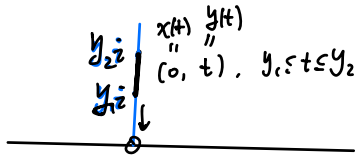
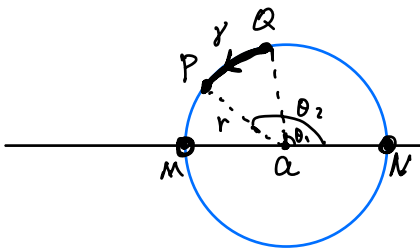


$$ds^2 = \frac{dx^2 + dy^2}{y^2}$$

$$L(\gamma) = \int_a^b ds = \int_a^b \frac{\sqrt{x'(t)^2 + y'(t)^2}}{y(t)} dt$$



$$L(\gamma) = \int_{y_1}^{y_2} \frac{\sqrt{0^2 + 1^2}}{t} dt = \ln t \Big|_{y_1}^{y_2} = \ln \frac{y_2}{y_1}$$



$$\begin{cases} x(t) = a + r \cdot \cos \theta & x'(t) = -r \cdot \sin \theta \\ y(t) = 0 + r \cdot \sin \theta & y'(t) = r \cdot \cos \theta \end{cases}$$

$$L(\gamma) = \int_{\theta_1}^{\theta_2} \frac{\sqrt{r^2 \sin^2 \theta + r^2 \cos^2 \theta}}{r \cdot \sin \theta} d\theta = \int_{\theta_1}^{\theta_2} \frac{d\theta}{\sin \theta} = \frac{\sin \theta d\theta}{\sin^2 \theta} = \frac{-d \cdot \cos \theta}{\sin \theta}$$

$$= - \int_{\theta_1}^{\theta_2} \frac{d \cdot \cos \theta}{1 - \cos^2 \theta} \stackrel{x = \cos \theta}{=} - \int_{\cos \theta_1}^{\cos \theta_2} \frac{dx}{1 - x^2} = \int \frac{dx}{1 - x^2} = \int \frac{1}{2} \left(\frac{1}{1+x} + \frac{1}{1-x} \right) dx$$

$$= \frac{1}{2} \ln \left| \frac{1+x}{1-x} \right| \Big|_{\cos \theta_2}^{\cos \theta_1} = \frac{1}{2} \ln \left| \frac{1+x}{1-x} \right|$$

$$\frac{1 + \cos \theta}{1 - \cos \theta} = \frac{2 \cdot \cos^2 \frac{\theta}{2}}{2 \cdot \sin^2 \frac{\theta}{2}} = \cot^2 \frac{\theta}{2}$$

$$= \ln \cot \frac{\theta}{2} \Big|_{\theta_2}^{\theta_1}$$

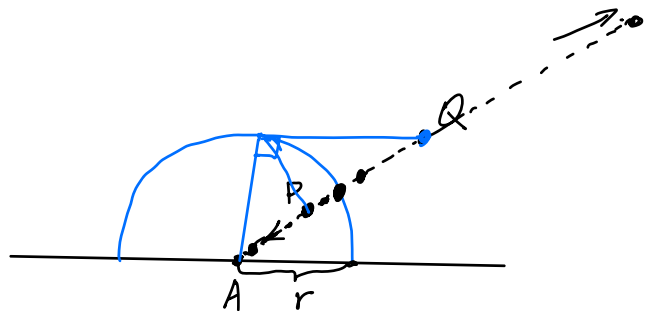
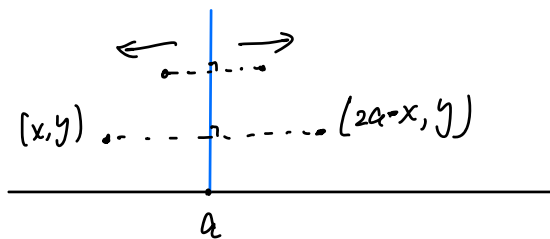
$$\frac{1}{2} \ln \left| \frac{1 + \cos \theta}{1 - \cos \theta} \right| = \ln \cot \frac{\theta}{2}$$

$$= \ln \frac{\cos \frac{\theta_1}{2}}{\cos \frac{\theta_2}{2}}$$

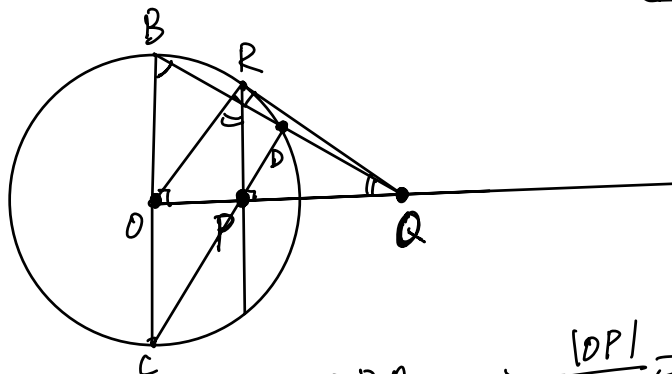
Isometry of hyperbolic upper half plane.

