

Progression Stabilizers and Representations

Recall IF  $G$  acts on  $M$  smoothly and properly, the orbits  $Gp \subseteq M$  are diffeomorphic to  $G/G_p$ , where  $G_p$  is the stabilizer  $G_p = \{g \in G : g \cdot p = p\}$

Let's think briefly about stabilizers.

Clearly  $G_p$  is a normal subgroup of  $G$ , and if  $j: G \rightarrow M$ ,  $\mathcal{F}_j$  has constant  $g \mapsto g \cdot j$

rank can be locally written  $(x_1, \dots, x_n) \rightarrow (x_1, \dots, x_{k-1}, 0, \dots, 0)$ , so  $j^{-1}(p)$  is in local coordinates  $\{(0, \dots, 0, x_{k+1}, \dots, x_n)\}$  a regular submanifold. (This is a slight generalization of the regular value thm.) So  $G_p$  is a closed Lie subgroup.

What is the Lie algebra of  $G_p$ ? Given  $x \in \mathfrak{g}$ , consider the path of diffeomorphisms  $M \rightarrow M$ ,  $t \mapsto \exp(tx) \cdot q$ . This gives a path  $\gamma_q(t) = \exp(tx) \cdot q$

at every point, and a vector field  $Y_x$  on  $M$  st  $Y_x(q) = \dot{\gamma}_q'(0)$ .  
via get a map  $\mathfrak{g} \rightarrow \text{Vect}(M)$ , The Lie algebra of  $G_p$  is then  $\mathfrak{g} \rightarrow Y_x$

exactly  $x \in \mathfrak{g}$  st  $Y_x(p) = 0$ .

Remark An ideal of a Lie algebra  $\mathfrak{g}$  is a subspace  $\mathfrak{h}$  st for any  $x \in \mathfrak{g}, y \in \mathfrak{h}, [x, y] \in \mathfrak{h}$ .

Propn For  $H$  an embedded Lie subgroup of  $G$ ,  $H$  normal  $\Rightarrow \mathfrak{h}$  is an ideal of  $\mathfrak{g}$  and  $\mathfrak{h}$  is an ideal of  $\mathfrak{g}$  and  $H, G$  connected  $\Rightarrow H$  normal.

PF  $H$  normal  $\Rightarrow$  For  $x \in \mathfrak{g}, y \in \mathfrak{h}, \exp(x)\exp(y)\exp(-x) \in H \Rightarrow \text{Ad}_{\exp(x)} y \in \mathfrak{h}$ .  
But  $(\text{Ad}_{\exp(x)})_* y = \text{ad}(x)y = [x, y]$ , so  $[x, y] \in \mathfrak{h}$ .

$\Leftarrow$  If  $\mathfrak{h}$  is an ideal of  $\mathfrak{g}$ , then  $\text{ad}(x)$  preserves  $\mathfrak{h} \Rightarrow \text{Ad}_{\exp(x)}$  preserves  $\mathfrak{h}$ . So  $\exp(x)\exp(y)\exp(-x) \in H$  For elements of the form  $\exp(x) \in \mathfrak{g}, \exp(y) \in \mathfrak{h}$ . But  $G, H$  are connected, so these generate the groups  $\Rightarrow$  we are done.  $\square$

So  $\mathfrak{g}$  in  $G/G_p \cong G_p$  for a free proper action of  $G$ ,  $T_p(G_p) \cong \mathfrak{g}/\mathfrak{h}$ , w/ notation as in previous page.

Some consequences

Corollary 1 Let  $f: G_1 \rightarrow G_2$  be a morphism of real or  $\mathbb{C}^*$  Lie groups and  $f_*: \mathfrak{g}_1 \rightarrow \mathfrak{g}_2$  the morphism of Lie algebras. Then  $\text{Ker } f$  is a closed Lie subgroup w/ Lie algebra  $\text{Ker } f_*$ , and the map  $G_1/\text{Ker } f \rightarrow G_2$  is an immersion. If  $\text{Im } f$  is a submfld, thus a closed Lie subgroup, we have a Lie group isomorphism  $\text{Im } f \cong G_1/\text{Ker } f$ .

PF Let  $G_1$  act on  $G_2$  by  $g \cdot h = f(g) \cdot h$  For  $f \in G_1, h \in G_2$ . Then the stabilizer of  $e \in G_2$  is  $\text{Ker } f$ , so it is a closed Lie subgroup w/ Lie algebra  $\text{Ker } f_*$ , and  $G_1/\text{Ker } f \hookrightarrow G_2$  is an immersion.

Corollary 2 Let  $G$  be a connected Lie group. Then its center  $Z(G)$  is a closed Lie subgroup w/ Lie algebra  $z(\mathfrak{g})$ . For  $G$  not connected,  $Z(G)$  is a closed Lie subgroup w/ Lie algebra contained (possibly properly) in  $z(\mathfrak{g})$ .

