

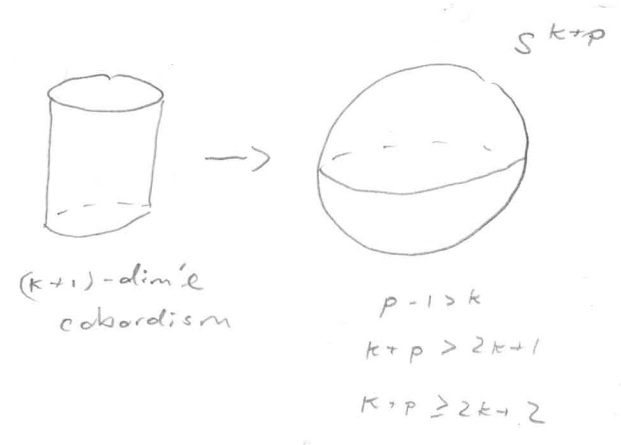
Lecture 3 Recall

$$\left\{ \begin{array}{l} \text{(smooth) } k+p \text{ y} \\ \text{classes of} \\ \text{maps } f: M \rightarrow S^k \end{array} \right\} \longleftrightarrow \left\{ \begin{array}{l} \text{Framed } m\text{-d submfd's} \\ \text{up to Framed cobordism} \end{array} \right\}$$

Corollary

$$\pi_{k+p}^S(S^p) = \left\{ \begin{array}{l} \text{Framed cobordism classes of } k\text{'dim'd} \\ \text{submanifolds in } S^{k+p} \end{array} \right\}$$

For $k < p-1$, we have $\pi_k^S = \mathbb{R}_k^{Fr}$



Left to prove

Thm 2 Two maps $M \rightarrow S^p$ are smoothly homotopic (\Rightarrow) their Pontrjagin mfd's are framed cobordant.

Last time \Rightarrow

Today \Leftarrow

Finally, Thm 2 Say F, g both have y as a regular value. (2) (6)

Remains to show $\Rightarrow (F^{-1}(y), F^*v) \sim (g^{-1}(y), g^*v) \Rightarrow F, g$

Lemma IF $(F^{-1}(y), F^*v)$ is equal to $(g^{-1}(y), g^*v)$ then F, g homotopic.
 F is smoothly homotopic to g .

PF Let $N = F^{-1}(y)$. Since $F^*v = g^*v$, $dF_x = dg_x \quad \forall x \in N$.

Case I $F = g$ on a nbhd V of N . Let $h: S^p - y \rightarrow \mathbb{R}^p$ be projection.

$$\text{Set } \begin{cases} H(x, t) = F(x) & \text{For } x \in V \\ H(x, t) = h^{-1} [t h(F(x)) + (1-t) h(g(x))] & \text{For } x \in M - V \end{cases}$$

\leftarrow These agree on $V - N$

Case II We need to arrange for such a neighborhood V .

First. Pick a product neighborhood $N \times \mathbb{R}^p \rightarrow V \subseteq M$, w/

V small enough so the antipode \bar{y} of y is not in $F(V)$ or

$g(V)$. Get $F, G: N \times \mathbb{R}^p \xrightarrow{\rightarrow V} \mathbb{R}^p \simeq S^p - \{y, \bar{y}\}$ w/ $F^{-1}(0) = G^{-1}(0) = N \times \{0\}$

and w/ $dF_{(x,0)} = dG_{(x,0)} = \text{projection to } \mathbb{R}^p$. IF we can

find c st $F(x, u) \cdot u > 0, G(x, u) \cdot u > 0$ For all $x \in N$ and $0 < \|u\| < c$,

then points in $F(x, u)$ and $G(x, u)$ are in the same

open half-space in \mathbb{R}^p . So a htpy $(1-t)F(x, u) + tG(x, u)$

doesn't map any new points into 0 for $\|u\| < c$.

Let's find such a c .

Taylor's Thm $\|F(x,u) - u\| \leq c_1 \|u\|^2$ For $\|u\| \leq 1$ and some c_1

Approximation at $(x,0)$.

Cauchy-Schwarz

$$\Rightarrow |(F(x,u) - u) \cdot u| \leq \|F(x,u) - u\| \|u\| \leq c_1 \|u\|^3$$

$$\|u\|^2 - F(x,u) \cdot u \leq c_1 \|u\|^3$$

$$\Rightarrow F(x,u) \cdot u \geq \|u\|^2 - c_1 \|u\|^3 > 0 \text{ on } 0 < \|u\| < c = \text{Min}(c_1^{-1}, 1)$$

For distant points we can choose some $\lambda: \mathbb{R}^p \rightarrow \mathbb{R}$ with

$$\lambda(u) = 1 \text{ For } \|u\| \leq \frac{c}{2}$$

$$\lambda(u) = 0 \text{ For } \|u\| \geq c$$

The homotopy $F_t(x,u) = [1 - \lambda(u)t] F(x,u) + \lambda(u)t G(x,u)$ is F for $\|u\| \geq c$, G for $\|u\| < \frac{c}{2}$, and has no new zeroes. ^{F_t can then} This can then be deformed into G using case I.

