  
a direct product  
(eg \$O(n)\$ nor abelian)  
 $O(n) \cong SO(n) \rtimes \mathbb{Z}/2\mathbb{Z}$

$$1 \longrightarrow SU(n) \longrightarrow U(n) \xrightarrow{\sim} U(1) \longrightarrow 1$$

\$SU(n)\$

\$\begin{matrix} \downarrow & \downarrow \\ \mathbb{Z} & \end{matrix}\$

(No comparable special group for the quaternions; the determinant is not a well-defined homomorphism.)

Complex numbers arbi \$\hookrightarrow\$ Real matrices

$$\begin{pmatrix} a & -b \\ b & a \end{pmatrix}$$

Quaternions

$$a+bi+cj+dj = (a+bi)+(cj+di)j$$

Complex  
matrices

$$\begin{pmatrix} a+ib & c+id \\ -c+id & a-ib \end{pmatrix}$$

Unit quaternions

$$Sp(1) \hookrightarrow SU(2)$$

as

$$\left\{ \begin{pmatrix} \alpha & -\bar{\beta} \\ \beta & \bar{\alpha} \end{pmatrix} : |\alpha|^2 + |\beta|^2 = 1 \right\}$$

For  $v = a + bi + c_1j + dk$ , let  $\operatorname{Re}(v) = a$ ,  $\operatorname{Im}(v) = bi + c_1j + dk$ .

Let  $\langle \cdot, \cdot \rangle$  be the normal dot product on  $\mathbb{R}^4$ , so that

$$\underbrace{\langle a + bi + c_1j + dk, a_2 + b_2i + c_2j + d_2k \rangle}_{\langle v, v' \rangle} = a_1a_2 + b_1b_2 + c_1c_2 + d_1d_2 = \operatorname{Re}(vv'),$$

Note that  $\operatorname{Re}(H)^\perp = \operatorname{Im}(H)$ .

Now  $v \in \operatorname{Sp}(1) \subset H$  by  $v \cdot w = vw\bar{v}$ . Note  $\operatorname{Re}(v\bar{v}) = 1$   $\operatorname{Re}(v\bar{j}\bar{v}) = 0$   
 $\operatorname{Re}(v\bar{i}\bar{v}) = 0$   $\operatorname{Re}(v\bar{k}\bar{v}) = 0$

So  $\operatorname{Re}(v \cdot w) = \operatorname{Re}(w)$ . But also

$$\begin{aligned} \langle v \cdot w, v \cdot w' \rangle &= \operatorname{Re}(vw\bar{v}(vw'\bar{v})) \\ &= \operatorname{Re}(vw\bar{v}\bar{v}w'\bar{v}) \\ &= \operatorname{Re}(vw\bar{v}v\bar{w}'\bar{v}) \\ &= \operatorname{Re}(vw\bar{w}'\bar{v}) \\ &= \operatorname{Re}(w\bar{w}') \\ &= \langle w, w' \rangle \end{aligned}$$

So  $\operatorname{Sp}(1)$  acts orthogonally on  $H$ . Hence since  $i*$  acts orthogonally on  $\operatorname{Re}(H)$ , it also does on  $\operatorname{Im}(H)$ .

This gives a homomorphism  $\varphi: \operatorname{Sp}(1) \rightarrow O(3)$ . Since  $\operatorname{Sp}(1)$  is connected, actually  $\varphi: \operatorname{Sp}(1) \rightarrow SO(3)$ .

$$\begin{array}{c} \operatorname{SU}(2) \\ \downarrow \\ \operatorname{SO}(3) \\ \downarrow \\ S^3 \end{array}$$

What is  $\ker \varphi$ ? If  $v = a + bi + c_1j + dk$  w/  $a^2 + b^2 - c_1^2 - d^2 = 1$ ,  $v \in \ker \varphi$  if  
 $vw\bar{v} = w \quad \forall w \in H$ . In particular  $v\bar{i}\bar{v} = i \Rightarrow vi = iv$   
 $\Rightarrow ai - bi - ck + dk = ai - bi + ck - dk \Rightarrow c, dk = 0$ . Likewise  $v\bar{j}\bar{v} = jv \Rightarrow b = 0$ ,  
so  $v = a \pm 1$ , and  $\ker \varphi = \{ \pm 1 \}$ .

