

Root Systems - The General Case

Recall  $G$  a compact connected Lie group,  $T$  a maximal torus,  $\dim(T) = r$ .  
 If  $\mathfrak{g} = \mathfrak{t} \oplus \mathfrak{p}$ , a root of  $G$  with respect to  $T$  is a nonzero weight of the adjoint representation (i.e., a character in the decomposition of  $\mathfrak{p}$  into  $\mathfrak{t}$ -invariant one-dim'l  $\mathfrak{t}$ -subspaces w/ the adjoint representation).

Example  $G = SU(2)$

$$\mathfrak{g} = \left\langle \begin{matrix} \mathfrak{h}_\alpha \\ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \underbrace{\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}}_{\mathfrak{p}} \right\rangle$$

$\uparrow$  spans  $\mathfrak{t}$                       spans  $\mathfrak{p}$

$$\text{Ad} \begin{pmatrix} t & 0 \\ 0 & t^{-1} \end{pmatrix} X_\alpha = t^2 X_\alpha$$

$\Rightarrow X_\alpha$  spans a  $\mathfrak{t}$ -inv't vector space corresponding to the character  $\lambda_2$



General Case

Propn Let  $G, T$  as above. Let  $H$  be a maximal abelian subgroup of  $G$ .  $\mathfrak{h}$  of  $\mathfrak{g}$  is the Lie algebra of a conjugate of  $T$ . Its dimension is the rank  $r$  of  $G$ .

PF Recall that  $\exp(\mathfrak{h})$  is commutative (elements w/ zero bracket exponentiate to commuting elements), and connected since it is the image of a connected space. Its closure is a closed abelian subgroup of  $G$ , hence a Lie subgroup, hence a torus  $H'$ . By maximality of  $H$  it must actually be a maximal torus. And

then by Cartan's thm  $H$  and  $T$  are conjugate.

Lemma Suppose  $G$  is a compact Lie group w/ Lie algebra  $\mathfrak{g}$ ,  $\rho: G \rightarrow GL(V)$  a representation, and  $d\rho: \mathfrak{g} \rightarrow \text{End}(V)$  the differential. IF  $v \in V$  and  $x \in \mathfrak{g}$  st  $d\rho(x)^n v = 0$  for any  $n > 1$ , then  $d\rho(x)v = 0$ .

PF We put a  $G$ -inv positive definite inner product  $\langle, \rangle$  on  $V$ . The inner product is then  $\mathfrak{g}$ -inv, which means  $\langle d\rho(x)v, w \rangle = -\langle v, d\rho(x)w \rangle$ .

Ergo  $d\rho(x)$  is skew-Hermitian  $\Rightarrow$  by the spectral theorem,  $V$  has a basis with respect to which the matrix of  $d\rho(x)$  is diagonal. But for a diagonal matrix,  $Mv = 0 \Rightarrow Mv = 0$ .

Let  $(\rho, V)$  be any finite dim'd cpx representation of  $G$ . IF  $\lambda \in \mathfrak{X}^*(T)$ , let  $V(\lambda) = \{v \in V : \rho(t)v = \lambda(t)v\}$ , so that  $V = \bigoplus_{\lambda} V(\lambda)$ . Note that in the event that  $(\rho, V) = (\text{Ad}, \mathfrak{g}_{\mathbb{C}})$  and  $\lambda = \alpha$  is a root,  $V(\lambda) = \mathfrak{X}_{\alpha}$ .

Propn Let  $(\rho, V)$  be an irrep of  $G$ , and let  $\alpha$  be a root.

(i) IF  $d\rho: \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  is the differential of  $\rho$ , then  $d\rho(H)v = d\lambda(H)v$  for all  $H \in \mathfrak{t}$  and  $v \in V(\lambda)$ .

(ii) We have  $[H, X_{\alpha}] = \text{ad}(H)X_{\alpha} = d\alpha(H)X_{\alpha}$  for  $H \in \mathfrak{t}$ ,  $X_{\alpha} \in \mathfrak{X}_{\alpha}$ .

