

Lecture 2

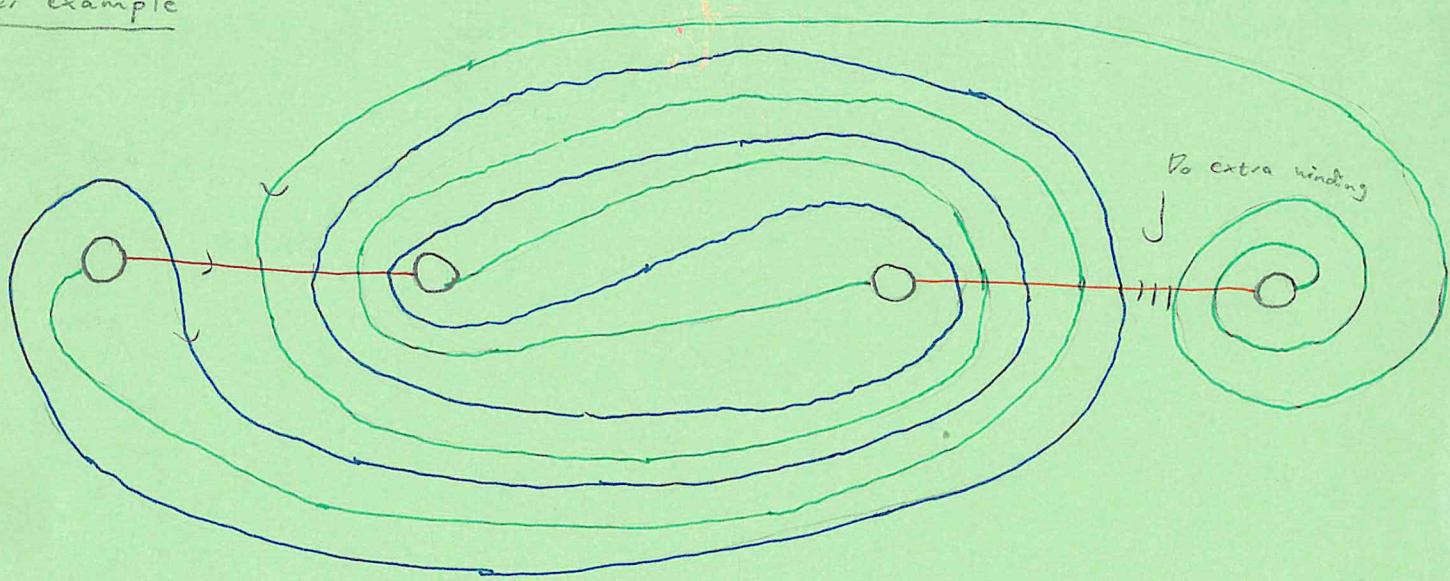
C117

Last Time A (singly-pointed) Heegaard diagram consists of
 $\mathcal{H} = (\Sigma, \vec{\alpha}, \vec{\beta}, z)$ w/

- Σ a surface of genus g
- $\vec{\alpha} = (\alpha_1, \dots, \alpha_g)$ (respectively $\vec{\beta} = (\beta_1, \dots, \beta_g)$) are a collection of nonintersecting simple closed curves of Σ s.t. $g = \dim \text{Span } \{[\alpha_i]\} \subseteq H_1(\Sigma; \mathbb{R})$, and $\alpha_i \pitchfork \beta_j$.
- z is a basepoint in $\Sigma - \{\vec{\alpha}\} - \{\vec{\beta}\}$.

A Heegaard diagram gives us a unique way of constructing a 3-manifold.
Last Time Some genus one Heegaard diagrams.

Another example



This is $\Sigma(2,3,2)$.

Exercise $H_1(Y) = \mathbb{Z}_2$ yourself. The genus one manifold $\Sigma(2,3,2)$ has a topology of spheres with one or w/ three extra wrappings,

$$H_1(Y) = \emptyset.$$

$$\Sigma(2,3,5) / \Sigma(2,3,7)$$

(2)

When do two Heegaard diagrams give the same 3-mfd?

