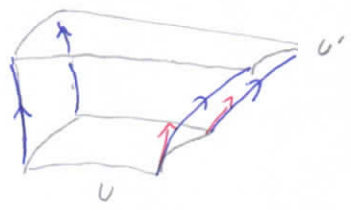


Lecture 23: Geodesics & Maximal Tori, C7d

Recall Let M be a Riemannian mfd of dimn n ; U a submfd of dimn $n-1$ which is homeomorphic to a disk. We choose a unit normal in a fixed direction near U . Geodesic coordinates near U are (t, x_2, \dots, x_n) such that $t \mapsto (t, x_2, \dots, x_n)$ is the geodesic through x in the direction of the unit normal.

Propn In geodesic coordinates, $g_{ii} = 0$ for $2 \leq i \leq n$ and $g_{11} = 1$.



Pf Recall that a geodesic should locally have

$$\frac{d^2 x_k}{dt^2} = -\{ij, k\} \frac{dx_i}{dt} \frac{dx_j}{dt} \cdot \text{In our case } \frac{dx_i}{dt} = 0 \text{ for } i \neq 1,$$

$$\text{so } \frac{d^2 x_k}{dt^2} = 0 \text{ for all } k. \text{ Ergo } 0 = -\{11, k\} \frac{dx_1}{dt} \frac{dx_1}{dt} = -\{11, k\},$$

So each $-\{11, k\} = 0$. Given that (g_{kl}) is invertible, we see that

$$[11, k] = 0 \text{ as well. So } \frac{1}{2} \left(\frac{\partial g_{1k}}{\partial x_1} + \frac{\partial g_{1k}}{\partial x_1} - \frac{\partial g_{11}}{\partial x_k} \right) = 0 \Rightarrow \frac{\partial g_{1k}}{\partial x_1} = \frac{1}{2} \frac{\partial g_{11}}{\partial x_k} \text{ for all } k.$$

IF we take $k=1$, $\frac{\partial g_{11}}{\partial x_1} = \frac{1}{2} \frac{\partial g_{11}}{\partial x_1} \Rightarrow \frac{\partial g_{11}}{\partial x_1} = 0$, so for fixed x_2, \dots, x_n , g_{11} is

a constant. When $x_1=0$, the initial condition of the geodesic through $(0, x_2, \dots, x_n)$ is that it is tangent to the unit normal to the surface, so in particular its tangent vector $\frac{\partial}{\partial x_1}$ at this point has length one. Ergo $g_{11} = 1$ when $x_1=0$, hence $g_{11} = 1$ throughout the geodesic coordinate

neighborhood. Now consider $2 \leq k \leq n$ and $\frac{\partial g_{1k}}{\partial x_1} = \frac{1}{2} \frac{\partial g_{11}}{\partial x_k} = 0$ since g_{11} is constant.

Now for $x_1=0$, by assumption $\frac{\partial}{\partial x_1}$ and $\frac{\partial}{\partial x_k}$ are orthogonal, so

g_{1k} vanishes when $x_1 = 0$, so it vanishes for all x_1 . \square

(2)

We can now check that short geodesics are paths of shortest length:

Propn ① Let $p: [0, 1] \rightarrow M$ be a geodesic. Then there exists an $\epsilon > 0$ st the restriction of p to $[0, \epsilon]$ is the unique path of shortest length from $p(0)$ to $p(\epsilon)$.

② Let $x \in M$. There exists a nbhd N of x st for all $y \in N$ there is a unique path of shortest distance from x to y , which is a geodesic.

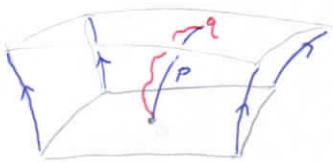
Pf We choose a hypersurface U orthogonal to p at $t=0$ and construct geodesic coordinates as previously. Choose ϵ and θ sufficiently small that the set N of points w/ coordinates $\{x_i \in [0, \epsilon], 0 \leq |x_2|, \dots, |x_n| \leq \theta\}$ is contained in the interior of the geodesic coordinate neighborhood.

