

(Review of) Manifolds

①

So far we've talked about finite and in particular discrete groups. But this class is actually about groups w/ some topology & in particular the structure of a manifold.

Let M be a topological space.

Recall

Defn M is Hausdorff if $\forall x \neq y \in M, \exists$ open $U, V \subseteq M: x \in U, y \in V, U \cap V = \emptyset$.

Defn A set of open subsets $\{U_i \subseteq M: i \in I\}$ is a basis for M if every open $V \subseteq M$ is $V = \bigcup_{i \in J} U_i$ for some $J \subseteq I$.

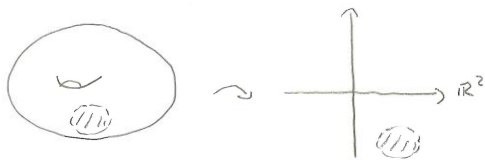
Defn A topological space is second-countable if it has a countable basis.

Ex $\{\prod_{i=1}^n (a_i, b_i): a_i < b_i, a_i \in \mathbb{Q}\}$ is a countable basis for \mathbb{R}^n

Ex Any uncountable set w/ the discrete topology is not second countable.

Defn An n -dim'l chart for an open set $V \subseteq M$ is a homeomorphism $\varphi: U \rightarrow V$ where $V \subseteq \mathbb{R}^n$ is open.

M



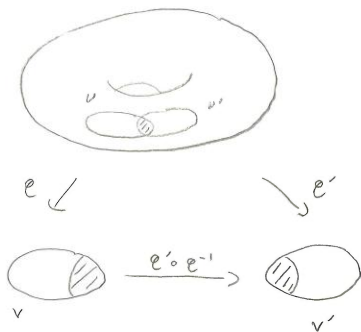
Defn M is locally Euclidean of dimension n if every point has a nbhd w/ an n dim'l chart.

(2)

Defn A topological manifold of dim n is a Hausdorff second-countable locally Euclidean topological space.

Example $U \subseteq \mathbb{R}^n$ open, $F: U \rightarrow \mathbb{R}^k$ cts \Rightarrow the graph $\Gamma(F)$ is defined to be $\{(x, F(x)) \in U \times \mathbb{R}^k : x \in U\}$ w/ a single chart given by projection.

Defn Two charts $e: U \rightarrow V$ and $e': U' \rightarrow V'$ are compatible if the overlap map $e' \circ e^{-1}: e(U) \rightarrow e'(U)$ is a smooth function.



Defn A (smooth) atlas $\mathcal{A} = \{(U_i, e_i) : i \in I\}$ for a topological manifold M consists of an open cover $M = \bigcup_{i \in I} U_i$ and charts $e_i: U_i \xrightarrow{\sim} V_i \subseteq \mathbb{R}^n$ which are pairwise compatible.

Defn An atlas \mathcal{A} is maximal if every chart compatible with all the charts in \mathcal{A} is in \mathcal{A} .

Exercise Every atlas is contained in a unique maximal atlas.

Defn A smooth structure on a topological mfd is a choice of maximal atlas. A smooth manifold is a topological mfd equipped w/ a smooth structure.

Example

- ① Countable set w/ the discrete topology
- ② \mathbb{R}^n : Maximal atlas: $\{ \varphi: U \subseteq \mathbb{R}^n \rightarrow V \subseteq \mathbb{R}^n : \text{smooth w/ smooth inverse} \}$
- ③ Any open $U \subseteq \mathbb{R}^n$
- ④ The graph of any smooth $F: U \rightarrow \mathbb{R}^k$ via projection onto the first factor
- ⑤ The n -sphere $S^n = \{ (x_0, \dots, x_n) \in \mathbb{R}^{n+1} : \sum x_i^2 = 1 \}$

charts $U_i^+ = \{ (x_0, \dots, x_n) \in S^n : x_i > 0 \}$ 2n+2 charts $\varphi_i^\pm: U_i^\pm \rightarrow \mathcal{B}_r(0) \subseteq \mathbb{R}^n$
 $U_i^- = \{ (x_0, \dots, x_n) \in S^n : x_i < 0 \}$ $(x_0, \dots, x_n) \mapsto (x_0, \dots, x_n)$