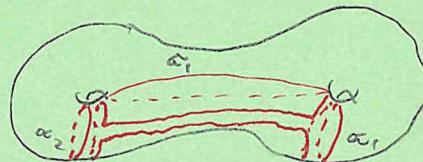
When they are connected by Heegaard moves.

- ① Isotopy of curves not crossing the basepoint.



Preserves
the
Heegaard
decomposition

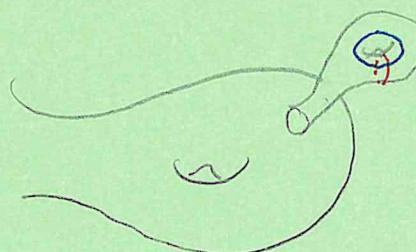
- ② Handleslides amongst α (respectively β) curves



$\alpha_1, \alpha_2, \tilde{\alpha}_i$ bound an embedded pair of pants in $\Sigma - \{\alpha_3, \dots, \alpha_g\}$



- ③ (De)Stabilization



Connect sum w/ a genus 1 surface as shown.

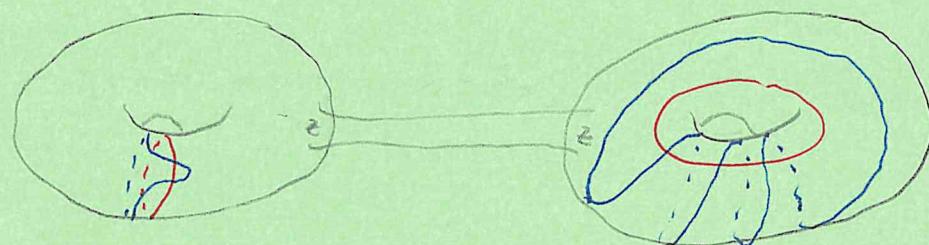
Note that this has the effect of connect summing your mfd w/ S^3 .

Theorem (Singer) Given two Heegaard decompositions (Y, u_0, v_0) and (Y, u_0', v_0') of a 3-mfd Y having genus g and g' respectively, $\exists g \text{ st the } (k-g) \text{-fold stabilization}$ of the first decomposition is diffeomorphic to the $(k-g)$ -fold stabilization of the second decomposition.

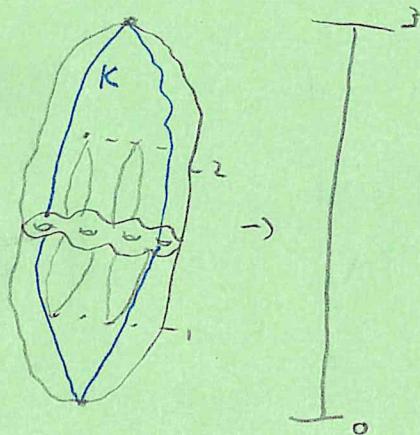
Thm Let N be a handlebody of genus g , and let $(\alpha_1, \dots, \alpha_g)$ and $(\alpha'_1, \dots, \alpha'_g)$ be two sets of attaching curves for N . Then the two sets of attaching curves can be connected by a series of isotopies and handleslides.

Ex Given two Heegaard diagrams, $H_1 = (\Sigma_g, \{\alpha_1, \dots, \alpha_g\}, \{\beta_1, \dots, \beta_g\}, z_1)$ and $H_2 = (\Sigma_g, \{\alpha'_1, \dots, \alpha'_g\}, \{\beta'_1, \dots, \beta'_g\}, z_2)$, if a sequence of stabilizations, pointed isotopies, and pointed handleslides connecting them.

Q Given two Heegaard diagrams H_i for γ_i , $i=1, 2$, how do we get a Heegaard diagram for the connected sum $\gamma_1 \# \gamma_2$?