We assume that the coordinates of $p(0)$ are $(0, \dots, 0)$, so that $p(t) = (t, 0, \dots, 0)$. Then $|p| = \epsilon$, where we let $|p|$ denote the length of the restriction of p to $[0, \epsilon]$.

Now we check that if $q: [0, \epsilon] \rightarrow M$ is any admissible path w/ $q(0) = p(0)$ and $q(\epsilon) = p(\epsilon)$, then $|q| \geq |p|$. First, suppose that $q([0, \epsilon])$ lies entirely within the neighborhood N and the x_1 -coordinate of $q(t)$ is monotonically increasing. Reparametrizing q , we can arrange that $q(t)$ and $p(t)$ have the same x_1 coordinate, namely t . We then write $q(t) = (t, x_2(t), \dots, x_n(t))$. Since $g_{1k} = g_{k1} = 0$

and $g_{11} = 1$, we see that

\downarrow



$$|q| = \int_0^\varepsilon \sqrt{\sum_{i,j} g_{ij} \frac{dx_i}{dt} \frac{dx_j}{dt}} dt$$

$$= \int_0^\varepsilon \sqrt{1 + \sum_{2 \leq i,j \leq n} g_{ij} \frac{dx_i}{dt} \frac{dx_j}{dt}} dt$$

Since (g_{ij}) is positive definite, its minor $(g_{ij})_{2 \leq i,j \leq n}$ is also positive definite, so in particular $\sum_{2 \leq i,j \leq n} g_{ij} \frac{dx_i}{dt} \frac{dx_j}{dt} \geq 0$, implying that $|q| \geq \int_0^\varepsilon \sqrt{1} dt = \varepsilon = |p|$.

Exercise Extend this argument to paths which have nonmonotonic first coordinate, or which are long enough to go outside of the neighborhood N .

For part (ii), given a unit tangent vector $X \in T_x M$, there is a unique geodesic $p_x: [0, \varepsilon_x] \rightarrow M$ through x which is tangent to X , w/ $\varepsilon_x > 0$ chosen small enough that this is a path of shortest length.

Indeed, we can choose ε_x small enough that it also works for nearby unit tangent vectors Y . (To see this, pick a local diffeomorphism of M moving x to Y ; regard X as fixed while the metric varies; this produces small variations of the g_{ij} , and the ε in part (i) can be used to work for sufficiently small variation of the g_{ij}).

So for each unit vector $X \in T_x M$ there is an $\varepsilon_x > 0$ and a nbhd N_x of x in the unit ball of $T_x M$ st $p_Y: [0, \varepsilon_x] \rightarrow M$ is a path of shortest length for all $Y \in N_x$. Since the unit ball in $T_x M$ is compact, it can be covered by finitely many of the nbhds N_x . Letting ε be the minimum of the corresponding ε_x , we can take N to be the set of points connected to x by a geodesic of length $< \varepsilon$.

If M is a connected Riemannian mfd, we make M into a metric space by defining $d(x,y)$ to be the infimum of $|p|$, where p is a path from x to y .

Thm Let M be a cpt connected Riemannian mfd, and let x and y be points of M . Then there is a geodesic $p: [0,1] \rightarrow M$ w/ $p(0) = x$ and $p(1) = y$.

Remark The condition in the theorem is stronger than it needs to be; this is true for manifolds that are geodesically complete, i.e. any well-paced geodesic can be extended to $(-\infty, \infty)$.

PF Let $\{p_i\}$ be a sequence of well-paced paths from x to y st $|p_i| \rightarrow d(x,y)$. Because they are well-paced, if $0 \leq a < b \leq 1$ we have that $d(p_i(a), p_i(b)) = (b-a)|p_i|$, and it follows that the $\{p_i\}$ are equicontinuous. Hence there is a subsequence that converges uniformly to a path p . This is clearly cts (it's not immediately obvious that it's smooth). But on each sufficiently short interval $0 \leq a < b \leq 1$, $p(b)$ is near enough to $p(a)$ that the unique path of shortest length between them is a geodesic. It follows that p itself is a geodesic.

Now we can consider applications to Lie groups.

