

1.2.13

$$*(5, b, c) \cdot (1, 2, 3) = 0$$

$$5 + 2b + 3c = 0$$

$$*(5, b, c) \cdot (1, -2, 1) = 0$$

$$5 - 2b + c = 0$$

$$(5 + 2b + 3c) + (5 - 2b + c) = 0 + 0$$

$$10 + 4c = 0$$

$$c = -\frac{5}{2} \rightarrow 5 - 2b - \frac{5}{2} = 0$$

$$-2b = -2.5 \rightarrow b = 1.25 = \frac{5}{4}$$

$$\Rightarrow (5, \frac{5}{4}, -\frac{5}{2})$$

1.2.16

$$A) \vec{u} = (15, -2, 4)$$

$$|\vec{u}| = \sqrt{225 + 4 + 16} = \sqrt{245} = 7\sqrt{5}$$

$$\text{Normalized} = \frac{1}{7\sqrt{5}} \vec{u} = \left(\frac{15}{7\sqrt{5}}, \frac{-2}{7\sqrt{5}}, \frac{4}{7\sqrt{5}} \right)$$

$$= \left(\frac{3\sqrt{5}}{7}, \frac{-2\sqrt{5}}{35}, \frac{4\sqrt{5}}{35} \right)$$

$$\vec{v} = (\pi, 3, -1)$$

$$|\vec{v}| = \sqrt{\pi^2 + 9 + 1} = \sqrt{10 + \pi^2}$$

$$\text{Normalized} = \frac{1}{\sqrt{10 + \pi^2}} \vec{v}$$

$$= \left(\frac{\pi}{\sqrt{10 + \pi^2}}, \frac{3}{\sqrt{10 + \pi^2}}, \frac{-1}{\sqrt{10 + \pi^2}} \right)$$

$$B) \vec{u} = (-1, 2, 0)$$

$$|\vec{u}| = \sqrt{1 + 4} = \sqrt{5}$$

$$\text{Normalized} = \frac{1}{\sqrt{5}} \vec{u} = \left(\frac{-1}{\sqrt{5}}, \frac{2}{\sqrt{5}}, 0 \right)$$

$$\vec{v} = (1, -1, 0)$$

$$|\vec{v}| = \sqrt{1 + 1 + 0} = \sqrt{2}$$

$$\text{Normalized} = \frac{1}{\sqrt{2}} \vec{v} = \left(\frac{1}{\sqrt{2}}, \frac{-1}{\sqrt{2}}, 0 \right)$$

$$= \left(\frac{\sqrt{2}}{2}, -\frac{\sqrt{2}}{2}, 0 \right)$$

$$C) \vec{u} = (5, -1, 2)$$

$$|\vec{u}| = \sqrt{25 + 1 + 4} = \sqrt{30}$$

$$\text{Normalized} : \frac{1}{\sqrt{30}} \vec{u} = \left(\frac{5}{\sqrt{30}}, \frac{-1}{\sqrt{30}}, \frac{2}{\sqrt{30}} \right)$$

$$\vec{v} = (-2, -3, -7)$$

$$|\vec{v}| = \sqrt{4 + 9 + 49} = \sqrt{62}$$

$$\text{Normalized} = \left(\frac{-2}{\sqrt{62}}, \frac{-3}{\sqrt{62}}, \frac{-7}{\sqrt{62}} \right)$$

Notice a mistake? Be the
first one to email me and get
a free candy bar! (or some
equivalent prize)

HW#2

[1.2.19]

Orthogonal \Rightarrow their dot product is zero

$$(7, x, -10) \cdot (3, x, x) = 21 + x^2 - 10x = 0$$

This is a quadratic:

$$x^2 - 10x + 21 = (x-7)(x-3) = 0$$

$\Rightarrow x=7, 3$ are the only solutions.

[1.2.25]

Two nonparallel vectors orthogonal to $(1, 1, 1)$: their respective dot products are zero. Let $\vec{v}_1 = (a, b, c)$ and $\vec{v}_2 = (d, e, f)$ with

$$\vec{v}_2 \cdot \vec{x} = 0 \Rightarrow d + e + f = 0$$

$$\vec{v}_1 \cdot \vec{x} = 0 \Rightarrow a + b + c = 0$$

There are many different valid solutions to this problem!

You can start with any two a, b and d, e and then solve the system to find c and f . Two examples are $(0, 4, -4)$ and $(1, 2, -3)$. The only caveat is that you must prove the two vectors you chose are nonparallel; i.e. there does not exist $\alpha \in \mathbb{R}$ such that $\alpha \vec{v}_1 = \vec{v}_2$, which is simple to do by showing the resulting system has no solutions; for example:

Assume $\exists \alpha \in \mathbb{R}$ such that $\alpha \vec{v}_1 = \vec{v}_2$. Then

$\alpha(0, 4, -4) = (1, 2, -3)$ and $0 = 1$, which is a contradiction, so our premise was false and no such scalar exists.