We can also consider doubly-ptd Heegaard diagrams.



We write K as a union of a flowline from the index 0 critical pt \rightarrow the index 3 critical pt.

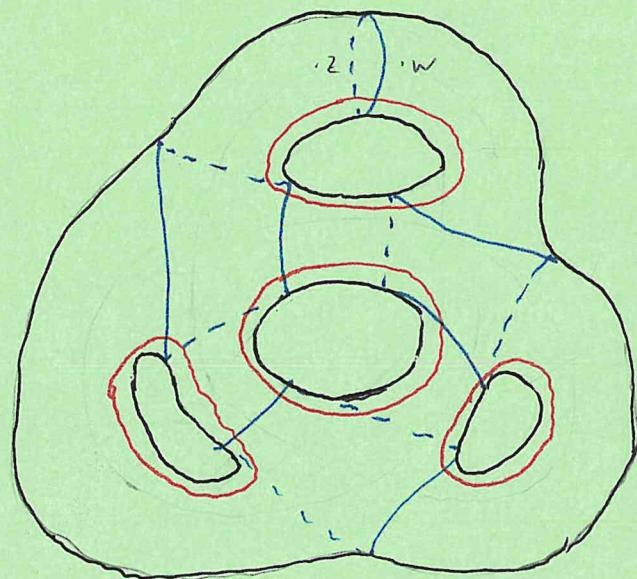
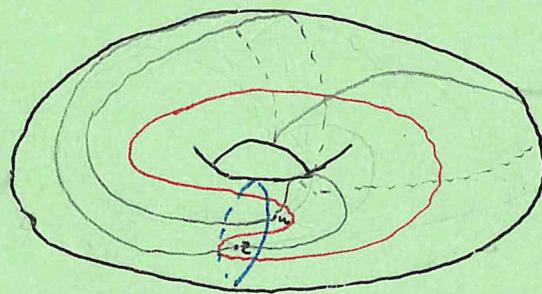
We put a basepoint z at the descending intersection and w at the ascending γ .

For practical purposes, if we have a Heegaard diagram

$H = (\Sigma, \vec{\alpha}, \vec{\beta}, w, z)$ we can recover the knot via.

- Connecting w to z by an arc in the complement of the $\vec{\beta}$ curves
- Connecting z to w by an arc in the complement of the $\vec{\alpha}$ curves.

Exercise This is necessarily unique up to isotopy.



We now ask for ^{pointed} isotopies and handle slides to avoid both basepoints.

Q1 How do I reverse the orientation of the knot or link?

Q2 How do I take the mirror of the knot or link?

Q3 How do I get a Heegaard diagram for ^{some} surgery on the trefoil?

Exercise Which surgery is it?

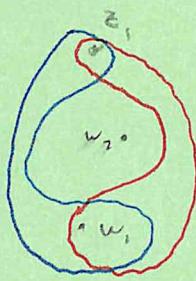
NB We can also take multi-pointed Heegaard diagrams.

$$H = (\Sigma_g, \{\alpha_1, \dots, \alpha_{g+k}\}, \{B_1, \dots, B_{g+k}\}, \{z_1, \dots, z_n\}) \text{ or}$$

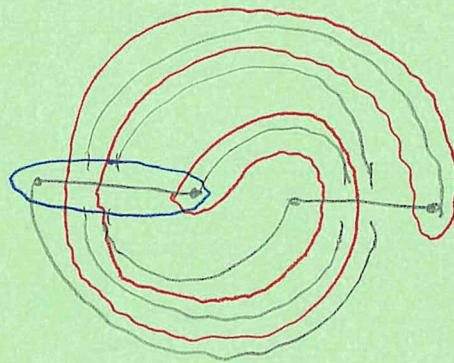
$$H = (\Sigma_g, \{\alpha_1, \dots, \alpha_{g+k}\}, \{B_1, \dots, B_{g+k}\}, \{z_1, \dots, z_n\}, \{w_1, \dots, w_n\})$$