Thm Let G be a cpt Lie group. There is a Riemannian metric on G which is invariant under left and right translation. In this metric, any geodesic is a (right or left) translate of a path $t \mapsto \exp(tX)$ for some $X \in \mathfrak{g}$.

PF Since G is a compact group acting by Ad on the real vector space \mathfrak{g} , there is an $\text{Ad}(G)$ inner product on \mathfrak{g} . This gives us an inner product on $T_e G$, which we transfer to $T_g G$ by the left-translation map. Right-translation in principle induces a different isomorphism $T_e G \xrightarrow{R_g} T_g G$, but these two maps differ by the derivative of conjugation, namely $\text{Ad}(g): \mathfrak{g} \rightarrow \mathfrak{g}$, so since our inner product is invariant under $\text{Ad}(g)$, the Riemannian metric thusly defined is invariant under both left and right translation.

To show that any geodesic is a translate of the exponential map, it suffices to check that any short segment of a geodesic is of the form $t \mapsto g \cdot \exp(tX)$, but the metric is translation-invariant, so this just asks us to check that geodesics near the identity are of the form $t \mapsto \exp(tX)$.

Case I $G \cong \mathbb{R}^n / \mathbb{Z}^n$ is a torus, and $T_e G \cong \mathbb{R}^n$ can be assumed to have the standard inner product. Then geodesics are just quotients of straight lines in \mathbb{R}^n and therefore translates of the exponential map.

Case II For general G , let $x \in \mathfrak{g}$ and $E_x: (-\epsilon, \epsilon) \rightarrow G$ be the geodesic through the origin tangent to $x \in \mathfrak{g}$. For $g \in \mathbb{R}$, $t \mapsto E_x(g \cdot t)$ is the geodesic through the origin tangent to gX , so that $E_x(gt) = E_{gX}(t)$. So there is a neighborhood U of the origin in \mathfrak{g} and a map $E: U \rightarrow G$ st $E_x(t) = E(tX)$ for $X, tX \in U$. Wts this is the same as the exponential map.

Given $g \in G$, then translating $E(tX)$ on the left by g and the right by g^{-1} gives another geodesic, which is conjugate to $\text{Ad}(g)X$.

Thus if $tX \in U$, $gE(tX)g^{-1} = E(t\text{Ad}(g)X)$. For fixed $X \in \mathfrak{g}$, let T be a maximal torus containing the one-parameter subgroup $\{\exp(tX) : t \in \mathbb{R}\}$.

Then $E(tX)$ commutes w/ $g \in T$ when $tX \in U$. Ergo the path $t \mapsto E(tX)$ runs through the centralizer $C(T)$ and therefore through $N(T)$.

Recalling that the closed component of $N(T)$ containing the identity is T , we see that $E(tX)$ lies in T . But the geodesics in T are exactly the paths $\exp(tX)$. \square

Thm Let G be a cpt ctd Lie group, and \mathfrak{g} its Lie algebra. Then the exponential map $\mathfrak{g} \rightarrow G$ is surjective.

PF Put a translation-invt Riemannian structure on G . Then given $g \in G$, there is a geodesic path from the identity to g . But this path is of the form $t \mapsto \exp(tX)$.

Thm Let G be a cpt ctd Lie group and T a maximal torus. There exists $k \in G$ st $g \in kTk^{-1}$.

PF Let \mathfrak{g} and \mathfrak{t} be the Lie algebras of G and T , resp. to be a generator of T . Let $X \in \mathfrak{g}$ and $H_0 \in \mathfrak{t}$ be such that $\exp(tX) = g$ and $\exp(tH_0) = e$, which is possible since \exp is surjective.

Since G is a compact group acting by Ad on \mathfrak{g} , there is a (G) -invt inner product \langle, \rangle on \mathfrak{g} . Choose $k \in G$ so that the real value $\langle X, \text{Ad}(k)H_0 \rangle$ is maximal. (This maximum is achieved, by compactness of G .) Let $H = \text{Ad}(k)H_0$. Then

$\exp(H) = ktk^{-1}$ is a generator for kTk^{-1} . (7)

IF $Y \in \mathfrak{g}$ is arbitrary, then $\langle X, \text{Ad}(e^{tY})H \rangle \Big|_{t=0} = \langle X, \text{ad}(Y)H \rangle = \langle X, [Y, H] \rangle = -\langle X, [H, Y] \rangle$

Since the bilinear form is invariant under Ad , it is also under ad , meaning that $0 = \langle X, [H, Y] \rangle + \langle [H, X], Y \rangle$. So $\langle [H, X], Y \rangle = 0$ for all $Y \in \mathfrak{g}$. $\Rightarrow [H, X] = 0$. Therefore $\exp(H)$ commutes w/ $\exp(tX)$ for all $t \in \mathbb{R}$.