1.2.26

Find the line through $(3, 1, -2)$ that intersects and is perpendicular to the line $\ell_1(t) = (-1+t, -2+t, -1+t)$.

Our line will be of the form $\ell_2(t) = (3, 1, -2) + t(a, b, c)$ where $(a, b, c) \cdot (1, 1, 1) = 0$ (perpendicular) and at time s , both lines meet at $(x_0, y_0, z_0) = \vec{P}_0$:

$$\ell_1(s) = \vec{P}_0 \Rightarrow (x_0, y_0, z_0) = (-1+s, -2+s, -1+s)$$

$$\ell_2(s) = \vec{P}_0 \Rightarrow (x_0, y_0, z_0) = (3+sa, 1+sb, -2+sc)$$

$$\text{We can then solve for } a, b, c: a = -\frac{4+s}{s}, b = -\frac{3+s}{s}, c = \frac{1+s}{s}.$$

But by \perp , $a+b+c=0$, so we can solve for s :

$$\left(-\frac{4+s}{s}\right) + \left(-\frac{3+s}{s}\right) + \left(\frac{1+s}{s}\right) = 0$$

$$-6+3s=0 \Rightarrow s=2$$

So by plugging back into $\ell_1(2)$, we can find the intersect pt:

$$(x_0, y_0, z_0) = (1, 0, 1)$$

From there we can solve for a, b, c : $\ell_2(2) = (1, 0, 1)$

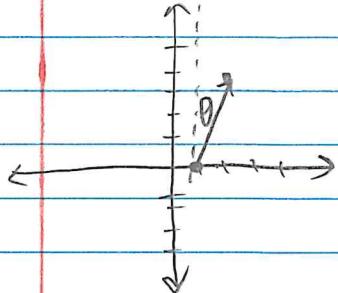
$$= (3+2a, 1+2b, -2+2c)$$

$$\Rightarrow a=-1, b=-\frac{1}{2}, \text{ and } c=\frac{3}{2}.$$

$$\Rightarrow \underline{\ell_2(t) = (3, 1, -2) + t(-1, -\frac{1}{2}, \frac{3}{2})}$$

1.2.29

$$a) (2, 4) - (1, 0) = \underline{(1, 4)} = \vec{v}$$



$$b) \vec{v} \cdot (0, 1) = |\vec{v}| |(0, 1)| \cos \theta$$

$$1 \cdot 0 + 4 \cdot 1 = \sqrt{17} \sqrt{1} \cos \theta$$

$$\theta = \arccos(4/\sqrt{17}) \approx 0.245 \text{ rad}$$

$$\approx 14.04^\circ$$

1.2.31

$\ell(t) = (3, 4, 5) + t(400, 500, -1)$ equivalent to $x(t) = x_0 + vt$
where is it when $x = 23, y = 29$?

$$3 + 400t = 23 \Rightarrow t = 0.05$$

$$4 + 500t = 29 \Rightarrow t = 0.05 \text{ hr} \quad \text{so } \textcircled{a} \ t = 0.05 \text{ hr (3 min)} \\ = \underline{12:03 \text{ pm}}$$

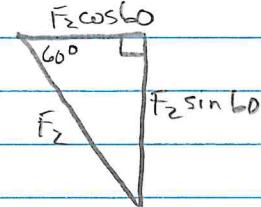
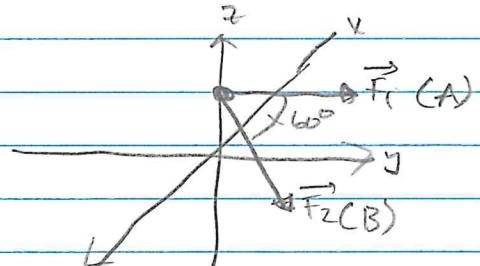
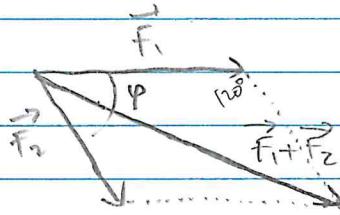
(b) What is its height at this time?