eg

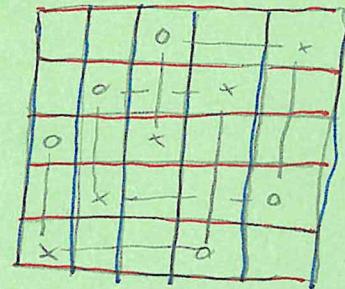
S^3



S^3

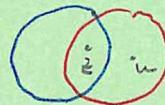


$S^1 \times S^1$



z_n

If we want to be able to change π_1 of bps we allow the stabilization.



Exercise Say I have $(\Sigma(k), \tilde{k})$ is a double branched cover. Construct (S^3, k)

an Heegaard diagram for $(\Sigma(k), \tilde{k})$.

Symmetric Products

Given a space Y , its ^{g -fold} symmetric product is

$$\text{Sym}^g(Y) = \underbrace{Y \times \dots \times Y}_{g\text{-times}} / S_g = \{ \text{Unordered } g\text{-tuples of points in } Y \}$$

\curvearrowleft Symmetric group

Example $\text{Sym}^g(\mathbb{C}) \xleftarrow{\text{diffeomorphism}} \mathbb{C}^g$

$$f(x) = (x-a_1) \dots (x-a_g) \longleftrightarrow \text{coefficients of } f(x)$$

Exercise $\text{Sym}^g(S^1) \xrightarrow{\text{homeomorphic}} S^1$

Exercise $\text{Sym}^g(\Sigma)$, for Σ a Riemann surface, is always a $2g$ -dim'l complex mfd.

[Extremely not true in higher dimensions.]

Exercise The homotopy type of $\text{Sym}^g(\Sigma - \{z_i\})$ is a skeleton of a torus. (In the standard CW decomposition.)

In $\text{Sym}^g(\Sigma)$ we have:

$$\cdot \Pi_{\infty} = \alpha_1 \times \dots \times \alpha_g$$

$$\cdot \Pi_B = B_1 \times \dots \times B_g$$

$$\cdot V_z = [z \times \text{Sym}^{g-1}(\Sigma_g)]$$

$$\cdot V_w = [w \times \text{Sym}^{g-1}(\Sigma_g)]$$

$$\text{Propn } \pi_2(\text{Sym}^g(\Sigma)) = \mathbb{Z} \text{ for } g > 2.$$

$$\text{Propn } \pi_1(\text{Sym}^g(\Sigma)) = H_1(\Sigma)$$

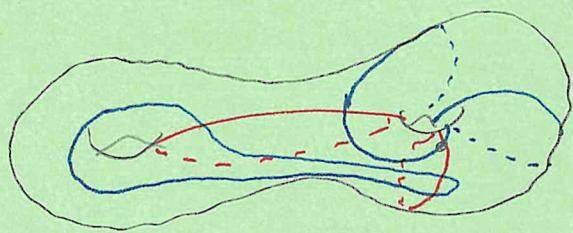
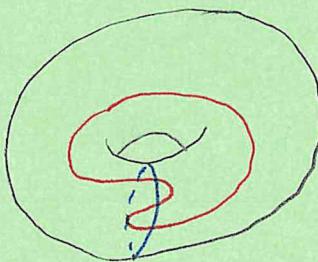
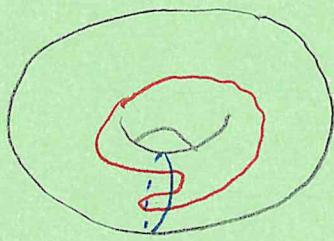
This is an actual product since the α_i do not intersect

Exercise

$$\frac{H_1(\text{Sym}^g(\Sigma))}{H_1(\Pi_{\infty}) \oplus H_1(\Pi_B)} \simeq \frac{H_1(\Sigma)}{[a_1, 1, \dots, 1, a_g]} \simeq H_1(Y)$$

We look at intersection points between π_α and π_β

(Finitely many b/c $\pi_\alpha \pitchfork \pi_\beta$).