PF Given  $g \in G$  and  $x \in \mathfrak{g}$ , it follows from  $\exp(\text{Ad}_g(x)) = g \exp(x) g^{-1}$  that  $g$  commutes w/ all  $\exp(tx) \Leftrightarrow \text{Ad}_g(x) = x$ . So for a connected Lie group, since elements of the form  $\exp(tx)$  generate  $G$ ,  $g \in Z(G) \Leftrightarrow g \in \text{Ker Ad}$ , where  $\text{Ad}: G \rightarrow GL(\mathfrak{g})$  is the map induced by the adjoint action. So  $Z(G)$  is a closed Lie subgroup w/ Lie algebra  $\text{ker}(\text{Ad}_x) = \text{ker}(\text{ad}) = z(\mathfrak{g})$ .

(If  $G$  is not connected, it's not necessarily clear that everything in  $G$  commutes w/ the subgroup associated to  $z(\mathfrak{g})$ , e.g.  $S^1 \subseteq O(2)$ .)

The quotient group  $G/Z(G)$  is usually called the adjoint group

$$\text{Ad } G = G/Z(G) \cong \text{Im}(\text{Ad}: G \rightarrow GL(\mathfrak{g}))$$

$$\text{ad } \mathfrak{g} = \mathfrak{g}/z(\mathfrak{g}) \cong \text{Im}(\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g}))$$

Corollary Let  $V$  be a representation of a Lie group  $G$ , and  $v \in V$ . The stabilizer  $G_v$  is a closed Lie subgroup in  $G$  w/ Lie algebra  $\{x \in \mathfrak{g} : \rho_x(v) = 0\}$ .

Example Let  $V$  be a vector space over  $K$  w/ bilinear form  $B$ , and let  $O(V, B) = \{g \in GL(V) : B(g \cdot v, g \cdot w) = B(v, w) \forall v, w\}$  be the symmetry group. This is a Lie group over  $K$  w/ Lie algebra

$$o(V, B) = \{x \in \mathfrak{gl}(V) : B(x \cdot v, w) + B(v, x \cdot w) = 0\}$$

For if we let  $G$  act on the space of bilinear forms by  $(g \cdot F)(v, w) = F(g^{-1}v, g^{-1}w)$ ,  $O(V, B)$  is the stabilizer of  $B$ , hence a Lie group.

Examples

- $O(p, q), SO(p, q)$
- $Sp(n, \mathbb{C})$

Example For an arbitrary finite-dim'l associative algebra over  $K$ ,

$$Aut(A) = \{g \in GL(A) : (ga) \cdot (gb) = g(a \cdot b) \forall a, b \in A\}$$

is a Lie group w/ Lie algebra

$$Der A = \{x \in \mathfrak{gl}(A) : (x \cdot a)b = a(x \cdot b) = x \cdot (ab) \forall a, b \in A\}$$

↳ derivations

Indeed if  $G = GL(A)$  acts on the space of linear maps  $A \otimes A \rightarrow A$ ,  $(g \cdot F)(a \otimes b) = g(F(g^{-1}a \otimes g^{-1}b))$ ,  $Aut A = G_u$  where  $u$  is the multiplication.

(5)

Invariant Bilinear Forms & the Haar measure

Recall that a volume form on an  $n$ -dimensional manifold consists of a smooth assignment to every point  $p \in M$  of an alternating

$$\begin{aligned} \text{multilinear map } \omega_p : (T_p M)^{\otimes n} &\longrightarrow \mathbb{R} \\ (v_1, \dots, v_n) &\longmapsto \omega_p(v_1, \dots, v_n) \end{aligned}$$

Multilinear: linear in each coordinate

Alternating:  $\omega_p(v_1, \dots, v_i, \dots, v_j, \dots, v_i, \dots, v_j, \dots, v_n) = -\omega_p(v_1, \dots, v_j, \dots, v_i, \dots, v_i, \dots, v_j, \dots, v_n)$

What would this look like in coordinates?

$$\begin{aligned} V &= \mathbb{R}^n \\ T_p V &= \left\{ \frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right\} \\ (T_p V)^* &= \{ dx_1, \dots, dx_n \} \\ V^* & \end{aligned} \quad \begin{aligned} v_i &= \sum a_{ij} \frac{\partial}{\partial x_j} \\ dx_j(v_i) &= a_{ij} \end{aligned}$$

The space of multilinear maps  $V^{\otimes k} \rightarrow \mathbb{R}$  is generated by tensors  $\{ dx_{i_1} \otimes \dots \otimes dx_{i_k} \}$ , and an arbitrary multilinear map looks like