$$z(t) = 5 - t = \underline{4.95 \text{ km}}$$

1.2.34

$$\textcircled{a} \quad |\vec{F}_1| = 150$$

$$|\vec{F}_2| = 110$$



$$\textcircled{b} \quad \vec{F}_1 = (150, 0)$$

$$\vec{F}_2 = (110 \cos 60, 110 \sin 60)$$

$$= (55, 55\sqrt{3})$$

$$\text{Finding } \phi: \vec{F}_1 \cdot (\vec{F}_1 + \vec{F}_2) = |\vec{F}_1| |\vec{F}_1 + \vec{F}_2| \cos \theta$$

$$30750 = (150)(10\sqrt{511}) \cos \theta$$

$$\theta = \arccos(20.5 / \sqrt{511}) \approx \underline{0.435 \text{ rad}} \approx \underline{24.9^\circ}$$

HW #2

5/8

1.3.7

Volume of parallelepiped = determinant of matrix with vectors as its rows: $(2, 1, -1), (5, 0, -3)$, and $(1, -2, 1)$ go to:

$$\begin{vmatrix} 2 & 1 & -1 \\ 5 & 0 & -3 \\ 1 & -2 & 1 \end{vmatrix} = 2 \begin{vmatrix} 0 & -3 \\ -2 & 1 \end{vmatrix} - 1 \begin{vmatrix} 5 & -3 \\ 1 & 1 \end{vmatrix} - 1 \begin{vmatrix} 5 & 0 \\ 1 & -2 \end{vmatrix}$$

$$= 2(-6) - 1(8) + 10 = -10 \text{ units}^3$$

1.3.9

All unit vectors perpendicular to $(1, 1, 0) = \{(a, b, c) | a+b=0, \sqrt{a^2+b^2+c^2}=1\}$

1) obvious: $\vec{r} = (0, 0, 1)$.

2) less obvious: $\vec{r} = (r, -r, \sqrt{1-2r^2})$ for $0 < r \leq \frac{\sqrt{2}}{2}$

Finding vectors perpendicular to \vec{a}, \vec{b} : they're on the line $\vec{a} \times \vec{b}$!

$\vec{a} \times \vec{b} = \vec{c}$, so all unit vectors orthogonal to \vec{a}, \vec{b} are $\pm \vec{c}$.

1.3.10

Same idea as above. $\vec{x} = (-5, 9, 4)$, $\vec{y} = (7, 8, 9)$:

$$\vec{x} \times \vec{y} = \begin{pmatrix} -5 \\ 9 \\ 4 \end{pmatrix} \times \begin{pmatrix} 7 \\ 8 \\ 9 \end{pmatrix} = (49, 73, -103) = \vec{z}$$

Normalize: $|\vec{z}| \approx 135.4$ (exactly $\sqrt{18339}$)

\Rightarrow Vectors orthogonal to \vec{x}, \vec{y} are of the form

$$\underline{\frac{\pm 1}{\sqrt{18339}} (49, 73, -103)}$$

HW #2

6/8

T.3.13 $\vec{u} = (1, -2, 1)$ $\vec{v} = (2, -1, 2)$

$$\vec{u} + \vec{v} = (3, -3, 3)$$

$$\vec{u} \cdot \vec{v} = 1 \cdot 2 + (-2) \cdot (-1) + 1 \cdot 2 = 6$$

$$\|\vec{u}\| = \sqrt{6}$$

$$\|\vec{v}\| = 3$$

$$\vec{u} \times \vec{v} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} \times \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} = \begin{vmatrix} i & j & k \\ 1 & -2 & 1 \\ 2 & -1 & 2 \end{vmatrix} = (-3, 0, 3)$$

* (1.3.15)

$$\vec{n} = (A, B, C)$$

$$A(x-x_0) + B(y-y_0) + C(z-z_0) = 0$$

for planes!

Find eq of the plane that

- (a) is perpendicular to $\vec{n} = (1, 1, 1)$ and passes thru $(1, 0, 0)$

$$1(x-1) + 1(y-0) + 1(z-0) = 0$$

$$\underline{x+y+z=1}$$

- (b) perpendicular to $\vec{n} = (1, 2, 3)$, passes thru $(1, 1, 1)$

$$1(x-1) + 2(y-1) + 3(z-1) = 0$$

$$\underline{x+2y+3z=6}$$

- (c) perpendicular to $\vec{n} = (5, 0, 2)$ (we can just extract this from the line eq) and passes thru $(5, -1, 0)$

