

Solutions #6

1) a- T is invertible iff T is injective
iff $\text{null } T = \{0_V\}$
iff $\text{null } (T - 0) = \{0_V\}$
iff 0 is not an eigenvalue.

b- By symmetry, it will suffice to show that if λ is an eigenvalue for T , then λ^{-1} is one for T^{-1} . Now let x be an eigenvector corresp. to λ . So

$$Tx = \lambda x.$$

Mult. both sides by T^{-1} gives

$$\underbrace{T^{-1}T}_{I_V} x = \lambda T^{-1}x$$

This becomes $x = I_V x = \lambda T^{-1}x$ or

$$\lambda^{-1}x = T^{-1}x.$$

This proves the claim. (Note: we used part a) to ensure $\lambda \neq 0$ so that λ^{-1} exists!!).

2) For a contradiction, assume T has (at least) $k+2$ distinct eigenvalues... This means we have at least $k+1$ distinct non-zero eigenvalues. Let

$$\lambda_1, \dots, \lambda_{k+1}$$

be these values w/ corresponding eigenvectors

$$x_1, \dots, x_{k+1}.$$

By thm 4.4, these are linearly indep. It will now suffice to show $x_i \in \text{ran } T$. (why?)

To do this observe that

$$\lambda_i x_i = T x_i \in \text{ran } T.$$

As $\text{ran } T$ is closed under scalar mult. and λ_i^{-1} exists ($\lambda_i \neq 0$), then

$$x_i = \lambda_i^{-1} \lambda_i x \in \text{ran } T$$

as desired.

3) we wish to find all $x, y, z, \lambda \in \mathbb{C}$ so that

$$\lambda \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2y \\ 0 \\ 5z \end{bmatrix}.$$

This gives 3 equations:

$$\lambda x = 2y, \quad \lambda y = 0, \quad \lambda z = 5z.$$

$$\underline{\lambda = 0}$$

In this case, $z = 0$. Also $y = 0$, but x is free.

so $\left\{ \begin{bmatrix} x \\ 0 \\ 0 \end{bmatrix} \mid x \in \mathbb{R} \right\}$ are the corresp. vectors.

$$\underline{\lambda = 5}$$

Then $y = 0$, and in turn, $x = 0$. so z is free and

$\left\{ \begin{bmatrix} 0 \\ 0 \\ z \end{bmatrix} \mid z \in \mathbb{R} \right\}$ are the corresp. eigenvect.

These are the only solutions, since

$$\lambda x = 2y \Rightarrow \lambda^2 x = 2\lambda y = 0$$

so $\lambda = 0$ (first case) or $x = 0$ and $\lambda \neq 0$. Then $y = 0$

and the only way to have a non zero eigenvector is

$$\text{for } z \neq 0 \Rightarrow \lambda = 5.$$

b) Consider the mapping

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \mapsto \begin{bmatrix} -b \\ a \\ -d \\ c \end{bmatrix}$$

on $\mathbb{R}^4$. The same proof as the rotation example given in class works here.

4) Let (λ, X) be an eigenvalue for ST .

Case 1: $TX \neq 0_V$

Then $STX = \lambda X$, and mult both sides by T yields

$$TS(TX) = \lambda(TX)$$

So (λ, TX) is an eigenpair for TS .

Case 2: $TX = 0_V$

As $TX = 0_V$, then $STX = S0_V = 0_V = \lambda X$
so $\lambda = 0$ in this case. We must show $\lambda = 0$ is
an eigenvalue for TS . Now

0 is e.v. for TS iff TS is not injective $\iff$ (*)
iff TS is not surjective.

As T is not injective (why?) then it cannot be
surjective. Therefore TS cannot be surjective.
We conclude from (*) that 0 is an eigenvalue for
 TS .

5) a- Let $v \in V$ be non zero. Assume it is not an eigenvector.

Extend it to a basis $\{v_1, \dots, v_n\}$ where $v_1 = v$.

As v is not an eigenvector then

$$Tv = a_1 v_1 + \dots + a_n v_n$$

and some $a_i \neq 0$ for $i > 1$. wlog assume $a_n \neq 0$.

Now consider the $n-1$ dim space

$$U = \text{span}(v_1, \dots, v_{n-1}).$$

By what we just showed U is not T -invariant.

$\therefore$ Every nonzero vector is a T -eigenvector.

b- Assume $\lambda \neq \alpha$ are eigenvalues, w/ corresp vectors u, v . Then $T(u+v) = \lambda u + \alpha v$.

Since $u+v \neq 0_V$, then this shows $u+v$ is not an eigenvector, $\Rightarrow \Leftarrow$.