$\sum_{(i_1, \dots, i_k)} a_{(i_1, \dots, i_k)} dx_{i_1} \otimes \dots \otimes dx_{i_k}$ . So over  $U$  a smooth assignment looks like

$\sum_{(i_1, \dots, i_k)} f_{(i_1, \dots, i_k)} dx_{i_1} \otimes \dots \otimes dx_{i_k}$ . For the map to be alternating, for  $\sigma \in S_k$  we

have  $f_{(i_{\sigma(1)}, \dots, i_{\sigma(k)})}(p) = \text{sgn}(\sigma) f_{(i_1, \dots, i_k)}(p)$ . In particular if  $i_k = i_\ell$  for any  $k \neq \ell$ ,

$$f_{(i_1, \dots, i_k)} = 0. \text{ So if we let } dx_{i_1} \wedge \dots \wedge dx_{i_k} = \sum_{\sigma \in S_k} (-1)^{\text{sgn} \sigma} dx_{i_{\sigma(1)}} \wedge \dots \wedge dx_{i_{\sigma(k)}}$$

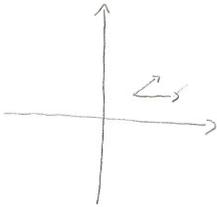
an alternating multilinear map can be written  $\sum_{1 \leq i_1 < i_2 < \dots < i_k \leq n} f_{(i_1, \dots, i_k)}(p) dx_{i_1} \wedge \dots \wedge dx_{i_k}$

The space of alternating multilinear maps  $\Lambda^k V^*$  is  $\binom{n}{k}$ -dimensional.

In particular, in coordinates a volume form is  $\omega = f \cdot dx_1 \wedge \dots \wedge dx_n$ , where  $f$  is some smooth fn  $f: U \rightarrow \mathbb{R}$ .

Examples

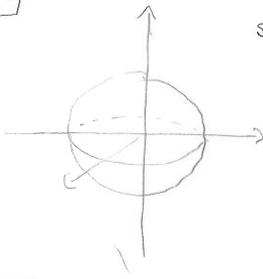
$\mathbb{R}^n$ ] The standard volume form is  $dx_1 \wedge \dots \wedge dx_n$



$\mathbb{R}^2$   $\omega = dx_1 \wedge dx_2$

$\omega(v_1, v_2), (w_1, w_2) = v_1 w_2 - v_2 w_1$

$S^2$

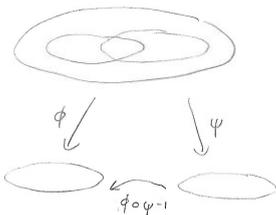


$S^2$   $ds = x dy \wedge dz + y dz \wedge dx + z dx \wedge dy = d\theta \wedge d\phi$

For a hypersurface, we can get a volume form by making the last term a unit normal;  $(x, y, z)$  in this case.

(Exercise: Rewrite in your favorite coordinates.)

Change of coordinates

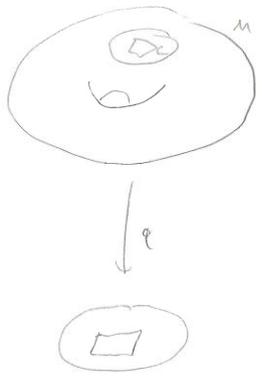


$f dx_1 \wedge \dots \wedge dx_n \rightsquigarrow f \circ (\phi \circ \psi^{-1}) \circ \det(\phi \circ \psi^{-1}) dy_1 \wedge \dots \wedge dy_n$

Note that, in particular, in order for such a form to exist it must be possible to choose coordinate charts for which  $\det(\phi \circ \psi^{-1}) > 0$  throughout. This is an orientation.

If  $G$  is a Lie group, choosing a basis  $\{x_1, \dots, x_n\}$  induces a frame  $X_1, \dots, X_n$  st at every  $g \in G$  the vectors  $X_1(g), \dots, X_n(g)$  are a basis for  $T_g G$ . So there is a volume form  $w = dx_1 \wedge \dots \wedge dx_n$ .

Relationship to Integration and measures.



If  $C$  cpt and inside a chart on which  $w = f dx_1 \wedge \dots \wedge dx_n$ ,

$$\int_C w = \int_{\phi(C)} (\phi^{-1})^* w = \int_{\phi(C)} f dx_1 dx_2 \dots dx_n$$

Propn This is well-defined (one checks that the change of variables formula works as expected).

For sets not contained in a single chart (but still cpt) one chooses a partition of unity on  $M$ :

Defn A partition of unity subordinate to a given atlas is a countable sequence of smooth  $\psi_i : M \rightarrow [0, 1]$  st

- ①  $\forall p \in M, \exists$  a nbhd on which  $\psi_i = 0$  for all but finitely many  $i$ .
- ②  $\sum_{i=1}^{\infty} \psi_i(p) = 1 \quad \forall p \in M$
- ③ Each  $\psi_i$  has cpt spt contained in some  $U_i$  st  $\phi_i : U_i \rightarrow \mathbb{R}^n$  is a chart in the atlas

Then  $\int_C w = \sum_i \int_C \psi_i w$

Note For cpt ? orientable  $\int_M \omega$  is finite.