So  $Sp(1) \xrightarrow{\varrho} SO(3)$ , As  $\mathbb{Z}/2\mathbb{Z}$  is normal,  $Sp(1)/\mathbb{Z}/2\mathbb{Z}$  is a

$$\begin{array}{c} \nearrow \\ Sp(1) \\ \searrow \end{array} / \mathbb{Z}/2\mathbb{Z}$$

Lie group, so  $\varrho: Sp(1) \rightarrow SO(3) \cong Sp(1)/\mathbb{Z}/2\mathbb{Z}$  is smooth if has

constant rank, it is bijective, hence is an immersion.

So  $SO(3) \cong SU(2)/\mathbb{Z}/2\mathbb{Z}$  as Lie groups.  $SU(2) \cong S^3$ . This is a

$$SO(3) \hookrightarrow \mathbb{R}P^3$$

double cover. ( $\pi_1(S^3) = 0$  and  $\pi_1(SO(3))$  is generated by  $\gamma(t) = \begin{pmatrix} \cos(2\pi t) & \sin(2\pi t) & 0 \\ -\sin(2\pi t) & \cos(2\pi t) & 0 \\ 0 & 0 & 1 \end{pmatrix}$ )

### The Hopf Fibration

Now  $SO(3) \hookrightarrow S^3$  transitively w/  $G_{e_i} = \{g \in SO(3); ge_i = e_i\} \cong SO(2) \cong S^1$

Hence  $S^2 \cong SO(3)/SO(2)$ .

It follows that  $SU(2)$  acts on  $S^2$  transitively, and

$$\varrho^{-1}(SO(2)) = \{v \in Sp(1); v i \bar{v} = i\} = \left\{ \begin{pmatrix} a+bi & 0 \\ 0 & a-bi \end{pmatrix}; a+bi \in U(1) \right\}$$

$$\Rightarrow S^2 \cong Sp(2)/_{U(1)} \cong S^3/S^1$$

So there is a smooth map  $F: S^3 \longrightarrow S^2$  w/ kernel  $S^1$ ,  
 $A \longmapsto Ae_r$

This is the Hopf fibration. (Note that this is not a product,  
any invariant of algebraic topology shows  $S^2 \times S^1 \neq S^3$ .)

Similarly, the structure of  $SO(4)$

$$\text{Dimension } \frac{4(4-1)}{2} = 6,$$

Let  $Sp(1) \times Sp(1) \subset H$  b/  $(u, v) \cdot w = uw\bar{v}$ . Then

$$\begin{aligned} \langle (u, v) \cdot w, (u, v) \cdot w' \rangle &= \operatorname{Re}(uw\bar{v}(\overline{uw'\bar{v}})) \\ &= \operatorname{Re}(uw\bar{v}v\bar{w}'\bar{u}) \\ &= \operatorname{Re}(uw\bar{w}'\bar{u}) \\ &= \operatorname{Re}(ww') \\ &= \langle w, w' \rangle \end{aligned}$$

As before  $(u, v) \mapsto (u, v)_+$  defines a homomorphism

$\psi: Sp(1) \times Sp(1) \rightarrow SO(4)$ . What is  $\ker \psi$ ?  $uw\bar{v} = w \forall w \in H$

$$\Rightarrow uw = vw \quad \forall w \in H \text{ including 1}$$

$$\Rightarrow u = v \Leftrightarrow u = \pm 1 \text{ by last time}$$

$$\text{So } \ker \psi = \mathbb{Z}/2\mathbb{Z}$$

Ergo  $\frac{Sp(1) \times Sp(1)}{\mathbb{Z}/2\mathbb{Z}} \rightarrow SO(4)$  is an embedding, and both are

connected and of dimn 6, so  $SO(4) \cong Sp(1) \times Sp(1)/\langle \{e_i, e_j, (-e_i, -e_j)\} \rangle$

