

$$\mathbb{H} = \{(x, y) : y > 0\}$$

$$ds^2 = \frac{dx^2 + dy^2}{y^2} \quad L(r) = \int_a^b \frac{\sqrt{x^2 + y^2}}{y} dt$$

$$\text{Isom}(\mathbb{H}) = \{f: \mathbb{H} \rightarrow \mathbb{H}, f^* ds^2 = ds^2\} \quad \uparrow \text{hyperbolic metric}$$

$$\cup \\ \text{Isom}^+(\mathbb{H}) = \{f \in \text{Isom}(\mathbb{H}), \underline{f \text{ preserves orientation}}\}$$

$$= \{T_r : r \in \text{SL}(2, \mathbb{R})\}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad a, b, c, d \in \mathbb{R}, ad - bc = 1.$$

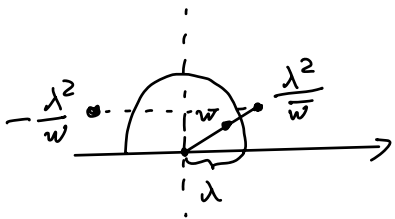
$$T_r(z) = \frac{az+b}{cz+d} = \begin{cases} \frac{az+b}{d} = \frac{a}{d}z + \frac{b}{d} & (c=0) \\ \frac{a}{c} - \frac{ad-bc}{c^2(z+\frac{d}{c})} & (c \neq 0) \end{cases}$$

translation    rescaling

$$z \xrightarrow{\text{translation}} z + \frac{d}{c} \xrightarrow{\text{translation}} -\frac{1}{c^2(z+\frac{d}{c})} \xrightarrow{\text{translation}} \frac{a}{c} - \frac{1}{c^2(z+\frac{d}{c})}$$

$$w \mapsto -\frac{\lambda^2}{w}$$

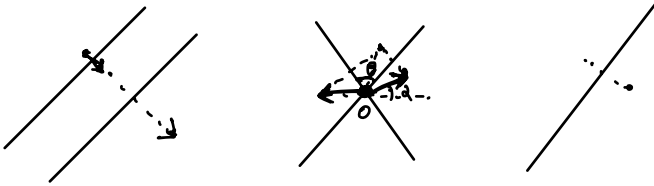
$$\begin{matrix} \text{inversion} \nearrow \\ \frac{\lambda^2}{w} \\ \searrow \text{reflection} \end{matrix}$$



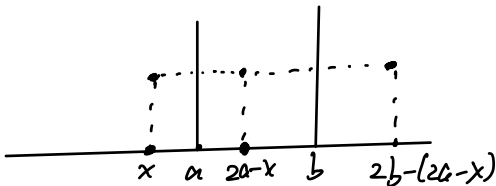
Thm: Any isometry of  $\mathbb{H}$  is composition of reflections.

Thm: Any isometry of  $\mathbb{R}^2$  is composition of reflections.  
 $\uparrow$   
 Euclidean plane

translation, rotation, reflection, glide reflection



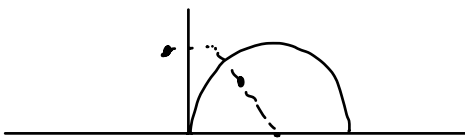
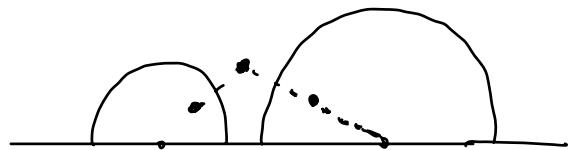
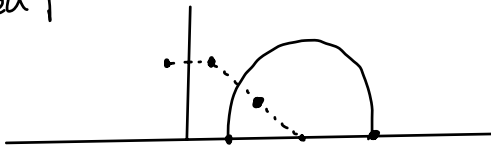
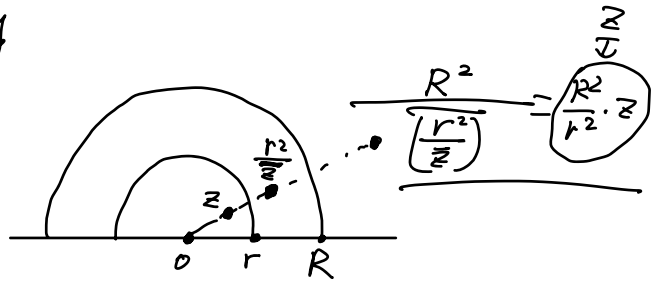
reflections in hyperbolic geometry



translations

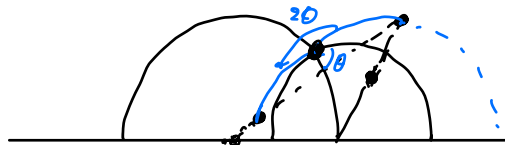
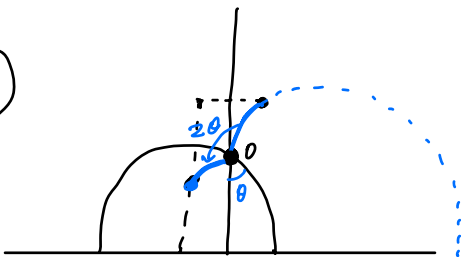
no fixed points