(iii) IF  $(\rho, V)$  is a finite-dim'd cpx representation of  $G$  and  $v \in V(\lambda)$  for some  $\lambda \in \mathfrak{X}^*(T)$ , then  $d\rho(X_{\alpha})v \in V(\lambda + \alpha)$

PF For part (i), let  $t \in \mathbb{R}$  and  $t \in \mathbb{R}$ . Then for any  $v \in V(\mathfrak{g})$ , we see

that  $\exp(tH)$  lies in  $T$ , so by definition of  $V(\mathfrak{g})$ , we see that

$$\rho(\exp(tH))v = \lambda(\exp(tH))v. \text{ So on } V(\mathfrak{g}), \rho(\exp(tH)) = \lambda(\exp(tH)) \Rightarrow$$

$$\left. \frac{d}{dt} (\rho(\exp(tH))) \right|_{t=0} = \left. \frac{d}{dt} (\lambda(\exp(tH))) \right|_{t=0} \text{ on } V(\mathfrak{g}) \Rightarrow d\rho(H)v = d\lambda(H)v \text{ for } v \in V(\mathfrak{g}).$$

Since the differential of  $\text{Ad}$  is  $\text{ad}$ , part (ii) is then a special case of part (i) in the case that  $\rho = \text{Ad}$ ,  $d\rho(H)(x_\alpha) = \text{ad}(H)x_\alpha = [H, x_\alpha]$ , and  $\lambda = \alpha$ .

For part (iii), we see that part (ii) implies that

$$d\rho(H) d\rho(x_\alpha) - d\rho(x_\alpha) d\rho(H) = d\rho[H, x_\alpha] \cdot d\rho(d\alpha(H) \cdot x_\alpha) = d\alpha(H) \cdot d\rho(x_\alpha)$$

↖ Always true ↗
↖ (ii) ↗
↖ This is a complex number ↗

Now apply this to  $v$ . Let  $w = d\rho(x_\alpha)v$ .

$$d\rho(H) d\rho(x_\alpha)v = d\rho(x_\alpha) d\rho(H)v + d\alpha(H) \cdot d\rho(x_\alpha)v$$

↖ (i) ↗

$$d\rho(H)w = d\rho(x_\alpha) d\lambda(H)(v) + d\alpha(H)w$$

$$d\rho(H)w = d\lambda(H) d\rho(x_\alpha)v + d\alpha(H)w$$

$$d\rho(H)w = (d\lambda(H) + d\alpha(H))(w)$$

$$\Rightarrow w \in V(\lambda + \alpha).$$

With this in mind we can study the spaces  $\mathfrak{E}_\alpha$  for the adjoint representation a little more carefully.

Notation Write  $\mathfrak{g}_{\mathbb{C}} = \mathfrak{g} \oplus i\mathfrak{g}$ . Let  $c: \mathfrak{g}_{\mathbb{C}} \rightarrow \mathfrak{g}_{\mathbb{C}}$  be the conjugation map, which is an automorphism of  $\mathfrak{g}_{\mathbb{C}}$  as a real Lie algebra (although not a complex-linear automorphism). Note that  $c(a\bar{z}) = \bar{a}c(z)$ . Now let  $G$  cpt,  $T$  a maximal torus, weight spaces as previously.

Propn (i)  $c(\mathfrak{X}_{\alpha}) = \mathfrak{X}_{-\alpha}$ .

(ii) IF  $x_{\alpha} \in \mathfrak{X}_{\alpha}$  and  $x_{\beta} \in \mathfrak{X}_{\beta}$ , and  $\alpha, \beta \in \Phi$ , then

$$[x_{\alpha}, x_{\beta}] \in \begin{cases} \mathfrak{t}_{\mathbb{C}} & \text{if } \beta = -\alpha \\ \mathfrak{X}_{\alpha+\beta} & \text{if } \alpha+\beta \in \Phi \end{cases}$$

while  $[x_{\alpha}, x_{\beta}] = 0$  if  $\beta \neq -\alpha$  and  $\alpha+\beta \notin \Phi$ .