Finally, Proof of Thm 2

(\Leftarrow) Say (x,w) is the framed cobordism between $F^{-1}(y)$ and $g^{-1}(y)$. Then just as we used the

Pontrjagin-Thom construction to give a smooth map for any framed submfld last time, we can produce

$$F: M \times [0,1] \rightarrow SP$$

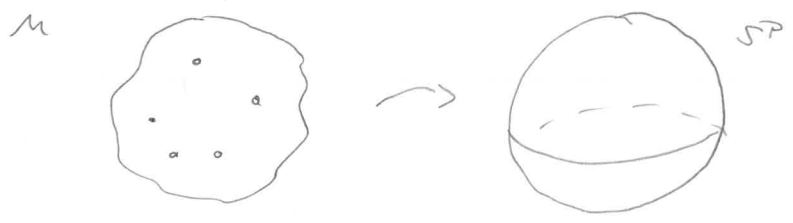
$$(x,t) \mapsto F_t(x)$$

w/ Pontrjagin mfd. $(F^{-1}(y), F^{-1}(v)) = (x,w)$. Now F_0, F have the same Pontrjagin mfd \Rightarrow by the lemma, $F_0 \sim F$. likewise $F_1 \sim g$.

So $F \sim g$! \square

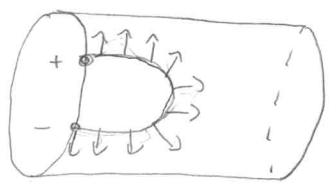
Example (Hopf degree)

M connected, orientable, $m=p$.



Framed submanifold Finite set of points w/ a basis for TM at each. Assign $\pm 1 = \text{sign}(x)$ at each according to whether the basis agrees w/ the orientation.

Framed cobordism Determined by sum of signs = degree.



Thm (Hopf) Two maps $M^p \rightarrow S^p$ are smoothly homotopic (\Rightarrow) they have the same degree.

So we see again that $\pi_0^S = \mathbb{Z}$.

Hw What is π_1^S ?

What if M is not orientable?

Given a basis for $T_x M$, can slide around a loop in M to reverse orientation.



Thm M connected, nonorientable, then two maps $M \rightarrow S^m$ are htpc (\Rightarrow) they have the same mod 2 degree.

Last Thing The J -homomorphism

We have

$$\pi_r^S = \left. \begin{array}{l} \text{Stably Framed} \\ r\text{-mfds up to stable} \\ \text{Framed cobordism} \end{array} \right\} = \Omega_{fr}^r$$

There is a map $J : \pi_r(SO) \rightarrow \pi_r^S$

\uparrow framings of S^r up to homotopy
 \uparrow all framed r -dim'l mfds up to Framed cobordism

In the sense of being a length-preserving map $\mathbb{R}^q \rightarrow \mathbb{R}^q$

Concretely An element of $SO(q)$ is a map $S^{q-1} \rightarrow S^{q-1}$; so $\xi \in \pi_r(SO(q))$

gives $S^r \times S^{q-1} \rightarrow S^{q-1}$. This gives a map $S^{r+q} = S^r * S^q \rightarrow \Sigma(S^{q-1}) = S^q$

The image of this map is an important subgroup of π_r^S

\downarrow $\Sigma(S^r \times S^{q-1})$
 \parallel $S^{r+q} \times S^{r+q} \vee S^{q+2}$

	0	1	2	3	4	5	6	7	8	9	10	11
$ \pi_r(SO) $	1	2	1	\mathbb{Z}	1	1	1	\mathbb{Z}	2	2	1	\mathbb{Z}
$ \text{Im}(J) $	1	2	1	24	1	1	1	240	2	2	1	504
$ \pi_r^S $	\mathbb{Z}	2	2	24	1	1	2	240	2^2	2^3	6	504

At 3 mod 4 order is B_{2n}
 $\frac{1}{4n}$
 Bernoulli number

For the past two lectures we've been talking about taking ^① ~~②~~ the suspension SX or ΣX of a space.

We've been talking about the maps

$$\langle X, Y \rangle \rightarrow \langle \Sigma X, \Sigma Y \rangle \rightarrow \langle \Sigma^2 X, \Sigma^2 Y \rangle \rightarrow \dots$$

We also want to think about a related construction, the based loop space, $\Omega X = \{ \gamma : [0, 1] \rightarrow X : \gamma(0) = \gamma(1) = x_0 \}$,

Before we talk seriously about this we should review topologies on spaces of maps.

Compact-open topology

- $\text{MAP}(X, Y)$ on Y^X
- Elements are cts maps. $f: X \rightarrow Y$
- Sub-basis for the topology: $M(K, U)$ For K compact in X and U open in Y .
- Basis is finite intersections of these.

eg for $X = [0, 1]$, a nbhd basis for $f: I \rightarrow Y$ is given by a partition of I into closed intervals $[x_i, x_{i+1}]$ and open sets U_i st $f([x_i, x_{i+1}]) \subseteq U_i$.