Euclidean: translation, rotation, reflection.

hyperbolic: ✓ ✓ ✓

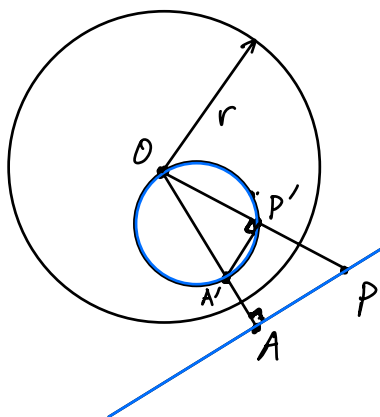


$$|AP| \cdot |AQ| = r^2$$



$$\triangle OPR \sim \triangle ORQ \Rightarrow \frac{|OP|}{|OR|} = \frac{|OR|}{|OQ|} \Rightarrow \underline{|OP| \cdot |OQ| = |OR|^2}$$

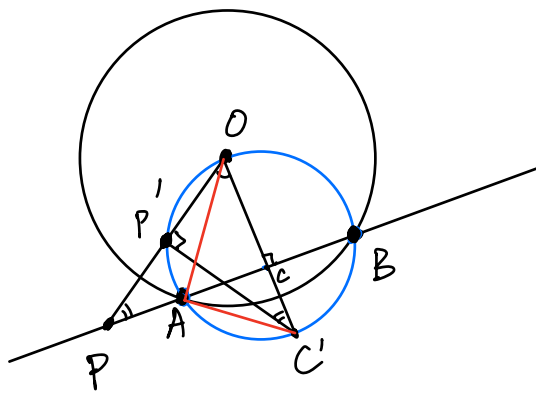
$$\triangle OBR \sim \triangle OPC \Rightarrow \frac{|OB|}{|OP|} = \frac{|OR|}{|OC|} \Rightarrow |OP| \cdot |OQ| = \frac{|OB| \cdot |OC|}{r^2}$$



$$\triangle OP'A' \sim \triangle OAP$$

$$\Rightarrow \frac{|OP'|}{|OA|} = \frac{|OA'|}{|OP|}$$

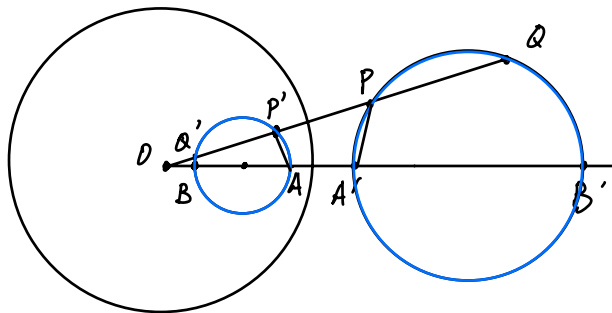
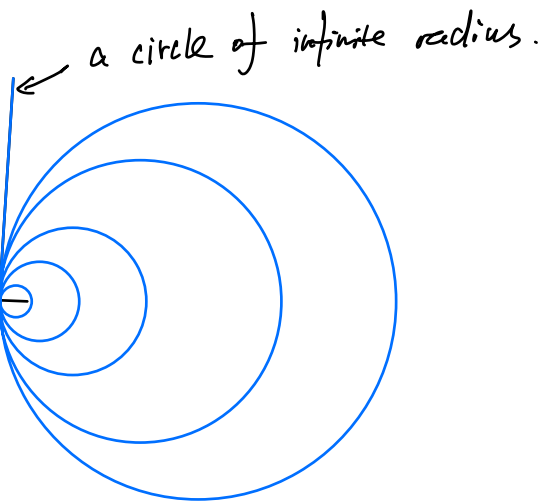
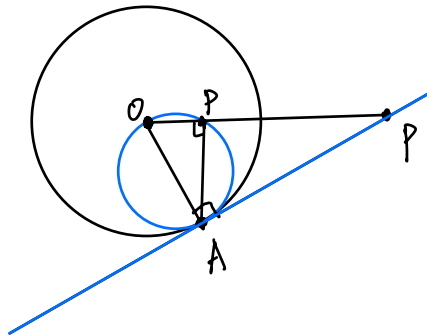
$$\Rightarrow |OP| \cdot |OP'| = |OA| \cdot |OA'| = r^2$$



$$\frac{|OP'|}{|OC'|} = \frac{|OC'|}{|OP|} \Rightarrow |OP'| \cdot |OP| = |OC'| \cdot |OC'| = r^2$$