(iii) IF  $0 \neq x_{\alpha} \in \mathfrak{X}_{\alpha}$ , then  $[x_{\alpha}, c(x_{\alpha})]$  is a nonzero element of  $\mathfrak{t}$ , and  $d_{\alpha}([x_{\alpha}, c(x_{\alpha})]) \neq 0$ .

In case (ii) if  $\alpha+\beta \in \Phi$ , we will eventually show that  $[x_{\alpha}, x_{\beta}]$  is a nonzero element of  $\mathfrak{X}_{\alpha+\beta}$ .

PF For part (i), recall that for  $H \in \mathfrak{t}$ ,  $d_{\alpha}(H)$  takes purely imaginary values. Then since we have that

$$[H, x_{\alpha}] = d_{\alpha}(H)x_{\alpha}$$

applying  $c$  we obtain

$$[H, c(x_{\alpha})] = [c(H), c(x_{\alpha})] = c([H, x_{\alpha}]) = c(d_{\alpha}(H)x_{\alpha}) = -d_{\alpha}(H)c(x_{\alpha})$$

$\Rightarrow c(x_{\alpha}) \in \mathfrak{X}_{-\alpha}$ .

Part (i) is a special case of the last part of the preceding

proposition: IF  $v \in V(\lambda)$ , then  $d_p(x_\alpha)v_{-1} \in V(\lambda + \alpha)$ . In this case

$$p = \text{Ad}, d_p = \text{ad}, \text{ so } [x_\alpha, x_\alpha] \in \begin{cases} \mathfrak{g}_0 = V(0) & \text{if } \beta = -\alpha \\ \mathfrak{g}_{\alpha+\beta} = V(\alpha+\beta) & \text{if } \alpha+\beta \in \Phi \end{cases}$$

IF  $\alpha+\beta \neq 0$  and not in  $\Phi$ ,  $V(\alpha+\beta) = \{0\}$  and we conclude that  $\text{ad}(x_\alpha)x_\beta = [x_\alpha, x_\beta] = 0$  as well.

Now for part (ii). Parts (i) and (ii) imply that  $[x_\alpha, c(x_\alpha)] \in \mathfrak{g}_0$ . <sup>Lies in  $\mathfrak{g}_{-\alpha}$</sup>  Now apply  $c$  to this element to obtain

$$c([x_\alpha, c(x_\alpha)]) = [c(x_\alpha), x_\alpha] = -[x_\alpha, c(x_\alpha)],$$

so  $[x_\alpha, c(x_\alpha)] \in \mathfrak{g}_0$ . We claim that  $[x_\alpha, c(x_\alpha)] \neq 0$ . Let  $\mathfrak{h}_\alpha$  be the kernel of  $d_\alpha$ , which is of course a subspace of codim 1. Let  $H_1, \dots, H_{r-1}$  be a basis thereof. IF  $[x_\alpha, c(x_\alpha)] = 0$ , then if we let

$$Y_\alpha = \frac{1}{2}(x_\alpha + c(x_\alpha)) \text{ and } Z_\alpha = \frac{1}{2i}(x_\alpha - c(x_\alpha))$$

then  $Y_\alpha$  and  $Z_\alpha$  are  $c$ -invt and therefore both lie in  $\mathfrak{g}$ , so we see that  $H_1, \dots, H_{r-1}, Y_\alpha, Z_\alpha$  are  $r+1$  commuting elements in  $\mathfrak{g}$  which are linearly independent over  $\mathbb{R}$ :  $Y_\alpha$  and  $Z_\alpha$  commute w/ each other, and  $[H_i, x_\alpha] = d_\alpha(H_i)x_\alpha = 0$ , likewise

$[H_i, c(x_\alpha)] = d(-\alpha)(H_i)(c(x_\alpha)) = 0$  since the  $H_i$  are also a basis for  $\ker(d(-\alpha))$ . But this is a contradiction; there is no abelian subalgebra of  $\mathfrak{g}$  w/ dim  $r+1$ . Ergo  $[x_\alpha, c(x_\alpha)] \neq 0$ .