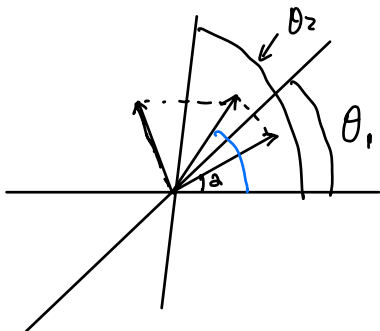
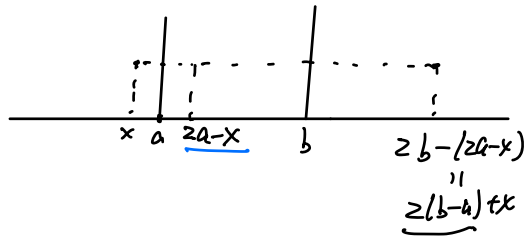
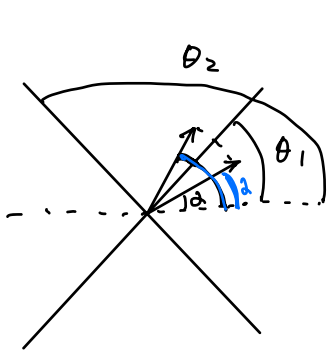
$$2(b-a)+x$$



1 fixed point

rotation





$$2(\theta_1 - \alpha) + \alpha = 2\theta_1 - 2\alpha + \alpha = 2\theta_1 - \alpha$$

$$\downarrow$$

$$2\theta_2 - (2\theta_1 - \alpha) = \underline{2(\theta_2 - \theta_1) + \alpha}$$

•  $\text{Isom}^+(\mathbb{H}) = \left\{ T_\gamma : \gamma = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{SL}(2, \mathbb{R}) \right\}$   
 $ad - bc = 1$ .

$$\frac{az+b}{cz+d} = z \iff az+b = (cz+d)z = cz^2 + dz$$

$$\iff c \cdot z^2 + (d-a)z - b = 0$$

$$z = \frac{-c \pm \sqrt{(d-a)^2 - 4c(-b)}}{2c} = \frac{-c \pm \sqrt{(d-a)^2 + 4bc}}{2c}$$