This defines a Lebesgue measure  $\mu(U) = \int_U \omega = \int_V \omega$  on the Borel  $\sigma$ -algebra

(i.e., the  $\sigma$ -algebra generated from open sets by countable unions, countable intersections, and complements)

For  $G$  a Lie group Rescale the left-inv't volume form s.t.  $\int_G \omega = 1$ .

What about right invariance?

- Want to consider  $R_g^* \omega$  for all  $\omega$ .
- There is a map  $\psi: G \rightarrow \mathbb{R}^x$   $\cong \mathbb{R}^x \omega_p$ , Let  $\psi(g)$  be the coefficient  
 $g \mapsto R_g^* \omega_p = \psi(g) \omega_p$

If  $G$  is cpt and connected, we observe that if  $|\psi(g)| < 1$ , then  $|\psi(g^n)| = |\psi(g)^n| \rightarrow 0$  as  $n \rightarrow \infty$ , which is impossible because  $G$  cpt. Likewise if  $|\psi(g)| > 1$ . So  $|\psi(g)| = 1$ .  $G$  connected  $\Rightarrow \omega$  right-inv't.  $G$  disconnected  $\Rightarrow \omega$  right-inv't up to a sign.

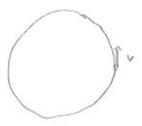
Inversion?  $i: G \rightarrow G$ .  $i^* \omega$  is clearly left-inv't since  $\omega$  right-inv't. So suffices to check  $\omega$  and  $i^* \omega$  are equal up to a sign at  $e$ . But the derivative of  $i$  at  $e$  is  $-I$ , so  $i^* \omega = (-1)^n \omega$

Thm Let  $G$  be a compact (real Lie) group. Then it has a canonical Borel measure which is left- and right- invt and invt under  $g \mapsto g^{-1}$  w/  $\int_G dg = 1$ . This is the Haar measure on  $G$ ,

For Fcts on  $G$ ,  $\int_G f dg = \int_G F \cdot w$ .

Example  $G = S^1 \simeq \mathbb{R}/\mathbb{Z}$ . The Haar measure is the ordinary measure  $dx$

$w$  is st  
 $w_G(v) = 1$



Example (we might have the tools to prove at some point)

Let  $G = U(n)$  and  $F$  be a smooth Fcn on  $G$  st  $F(ghg^{-1}) = F(h)$ . Then

$$\int_{U(n)} F(g) dg = \frac{1}{n!} \int_T F \left( \begin{matrix} t_1 & & \\ & \dots & \\ & & t_n \end{matrix} \right) \prod_{i < j} |t_i - t_j|^2 dt$$

where  $T = \left\{ \left( \begin{matrix} t_1 & & \\ & \dots & \\ & & t_n \end{matrix} \right), |t_k| = 1 \right\}$  is the subgroup of diagonal matrices

and  $dt = \frac{1}{(2\pi)^n} d\theta_1 \dots d\theta_n$  is the Haar measure.

Thm Any finite-dim'l representation of a cpt Lie group is completely reducible.

PF  $\tilde{\theta}(v, w) = \int_G \theta(gv, gw) dg$ . Then  $\tilde{\theta}(v, v) > 0$  since it is a positive fn and by right-invariance of the measure,  $\tilde{\theta}(hv, hw) = \int_G \theta(ghv, ghw) dg = \int_G \theta(gv, gw) dg = \tilde{\theta}(v, w)$ .

Orthogonality of Characters

Let  $G$  be a compact real Lie group, and  $V$  be a representation. Choose a basis  $\{v_1, \dots, v_k\}$  for  $V$ , and write each  $\rho_g = \rho(g)$  in this basis. The entries in the corresponding matrix  $\rho_{ij}(g)$  are matrix coefficients of  $V$ .

As previously, we have an inner product on  $C^\infty(G, \mathbb{C})$  given by

$$(F_1, F_2) = \int_G F_1(g) \overline{F_2(g)} dg.$$

As previously, the character of a representation  $V$  is

$$\chi_\rho(g) = \text{tr } \rho(g) = \sum_i \rho_{ii}(g)$$

Properties

- ①  $\chi_{\rho \oplus \sigma} = \chi_\rho + \chi_\sigma$
- ②  $\chi_{\rho \otimes \sigma} = \chi_\rho \chi_\sigma$
- ③  $\chi_\rho(g h g^{-1}) = \chi_\rho(h)$
- ④  $\chi_{\rho^*} = \overline{\chi_\rho}$