⑥ $\text{Mat}_{n,k}(\mathbb{R}) \cong \mathbb{R}^{nk}$

⑦ Products: For M smooth of dimension m and N smooth of dimension n , $M \times N$ is a smooth $m+n$ manifold.

eg $T^n = \underbrace{S^1 \times \dots \times S^1}_n$

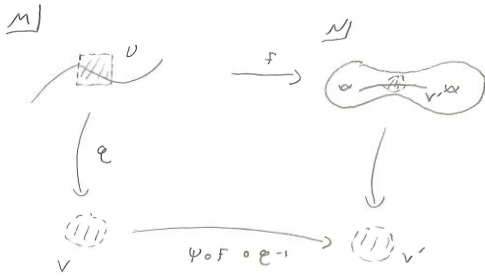
Smooth Functions M, N smooth manifolds of dim m, n respectively.

Defn $F: M \rightarrow N$ is smooth if \forall chart $\varphi: U \rightarrow V \subseteq \mathbb{R}^m$ on M , $\psi: U' \rightarrow V' \subseteq \mathbb{R}^n$ on N

$\psi \circ F \circ \varphi^{-1}$ is smooth where defined, i.e. smooth as a function

$\varphi(F^{-1}(U')) \rightarrow \mathbb{R}^m$

\mathbb{R}^m



Ex If $M = \mathbb{R}^m$, $N = \mathbb{R}^n$, then f smooth in this sense $\Leftrightarrow f$ is smooth in the usual sense.

Ex f is smooth $\Leftrightarrow \psi \circ f \circ e^{-1}$ is smooth for all e, ψ in a pair of atlases on M and N not necessarily maximal.

Ex Compositions of smooth maps are smooth.

Defn A diffeomorphism is a smooth homeomorphism w/ smooth inverse.

Example $\exp: \mathbb{R} \rightarrow \mathbb{R}_+$

Remark Diffeomorphism is an equivalence relation.

• All manifolds of $\dim n \leq 3$ have unique-up-to-diffeomorphism smooth

Thm (Milnor, 1957) \exists exactly 28 equivalence classes of smooth structure on S^7 .

Thm (Donaldson & Taubes, 1970) \exists uncountably many equivalence classes of smooth structure on \mathbb{R}^4 .

Thm (Kervaire, 1960, later Donaldson) \exists nonsmoothable manifolds.

Derivations & tangent spaces

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M a smooth mfd, $p \in M$

Defn $C^\infty(M) = \{ \text{smooth fns } f: M \rightarrow \mathbb{R} \}$. This is an \mathbb{R} -algebra.

Defn A derivation at p is a linear map $V: C^\infty(M) \rightarrow \mathbb{R}$ st

$$V(fg) = V(f)g(p) + f(p)V(g).$$

Ex $M = \mathbb{R}^n$, $V(f) = \frac{\partial f}{\partial x_i} \Big|_p$

Ex Directional derivatives along a parametric curve γ ,

$$\gamma: (-\epsilon, \epsilon) \rightarrow M \text{ smooth}$$

$$\gamma(0) = p$$

$$V(f) = (f \circ \gamma)'(0)$$

Defn The tangent space $T_p M$ to M at p is the vector space of all derivations at p .

Propn Any derivation may be expressed as a directional derivative.

Corollary Since $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}$ is a basis for $T_p \mathbb{R}^n$, $T_p M$ is n -dimensional.

Defn If $\varphi: M \rightarrow N$ is smooth, then the push-forward or derivative at $p \in M$ is the linear map

$$\varphi_* = \varphi_p: T_p M \rightarrow T_{\varphi(p)} N$$

given by $\varphi_* V(f) = V(f \circ \varphi)$.

Exercise This is a derivation.

Exercises (a) There is a chain rule: $M \xrightarrow{\psi} N \xrightarrow{e} P$ has

$$(\psi \circ \psi)_* = e_* \circ \psi_* \quad \text{i.e.} \quad D_P(\psi \circ \psi) = D_{\psi(P)}(e) \circ D_P \psi$$

(b) e a diffeomorphism $\Rightarrow e_*$ is an isomorphism and

$$(e_*)^{-1} = (e^{-1})_*$$

Example $e: \mathbb{R}^m \rightarrow \mathbb{R}^n$, Then $e(x) = (e_1(x), \dots, e_n(x))$

$$V = \frac{\partial}{\partial x_j} \quad f(\vec{y}) = y_i \quad (e_* V)(f) = \frac{\partial}{\partial x_i} (y_i \circ e)_P = \frac{\partial e_i}{\partial x_j} \Big|_P$$

So in terms of the bases $\left\{ \frac{\partial}{\partial x_i} \right\}$ and $\left\{ \frac{\partial}{\partial y_i} \right\}$, the matrix of e_* is given by the Jacobian.