## Application to Grassmannians

Know  $\mathrm{SO}(4) \subset \mathrm{Gr}_2 \mathbb{R}^4$  transitively

$\Rightarrow \mathrm{SU}(2) \times \mathrm{SU}(2) \subset \mathrm{Gr}_2 \mathbb{R}^4 \cong \{\text{real 2-d subspaces of } \mathbb{H}^2\}$

$$(\mathrm{SU}(2) \times \mathrm{SU}(2))_{\langle i, j \rangle} = \underbrace{\mathrm{U}(1) \times \mathrm{U}(1)}_{\text{the diagonal matrices}} \quad \text{where} \quad \mathrm{U}(1) \cong \left\{ \begin{pmatrix} a & 0 \\ 0 & \bar{a} \end{pmatrix} \right\}$$

correspond to  
arbitrary  $a_j + b_k i$

$$\text{Hence } \mathrm{Gr}_2 \mathbb{R}^4 \cong \frac{\mathrm{SU}(2) \times \mathrm{SU}(2)}{\mathrm{U}(1) \times \mathrm{U}(1)} \stackrel{s^3}{\cong} \frac{\mathrm{SU}(2)}{\mathrm{U}(1)} \times \frac{\mathrm{SU}(2)}{\mathrm{U}(1)} \stackrel{s^2 \times s^2}{\cong} \frac{\mathrm{SU}(2)}{\mathrm{U}(1)} \times \frac{\mathrm{SU}(2)}{\mathrm{U}(1)}$$

One more  $\frac{\mathrm{Sp}(2)}{\mathbb{Z}/2\mathbb{Z}} \cong \mathrm{SO}(5)$  (Harder.)

## Vector Fields $\rightsquigarrow$ Lie Algebras

Defn A vector field on  $M$  is a function  $Y: M \rightarrow \bigcup_{p \in M} T_p M$ .

st ①  $\forall p \in M, Y(p) \in T_p M$

② A chart  $\varrho: U \rightarrow V \subseteq \mathbb{R}^n$ , if  $\theta: \bigcup_{v \in V} T_v \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the natural map,  
 $\theta \circ \varrho_x \circ Y|_U: U \rightarrow \mathbb{R}^n$  is smooth.

In particular, if  $M \subseteq \mathbb{R}^n$  is open,  $Y(x) = \sum_{i=1}^n y_i(x) \frac{\partial}{\partial x_i}$  for  $y_i \in C^\infty(M)$ ,

Defn The tangent bundle to  $M$  is  $TM := \bigcup_{p \in M} T_p M$  equipped w/ the structure  
of a  $2n$ -diml mfd as follows: For each chart  $\varrho: U \rightarrow V \subseteq \mathbb{R}^n$   
in an atlas for  $M$ , let  $\tilde{U} = \bigcup_{p \in U} T_p M$ , and  $\tilde{V} = \bigcup_{q \in V} T_q \mathbb{R}^n \cong V \times \mathbb{R}^n$  an open  
subset of  $\mathbb{R}^{2n}$ . Then take  $\tilde{\varrho}: \tilde{U} \rightarrow \tilde{V}$  to be  $(\varrho(p), D_p \varrho(u))$  for  $u \in T_p M$ .

$TM$

$\varrho$  a diffeomorphism  $\Rightarrow \tilde{\varrho}$  is a bijection.