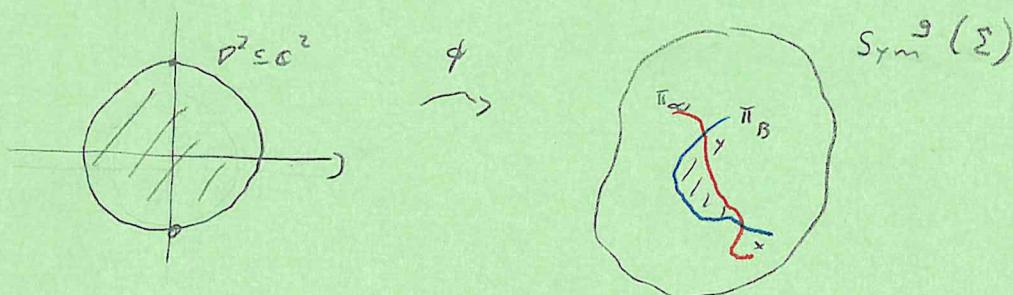
B_1	R_1	R_2
	1	1
B_2	1	2

$$\text{Def}_n CF^-(Y) = \bigoplus_{x \in \pi_\alpha \cap \pi_\beta} \mathbb{F}_2 [v] \langle \times \rangle$$

$$\widehat{CF}(Y) = \bigoplus_{x \in \pi_\alpha \cap \pi_\beta} \mathbb{F}_2 \langle \times \rangle$$

Boundary Operator

Whitney Disk A map $\varphi: \{i, -i\} \rightarrow \pi_\alpha \cap \pi_\beta$



$s+$ $[-i, i] \rightarrow \pi_\alpha^-$. This is a Whitney disk from x to y .

$[i, -i] \rightarrow \pi_\beta^-$ The set of homotopy classes of such disks is $\pi_2(y, y)$.

• $\pi_\alpha^-, \pi_\beta^-$ are totally real in $\text{Sym}^2(\Sigma)$, i.e. $T(T(\pi_\alpha^-)) \cap T(\pi_\alpha^-) = \emptyset$

(8)

$$n_z(\phi) = \#_{\text{Alg}} \text{Im}(\phi) \cap V_z$$

$$n_w(\phi) = \#_{\text{Alg}} \text{Im}(\phi) \cap V_w.$$

Disks come w/ a natural multiplicative structure

$$\pi(x, y) * \pi(y, z) \rightarrow \pi(x, z)$$

$$\pi'_2(Sym^2(\Sigma)) * \pi_2(\gamma, \gamma) \rightarrow \pi_2(x, y)$$



We can also study a disk via studying its shadow

Defn Let D_1, \dots, D_m denote the closures of the components of $\Sigma - \sum \partial_{z_i} - \arg \beta - \sum B_{ij} - \{B_j\}$. Given $\phi \in \pi_2(x, y)$ the shadow of ϕ , or domain associated to ϕ , is a formal linear combination of the regions $\sum_{i=1}^m n_{z_i}(\phi) D_i$.

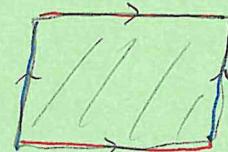
$$D(\phi) = \sum_{i=1}^m n_{z_i}(\phi) D_i$$

For z_i some point in the interior of D_i .

The shadow is a (multiply branched) cover of the disk.

$$\begin{array}{ccc} S & \longrightarrow & \Sigma \\ \downarrow & & \int \\ D^2 & \longrightarrow & Sym^2(\Sigma) \end{array}$$

Things that are disks on a diagram of $g = 2$



w



Is there a disk connecting any two points of $\pi_A \cap \pi_B$?