We would furthermore like to show that  $d\alpha([X_\alpha, c(X_\alpha)]) \neq 0$ . ⑥

Suppose for the sake of contradiction that it vanishes. Then

if  $H_0 = -i[X_\alpha, c(X_\alpha)] \in \mathfrak{t}$ , we have

$$[H_0, X_\alpha] = d\alpha(H_0)X_\alpha = d\alpha(-i[X_\alpha, c(X_\alpha)])X_\alpha = 0$$

and likewise  $[H_0, c(X_\alpha)] = 0$ . Then w/  $Y_\alpha$  and  $Z_\alpha$  the same elements of  $\mathfrak{g}$  as previously, we have  $[H_0, Y_\alpha] = [H_0, Z_\alpha] = 0$ .

But a quick computation shows that  $[Y_\alpha, Z_\alpha] = \frac{1}{2}H_0$ .

So we have both  $[Y_\alpha, Z_\alpha] = \frac{1}{2}H_0$  and  $[Y_\alpha, H_0] = 0$ , so we

see that  $\text{ad}(Y_\alpha)^2 Z_\alpha = 0$  and  $\text{ad}(Y_\alpha)Z_\alpha \neq 0$ . But today's second lemma said that was impossible, so we are done.

We're now ready for our first geometric consequence!

Propn IF  $\dim(T) = 1$ , then either  $G = T$  or  $\dim(G) = 3$ . IF  $\alpha$  is any root,  $\mathfrak{X}_\alpha$  is one dimensional, and the only other root is  $-\alpha$ .

PF Since  $\mathfrak{e}_\alpha$  is a one-dimensional complex vector space, let  $H$  be a basis vector. First assume  $G \neq T$ , so that  $\mathfrak{F}$  is nonempty. Then the spaces  $\mathfrak{X}_\alpha$  are just eigenspaces of  $H$  on  $\mathfrak{p}_\alpha$ . Since  $T$  is one-dimensional, so is  $V = \mathbb{R} \oplus_{\mathbb{Z}} X^*(T)$ .

Ergo if  $\alpha \in \mathfrak{F}$ , every  $\beta \in \mathfrak{F}$  is of the form  $s\alpha$  for some nonzero constant  $s$ . Choose  $\alpha$  st all  $|s| \geq 1$  (i.e., choose the shortest root). Let  $0 \neq X_\alpha \in \mathfrak{X}_\alpha$ , and let  $X_{-\alpha} = -c(X_\alpha) \in \mathfrak{X}_{-\alpha}$ .



Consider the complex vector space

$$W = \mathbb{C}x_{-\alpha} \oplus \mathfrak{t}_{\mathbb{C}} \oplus \bigoplus_{\substack{s \in \mathbb{Z} \\ s > 0}} \mathfrak{X}_{s\alpha}$$

By the preceding proposition, each component is mapped into another by  $\text{ad}(x_{\alpha})$  and  $\text{ad}(x_{-\alpha})$ : For example,  $\text{ad}(x_{-\alpha})$  kills  $x_{-\alpha}$ , shifts  $\mathfrak{t}_{\mathbb{C}}$  to  $\mathbb{C}x_{-\alpha}$ , and shifts  $\mathfrak{X}_{\lambda\alpha}$  into  $\mathfrak{t}_{\mathbb{C}}$  if  $\lambda=1$  or  $\mathfrak{X}_{(\lambda-1)\alpha}$  if  $\lambda \neq 1$ , and  $\lambda-1 > 0$ , so this last term is in  $W$ . Moreover,

$$[x_{\alpha}, x_{-\alpha}] \in \mathfrak{t}_{\mathbb{C}} \Rightarrow [x_{\alpha}, x_{-\alpha}] \text{ is a nonzero linear multiple of } H.$$

But the commutator of two linear transformations on a finite-dimensional vector space has trace zero, so the trace of  $H$  on  $W$  is zero.