And if  $\varrho: U \rightarrow V$ ,  $\varrho': U' \rightarrow V'$ ,  $q = \varrho(p) \in \varrho(U)$ ,

$$\tilde{\varrho}' \circ \tilde{\varrho}(p) = \tilde{\varrho}'(D_p \varrho)^{-1} v$$

$$= (\varrho'(p), D_p \varrho' \circ D_p \varrho^{-1} v)$$

$$= (\varrho' \circ \varrho^{-1}(q), D_q (\varrho' \circ \varrho^{-1}) v)$$

$\nearrow \searrow$   
both smooth  
by construction

So  $\tilde{\varrho}' \circ \tilde{\varrho}$  is smooth where it exists.

Example  $T\mathbb{S}^2 \neq S^2 \times \mathbb{R}^2$



Clearly  $n: TM \rightarrow M$  is smooth.

Exercise  $F: M \rightarrow N$  smooth induces smooth  $f_* = DF: TM \rightarrow TN$ .

Defn A vector field on  $M$  is a smooth  $\gamma: M \rightarrow TM$  or  $m \circ \gamma = \text{id}_M$ .

We can add two vector fields in a sensible way; the set of vector fields on  $M$  is a vector space  $VF(M)$ .

### Global Derivations

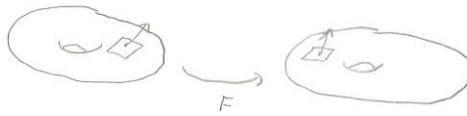
Defn A global derivation on  $M$  is a linear map  $\gamma: C^\infty(M) \rightarrow C^\infty(M)$  satisfying  $\gamma(fg) = \gamma(f)g + f\gamma(g)$ .

$GD(M)$  is also a vector space.

Then  $GD(M) \cong VF(M)$

Pf Smooth vector field  $\gamma = \sum_{i=1}^n y_i(x) \frac{\partial}{\partial x_i}$  in each chart  $U$ , so for  $f \in C^\infty(M)$ ,  $\gamma f|_U = \sum_{i=1}^n y_i(x) \frac{\partial f}{\partial x_i}(x) \in C^\infty(U) \Rightarrow \gamma f \in C^\infty(M)$ . This gives a natural map  $VF(M) \rightarrow GD(M)$ . Now if  $\gamma \in GD(M)$ , we claim that the map  $p \mapsto \gamma(p)$  is a smooth vector field. Locally  $(\gamma)_x$  is  $\sum_{i=1}^n y_i(x) \frac{\partial}{\partial x_i}$  for some functions  $y_i$ . It suffices to check these functions are smooth. Let  $x_j$  be coordinate functions on  $U$ , and extend to  $M$  using a bump function (see hw), so  $\gamma x_j \in C^\infty(M)$ . Then  $(\gamma x_j)(x) = \sum_{i=1}^n y_i(x) \frac{\partial}{\partial x_i}(x_j) = y_j(x) \in C^\infty(M)$ .

Def If  $Y \in \text{VF}(M)$ ,  $F: M \rightarrow N$  a diffeomorphism, the push-forward  $FY \in \text{VF}(N)$  is the vector field such that  $FY(F(p)) = F(Y(p))$ .



(\*) Lemma from page 10 here

Smoothness  $FY = F_* \circ Y \circ F^{-1}$  is smooth.

### The Lie bracket

If  $X, Y \in \text{VF}(M) = \text{GD}(M)$ , then  $F \mapsto XY(F)$  is not in general in  $\text{GD}(M)$ .

$$\begin{aligned} XY(F_g) &= X((YF)_g + F(Y_g)) \\ &= X(YF)_g + XF(Y_g) \\ &= (XYF)_g + \underline{(YF)(x_g)} + \underline{(XF)(Y_g)} + F(XY_g) \end{aligned}$$

But  $F \mapsto XYF - YXF \in \text{GD}(M)$  does satisfy the Leibniz rule. (Notice the

so  $X, Y$  define a new vector field called the Lie bracket. unfortunate terms above are symmetric