Since $\exp(H)$ generates kTk^{-1} , the one-parameter subgroup $\exp(tX)$ is contained in the centralizer of kTk^{-1} . But kTk^{-1} is in fact a maximal torus, so it follows that $\{\exp(tX)\} \subseteq kTk^{-1}$. In particular, $g = \exp(X) \in kTk^{-1}$. \square

Thm (Cartan) Let G be a compact connected Lie group and T be a maximal torus. Then every maximal torus is conjugate to T , and every element of G is contained in a conjugate of T .

PF The second statement is implied by the previous one. For the first statement, let T' be another maximal torus and X a generator. Then X is contained in kTk^{-1} for some k , so $X \in kTk^{-1}$. As both are maximal tori, they are equal.

Propn Let G be a cpt connected Lie group, $S \subseteq G$ a torus (not necessarily maximal), and $g \in G \setminus S$ an element of its centralizer. Let H be the closure of the group generated by S and g . Then H has a topological generator; that is, there exists $h \in H$ st the subgroup generated by h is dense in H .

PF Since H is closed and abelian, its connected cpt H° containing the identity is a torus. Let h_0 be a generator of the torus. Now H/H° is compact and discrete, hence finite. Since $S \subseteq H^\circ$ and S and g together generate a dense subgroup of H , the finite group H/H° is cyclic, generated by gH° . Let r be the order of this group, so $g^r \in H^\circ$. Since the r th power map $H^\circ \rightarrow H^\circ$ is surjective, $\exists u \in H^\circ$ so $(gu)^r = h_0$. Then the group generated by $h = ug$ contains h_0 and a generator $gH^\circ = (gu)H^\circ$ of H/H° . So h is a topological generator of H . \square

Propn IF G is a Lie group and $u \in G$, then the centralizer $C_G(u)$ is a closed Lie subgroup, and its Lie algebra is $\{x \in \text{Lie}(G) : \text{Ad}(u)x = x\}$.

PF To show $H = C_G(u)$ is a closed submfd of G , it suffices to show its intersection w/ a small nbhd of the identity is a closed submfd. In a nbhd N of the origin in $\text{Lie}(G)$, the exponential map is a diffeomorphism onto $\exp(N)$, and we see that the preimage of $C_G(u)$ in N is a vector subspace by recalling that conjugation by u corresponds to the linear map $\text{Ad}(u)$ of N . In particular $u \exp(tx) u^{-1} = \exp(t \text{Ad}(u)x)$, so $\exp(tx) \in C_G(u)$ for all $t \Leftrightarrow \text{Ad}(u)x = x$.

Thm Let G be a ctol cpt Lie group and $S \subseteq G$ a torus. Then the centralizer $C_G(S)$ is a closed ctol Lie subgroup of G .

PF Let $g \in C_G(S)$. By the previous propn, there exists an element $h \in C_G(S)$ which generates the closure H of the group generated by S and g . Let T be a maximal torus in G containing h . Then T centralizes S , so the closure of $T \cdot S$ is a ctol cpt abelian group, hence a torus, and by maximality of T we must have $S \subseteq T$. Now clearly $T \subseteq C_G(S)$, and since T is ctol, $T \subseteq C_G(S)^\circ$. Now $g \in H \subseteq T \subseteq C_G(S)^\circ$. Ergo $C_G(S)^\circ = C_G(S)$, i.e. $C_G(S)$ is connected. Now if u is a generator of $C_G(S)$, then $C_G(S) = C_G(\langle u \rangle)$, so by the last thm $C_G(S)$ is a closed ctol Lie subgroup. \square