$$5(x-5) + 0(y+1) + 2(z-0) = 0$$

$$\underline{5x+2z=25}$$

- (d) $\vec{n} = (-1, -2, 3)$ thru $(2, 4, -1)$

$$-1(x-2) - 2(y-4) + 3(z+1) = 0$$

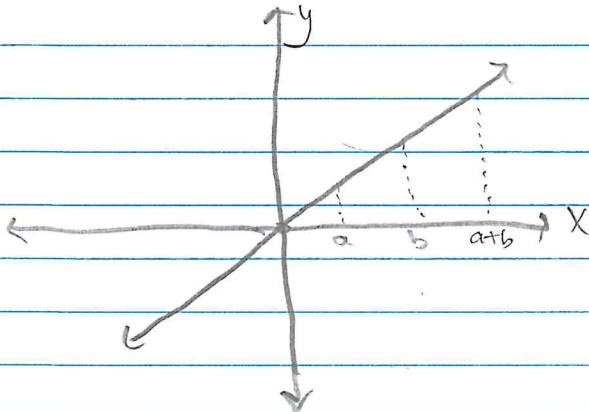
$$\underline{-x-2y+3z=-13}$$

Question #4

- (a) A line $\ell(t) = \vec{a} + t\vec{v}$, $\ell: \mathbb{R} \rightarrow \mathbb{R}^3$, is a linear transformation precisely when $\vec{a} = \vec{0}$, i.e. the line begins at the origin. We can show this using the definition of a linear transformation:

$$\begin{aligned} \ell(s+t) &= \ell(s) + \ell(t) \\ \vec{a} + (s+t)\vec{v} &= (\vec{a} + s\vec{v}) + (\vec{a} + t\vec{v}) \\ \vec{a} + s\vec{v} + t\vec{v} &= 2\vec{a} + s\vec{v} + t\vec{v} \Rightarrow \vec{a} = 2\vec{a}, \text{ so } \vec{a} = \vec{0}. \end{aligned}$$

This makes sense because linear transformations just scalar multiply or rotate vectors; they can't translate ("slide") them. Think about $\mathbb{R} \rightarrow \mathbb{R}$, i.e. $y = mx + b$:



We only have $y(a) + y(b) = y(a+b)$ when the y-intercept = 0.

- (b) Think about any vector $\vec{v} = (x, y) \in \mathbb{R}^2$. We can write this as a linear combination of the basis vectors: $\vec{v} = x\vec{i} + y\vec{j}$. That's cool because we can now harness the properties of linearity to figure out all of $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ if we just know $f(\vec{i})$ and $f(\vec{j})$:

$$\begin{aligned} \text{For arbitrary } \vec{v}, \quad f(\vec{v}) &= f(x\vec{i} + y\vec{j}) = f(x\vec{i}) + f(y\vec{j}) \\ &= x f(\vec{i}) + y f(\vec{j}) \quad !!! \end{aligned}$$

Let's say $f(\vec{i}) = \begin{pmatrix} c_1 \\ d_1 \end{pmatrix}$ and $f(\vec{j}) = \begin{pmatrix} c_2 \\ d_2 \end{pmatrix}$. Then, we can write: (next pg)

Question #4 ctd ..

$$\vec{v} = x f(\vec{e}) + y f(\vec{j}) = x \begin{pmatrix} c_1 \\ d_1 \end{pmatrix} + y \begin{pmatrix} c_2 \\ d_2 \end{pmatrix} = \begin{pmatrix} xc_1 + yc_2 \\ xd_1 + yd_2 \end{pmatrix}$$

Cool! How does that become a matrix? Well, let's reverse engineer it: what does a matrix product look like?

$$\begin{bmatrix} t & u \\ v & w \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} ta+ub \\ va+wb \end{bmatrix}$$

From here, we can see that
 $c_1 \leftrightarrow t, c_2 \leftrightarrow u, d_1 \leftrightarrow v, \text{ and } d_2 \leftrightarrow w,$

so we can write:

$$f\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{bmatrix} c_1 & c_2 \\ d_1 & d_2 \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

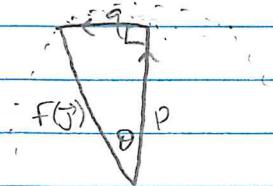
and, if you look closely,
you'll notice the matrix
is really just $[f(\vec{e}) \mid f(\vec{j})]!$

(C). Rotation counterclockwise by θ is a linear transformation
with

$$R_\theta(\vec{v}) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \vec{v}.$$

How do we know

that? Look at how it treats \vec{e}, \vec{j} :



$$p = \cos \theta |\vec{e}|$$

$$q = \cos \theta |\vec{j}|$$



$$\Rightarrow (1, 0) \mapsto (\cos \theta, \sin \theta)$$

$$p = \cos \theta |\vec{j}|$$

$$q = -\sin \theta |\vec{j}| \Rightarrow (0, 1) \mapsto (-\sin \theta, \cos \theta)$$

In the same way, look at how reflection over the x axis affects $(1, 0)$ and $(0, 1)$:

$$(1, 0) \mapsto (1, 0) \quad (0, 1) \mapsto (0, -1)$$

$$\text{so } F(\vec{v}) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \vec{v} = [F(\vec{e}) \mid F(\vec{j})]$$