### Case of $\mathbb{R}^n$

$$\text{Open } U \subseteq \mathbb{R}^n, \quad X = \sum_{i=1}^n f_i \frac{\partial}{\partial x_i}, \quad Y = \sum_{j=1}^n g_j \frac{\partial}{\partial x_j}$$

$$\begin{aligned} XYh - YXh &= \sum_{i,j} f_i \frac{\partial}{\partial x_i} \left( g_j \frac{\partial}{\partial x_j} h \right) - g_j \frac{\partial}{\partial x_j} \left( f_i \frac{\partial}{\partial x_i} h \right) \\ &= \left( \sum_{i,j} f_i \frac{\partial g_j}{\partial x_i} \frac{\partial}{\partial x_j} - g_j \frac{\partial f_i}{\partial x_j} \frac{\partial}{\partial x_i} \right) h \end{aligned}$$

Propn  $F: M \rightarrow N$  a diffeomorphisms  $\Rightarrow F[x, y] = [Fx, FY]$

$$\begin{aligned}
 \underline{\text{Proof}} \quad \text{For } g \in C^\infty(N), \quad [Fx, FY]_g &= (Fx)(FY)g - (FY)(Fx)g \\
 &= Fx(Y(g \circ F) \circ F^{-1}) - FY(x \circ (g \circ F) \circ F^{-1}) \\
 &= x(Y(g \circ F) \circ F^{-1}) - Y(x \circ (g \circ F) \circ F^{-1} \circ F) \circ F^{-1} \\
 &= XY(g \circ F) \circ F^{-1} - YX(g \circ F) \circ F^{-1} \\
 &= [x, y] (g \circ F) \circ F^{-1} \\
 &= F[x, y]_g
 \end{aligned}$$

(x)

Lemma As a GP,  $FY(g) = Y(g \circ F) \circ F^{-1}$ .

$$\begin{aligned}
 \underline{\text{PF}} \quad (FY)(g)(F(p)) &= FY(F(p))_g \\
 &\equiv F_* Y(p)_g \\
 &= Y(p)(g \circ F) \\
 &= Y(g \circ F)(p) \\
 &= Y(g \circ F)(F^{-1}(F(p)))
 \end{aligned}$$

Defn A Lie algebra is a real vector space equipped w/ a bilinear operation  $x, y \mapsto [x, y]$  satisfying

$$\textcircled{1} \text{ Antisymmetry } [x, y] = -[y, x]$$

$$\textcircled{2} \text{ Jacobi identity } [[x, y], z] + [[y, z], x] + [[z, x], y] = 0$$

Lie algebras are not algebras.

Example 0 Any vector space w/  $[v_1, v_2] = 0$ .

Example 1 Any algebra w/  $[x, y] = xy - yx$ .

$[[x, y], z] + [[y, z]]x + [[z, x]]y = 0$  after writing out twelve cancelling terms

Example 2  $VF(M)$  on any smooth  $M$ . The Jacobi identity follows from the fact that  $XYF$  is a sensible term even if  $XY$  isn't.

Example 3 Any subspace of a Lie algebra closed under the Lie bracket.

$$\{A \in M_n(\mathbb{R}) : \text{tr}(A) = 0\} \quad \text{tr}(AB - BA) = \text{tr}(AB) - \text{tr}(BA) = 0.$$

Example 4  $G$  a Lie group,  $L_g : G \rightarrow G$ , say  $x \in VF(G)$  is left-invariant  
 $h \mapsto gh$

If  $\forall g \in G$ ,  $L_g x = x$ . Let  $\text{Lie}(G) := \{ \text{left-inv vector fields on } G \}$ .

Propn  $\text{Lie}(G)$  is closed under  $[\cdot, \cdot]$

$$\begin{aligned} \text{PF} \quad L_g [x, y] &= [L_g x, L_g y] \\ &= [x, y] \end{aligned}$$

Example  $G = S^1$



Left invt vector field has same magnitude & orientation at each point.