However, if  $C = \overbrace{\text{tr}(\text{ad}(H))}^{\text{complex number}}$ , the trace of  $\text{ad}(H)$  on  $\mathfrak{X}_{\lambda\alpha}$  is  $\lambda \cdot C \cdot \dim(\mathfrak{X}_{\lambda\alpha})$ , and the trace of  $\text{ad}(H)$  on  $\mathbb{C}x_{-\alpha}$  is  $-C$ , and the trace of  $\text{ad}(H)$  on  $\mathfrak{t}_{\mathbb{C}}$  is  $0$ . So the total trace of  $H$  on  $W$  is  $-C + \sum_{\lambda \geq 1} \lambda C \dim(\mathfrak{X}_{\lambda\alpha}) = 0$ . We see there is

exactly one  $\mathfrak{X}_{\lambda\alpha}$  w/  $\lambda > 0$ , namely  $\mathfrak{X}_{\alpha}$ , and  $\dim(x_{\alpha}) = 1$ . So

$$\mathfrak{g} = \mathbb{C}H \oplus \mathbb{C}x_{\alpha} \oplus \mathbb{C}x_{-\alpha} \text{ is 3-dimensional. } \square$$

Now we turn our attention to the general case. If  $\alpha \in \mathfrak{H}$ , let  $T_{\alpha} \subseteq T$  be the kernel of  $\alpha$ . This is a closed (not necessarily connected!) subgroup w/ Lie algebra  $\mathfrak{t}_{\alpha}$  the kernel of  $d\alpha$ .

Propn (i) If  $\alpha \in \Phi$ ,  $\dim(x_\alpha) = 1$

(ii) If  $\alpha, \beta \in \Phi$  and  $\alpha = \lambda\beta$ ,  $\lambda \in \mathbb{R}$ , then  $\lambda = \pm 1$ .

PF Let  $H = C_G(T_\alpha)$  be the centralizer of  $T_\alpha$ , in which  $T_\alpha$  is a normal subgroup. The Lie algebra of  $H$  is the centralizer  $\mathfrak{h}$  of  $t_\alpha$  in  $\mathfrak{g}$ , so  $\mathfrak{h}_\alpha = t_\alpha \oplus \bigoplus_{\substack{\lambda \in \Phi \\ \lambda \in \mathbb{R}}} \mathfrak{X}_{\lambda\alpha}$ . [Since certainly  $t_\alpha$  commutes w/ every element in  $t_\alpha$ , and  $[H, x_\alpha] = d_\alpha(H)x_\alpha = 0$  for  $H \in t_\alpha$ , similarly for  $[H, x_{-\alpha}]$ , but if  $[H, x_\beta] = d_\beta(H)x_\beta$  for all  $H \in t_\alpha$ , then  $d_\beta$  has the same kernel as  $d_\alpha \Rightarrow \beta$  is a scalar multiple of  $\alpha$ . Ergo the maximal torus of the group  $H/T_\alpha$  is  $T/T_\alpha$ , which is one-dimensional. By the preceding proposition, its complexified Lie algebra is three-dimensional. But  $\bigoplus \mathfrak{X}_{\lambda\alpha}$  is embedded injectively in this Lie algebra, so  $\lambda = \pm 1$  are the only values of  $\lambda$ , and the spaces  $\mathfrak{X}_{\pm\alpha}$  are one-dim.

Wednesday Proving that the roots always form a reduced root system.

Monday Classification of root systems 3 pictures (no proofs)