After choosing a chart, $T_P M \cong T_{e(P)} \mathbb{R}^n \cong \mathbb{R}^n$ noncanonically. Ergo the rank of the derivative at P is well-defined.

Submersions, immersions, and embeddings

$f: M \rightarrow N$ smooth

Defn f is a submersion if its derivative is surjective for all $x \in M$ and an immersion if it is injective.

eg $\mathbb{R}^k \times \mathbb{S}^1 \hookrightarrow \mathbb{R}^m$ immersion

$\mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}^m$ submersion

More generally $M \times N \xrightarrow{\pi} M$ submersion

$$D_{(P,Q)}(\pi) : T_{(P,Q)}(M \times N) \rightarrow T_P M$$

$$\cong T_P M \times T_Q N$$

Ergo parametric curves and surfaces in \mathbb{R}^3 are immersed

$$\bullet (x(t), y(t), z(t)) : \forall t \in (a, b), (x'(t), y'(t), z'(t)) \neq (0, 0, 0)$$

$$\parallel$$

$$e_* \left(\frac{d}{dt} \right)$$

$$\bullet S: (a, b) \times (c, d) \rightarrow \mathbb{R}^3 \quad 0 \neq \vec{n} = \frac{ds}{du} \times \frac{ds}{dv} \Leftrightarrow \frac{ds}{du} = S_* \frac{d}{du} \quad \frac{ds}{dv} = S_* \frac{d}{dv} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{lin indep}$$

IF $F: M \rightarrow N, F_* = D_p F$ is injective/surjective \Leftrightarrow $\begin{array}{c} \swarrow \text{charts} \\ (\psi \circ F \circ \varphi^{-1})_* \\ \parallel \\ \psi_* \circ F_* \circ \varphi_*^{-1} \\ \swarrow \uparrow \text{Iso} \end{array}$ is injective/surjective.

So one can check immersion/submersion on charts.

Embedding

Defn An injective immersion $F: M \rightarrow N$ is an embedding if it is also a homeomorphism onto its image.


eg Inclusion $\mathbb{R}^k \times \{0\} \hookrightarrow \mathbb{R}^n$

- ① Inclusion of an open $V \subseteq M$
- ② Graph of a smooth $F \in \mathcal{F}_n$.

Counterexamples

①  $\subseteq \mathbb{R}^2$

(Immersion but not embedding)

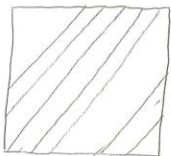
②  $\subseteq \mathbb{R}^2$ Not a homeomorphism onto its image

③ Line of irrational slope on a torus

⑤

$$S^1 = \{z \in \mathbb{C} : |z| = 1\} \quad \alpha \in \mathbb{R} \setminus \mathbb{Q} \quad F: \mathbb{R} \rightarrow T = S^1 \times S^1$$

$$t \mapsto (e^{it}, e^{i\alpha t})$$



Exercise F is smooth but the subspace topology on this line is not the subspace topology on the reals.

Inverse function theorem

Thm For any $p \in U$ open in \mathbb{R}^n , $F: U \rightarrow \mathbb{R}^n$ smooth, $D_p F$ is an isomorphism \Leftrightarrow an inverse to F exists near p , i.e. \exists a neighborhood $V \ni p : F(V)$ open, $F|_V : V \rightarrow F(V)$ has a smooth inverse.

Corollary $F: U \rightarrow \mathbb{R}^m$ smooth st $D_p F$ injective, then F is an embedding

\mathbb{R}^m
 \mathbb{R}^n

near p , i.e. \exists a nbhd $V \ni p$ st $F|_V$ is an embedding.

$(V) \rightarrow \mathbb{R}^m$] restriction to V is an embedding.