$T_\gamma$  has a fixed point in  $\mathbb{H} \iff$

$$(d-a)^2 + 4bc < 0$$

$\Downarrow$   
 $T_\gamma$  is a rotation

$$\left\{ z : \begin{array}{l} y > 0 \\ \parallel \\ x+iy \end{array} \right\}$$

$$\parallel \quad \parallel$$

$$x+iy \quad \text{Im}(z)$$

$(d-a)^2 + 4bc > 0 \implies T_\gamma$  has no fixed point in  $\mathbb{H}$

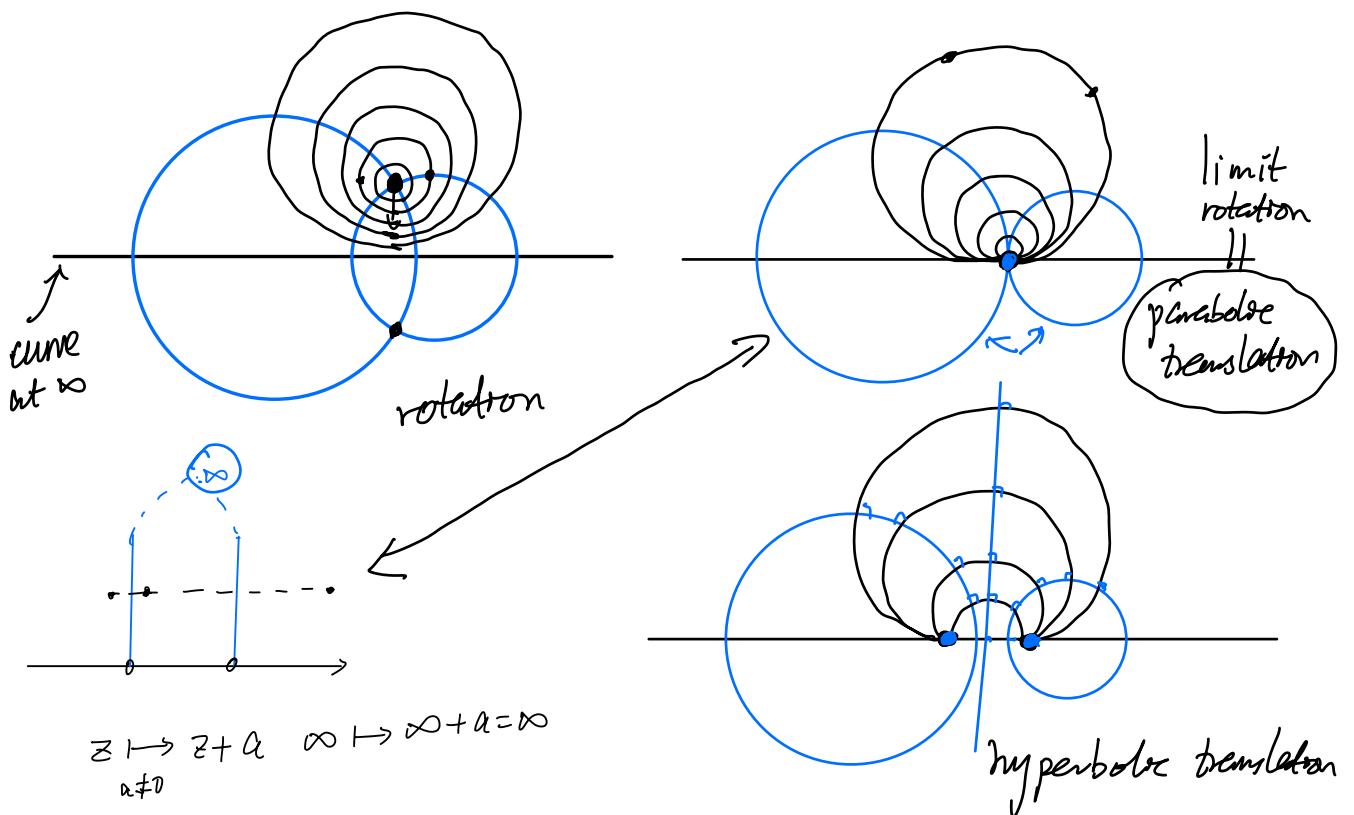
$T_\gamma$  has 2 fixed points on  $\mathbb{R} \cup \{\infty\}$

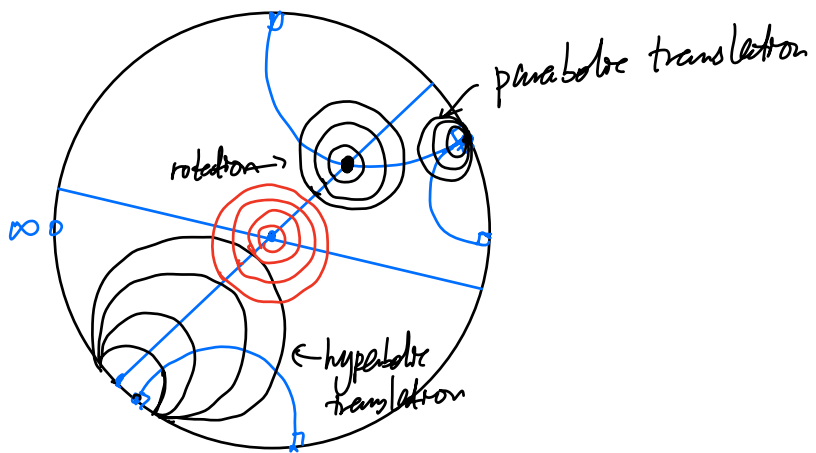
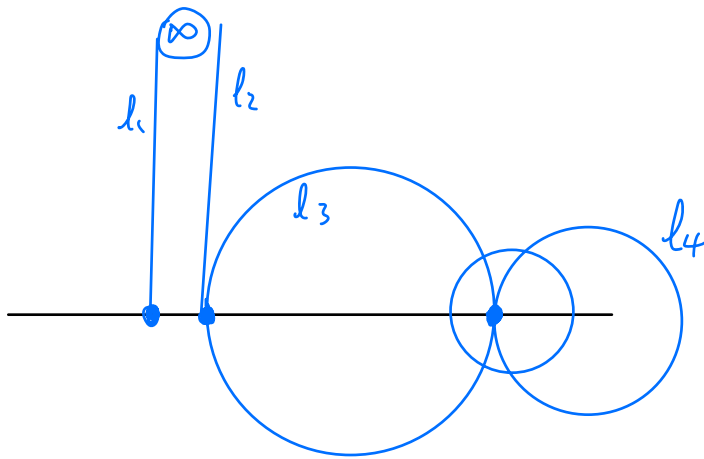
$\implies T_\gamma$  is translation (hyperbolic translation)

$(d-a)^2 + 4bc = 0 \implies T_\gamma$  has no fixed point in  $\mathbb{H}$

$T_\gamma$  has 1 fixed point on  $\mathbb{R} \cup \{\infty\}$

$T_\gamma$  is translation (parabolic translation)





Poincaré unit disk