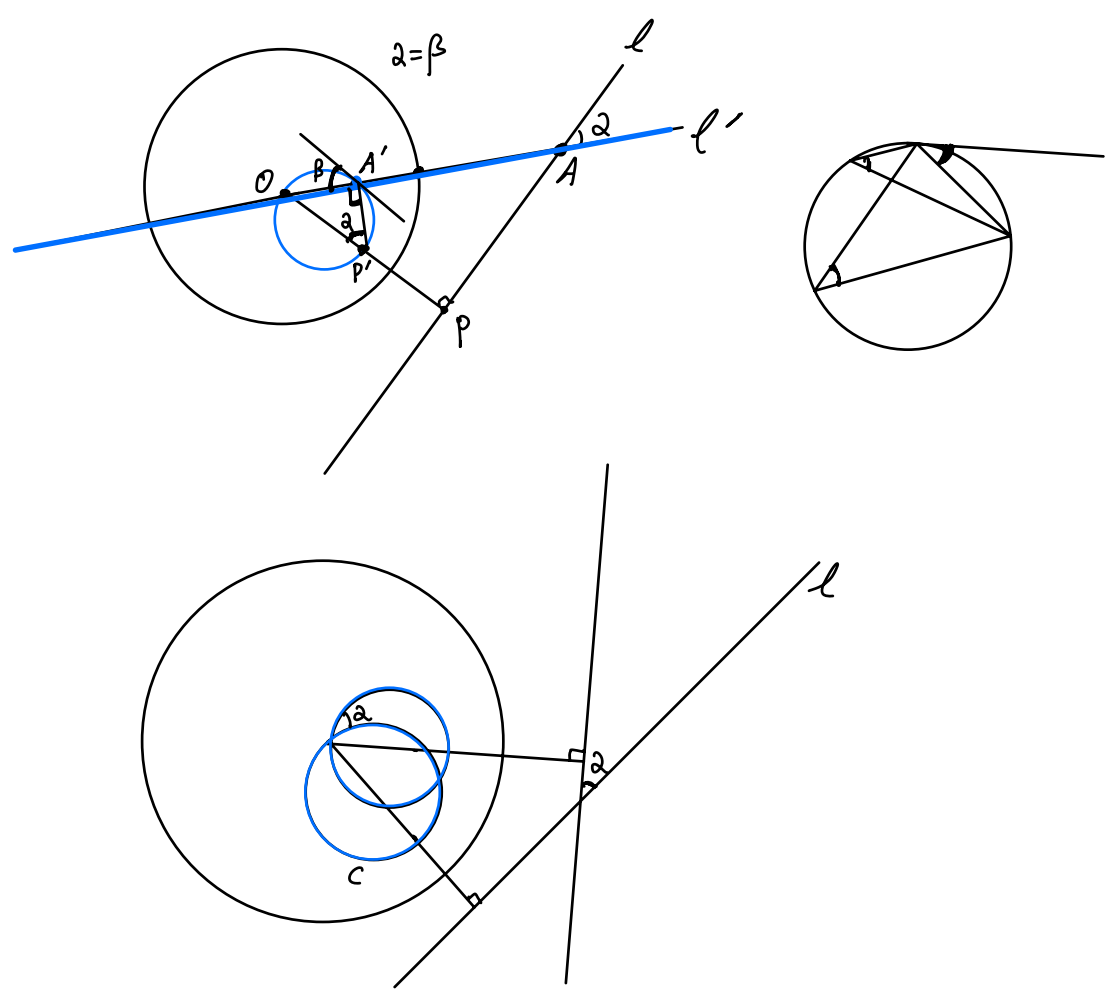
$\Delta O'P' \sim \Delta OPC$

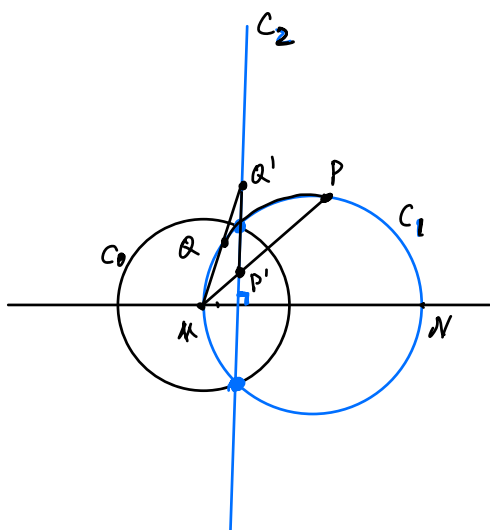
$$|OP| \cdot |OP'| = |OA|^2 = r^2.$$



1. Inversion maps circles to circles.
 (may be of infinite radius).

2. Inversion preserves angles.





geodesic = "shortest curves"

reflection = "inversion"