PF Let $u_1, \dots, u_{m-n} \in \mathbb{R}^m$ be a basis for $(\text{im } D_p F)^\perp$ and define

$\tilde{F}: U \times \mathbb{R}^{m-n} \rightarrow \mathbb{R}^m$ by $\tilde{F}(x, y) = F(x) + \sum y_i u_i$. Then $\text{im } D_{(p,0)} \tilde{F} = \text{im } D_p F + (\text{im } D_p F)^\perp = \mathbb{R}^m$

Then $D_{(p,0)} \tilde{F}$ is an isomorphism. We apply the inverse function theorem

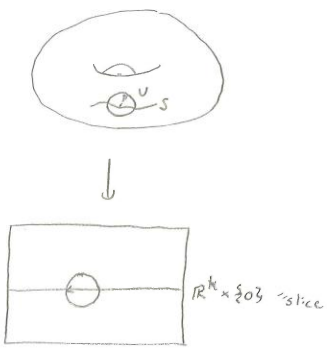
to \tilde{F} to get an inverse for \tilde{F} near $(p, 0)$. Ergo $F|_{V \times \{0\}} = \tilde{F}|_{V \times \{0\}}$

has injective derivative and is a homeomorphism onto its image. Hence

$F|_{V \times \{0\}}$ is an embedding.

Defn A regular submfld of M of dimension k is a subset $S \subseteq M$ st every $p \in S$ has an "adapted chart"; $\varphi: U \rightarrow V$ and st $\varphi(p) = 0$ and $\varphi(U \cap S) = (\mathbb{R}^k \times \{0\}) \cap V$.

Note Restricting adapted charts to S furnishes an atlas making S a smooth mfd of dim k .



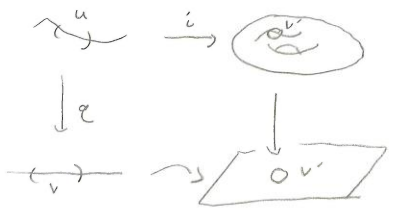
Thm $S \subseteq M$ regular submflds are precisely the subsets of M which are images of embeddings.

\Rightarrow Regular submanifolds are embedded via the inclusion map

\Leftarrow Suppose $i: S \rightarrow M$ is an embedding and $\varphi: U \rightarrow V$ be a chart near $p \in S$.

Let $\psi: U' \rightarrow V'$ be a chart near $i(p)$. We can choose the charts so

that $i(S) \cap U' = i(U)$ by shrinking if necessary. Then $F := \psi \circ i \circ \varphi^{-1}: V \rightarrow V'$ has injective derivative at $\varphi(p)$.



Let u_1, \dots, u_{n-k} be a basis for $(\text{im } D_{\varphi(p)} F)^\perp$ and let

$$\hat{F}: V \times \mathbb{R}^{n-k} \rightarrow V'$$

$$(\vec{x}, \vec{y}) = F\vec{x} + \sum_{i=1}^{n-k} y_i u_i$$

The inverse function theorem implies that \tilde{F} is a local diffeomorphism. (10)

$$\begin{array}{ccc} (\mathcal{E}(p), 0) \in W & \longrightarrow & W' \\ \uparrow & & \uparrow \\ V \times \mathbb{R}^{n-k} & & V' \end{array}$$

Then $\tilde{f} \circ \psi$ provides an adapted chart near $i(p)$. This is a diffeomorphism onto its image. If $\pi: W \rightarrow V$ is the projection on the first factor, then the inverse to $i: S \rightarrow i(S)$ is given on charts by $\mathcal{E}^{-1} \circ \pi \circ \tilde{F}^{-1} \circ \psi$, hence smooth, so $i: S \rightarrow i(S)$ is a diffeomorphism.

Propn $F: M \rightarrow N$ smooth, $S \subseteq N$ regular submfld consisting entirely of regular values of F , i.e. $D_x F: T_x M \rightarrow T_x N$ surjective $\forall x \in M$ w/ $F(x) \in S$. Then $F^{-1}(S) \subseteq M$ is a regular submfld w/ $\dim F^{-1}(S) = \dim(M) - \dim(N) + \dim(S)$.

PF For $y \in S$, let $\psi: U \rightarrow V$ be an adapted chart, $\psi(y) = \vec{0}$.

For $x \in F^{-1}(y)$, let $\mathcal{E}: U' \rightarrow V'$ be a chart

