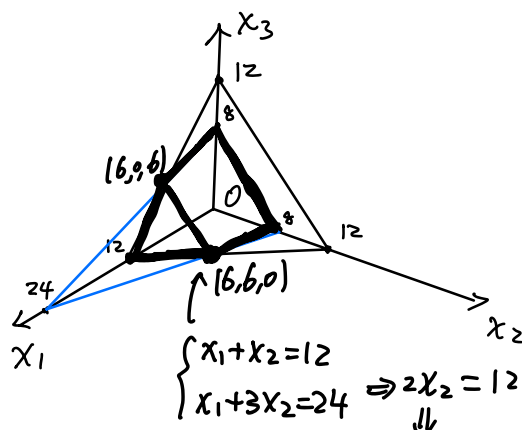


Maximize $Z = 2x_1 + 4x_2 + 3x_3$

Subject to $x_1 + x_2 + x_3 \leq 12$

$x_1 + 3x_2 + 3x_3 \leq 24$

$x_1 \geq 0, x_2 \geq 0, x_3 \geq 0.$



Extremal points:

$(12, 0, 0), (6, 6, 0), (6, 0, 6), (0, 8, 0), (0, 0, 8), (0, 0, 0)$ $x_2 = 6, x_1 = 6$

$\downarrow$
 $z = 24, 36, 36, 32, 32, 0$ $(6r + 6(1-r), 6r + 0, 0 + 6(1-r))$

Optimal solutions: $(6, 6, 0), (6, 0, 6)$. $r \cdot (6, 6, 0) + (1-r) \cdot (6, 0, 6)$

Maximum: 36

$(6, 6r, 6(1-r))$
 $0 \leq r \leq 1.$

$\Rightarrow$ Canonical Form: $x_1 + x_2 + x_3 + x_4 = 12$

$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 \\ 1 & 3 & 3 & 0 & 1 \end{pmatrix}$
 $\uparrow \uparrow$

$x_1 + 3x_2 + 3x_3 + x_5 = 24$

$x_i \geq 0, i = 1, \dots, 5.$

$(12, 0, 0) \longrightarrow (12, 0, 0, 0, 12)$

$(6, 6, 0) \longrightarrow (6, 6, 0, 0, 0)$

$(6, 0, 6) \longrightarrow (6, 0, 6, 0, 0)$

$(0, 0, 8) \longrightarrow (0, 0, 8, 4, 0)$

$(0, 0, 0) \longrightarrow (0, 0, 0, 12, 24)$

Def: (basic solution to $Ax = b$)

$A = (A_1 A_2 \dots A_n)$ $m \times n$ matrix.

$A_{i_1}, \dots, A_{i_m}$ (linearly independent) $\Rightarrow B = \underbrace{(A_{i_1} \dots A_{i_m})}_{m \times m}$

$$\begin{pmatrix} x_{B i_1} \\ x_{B i_2} \\ \vdots \\ x_{B i_m} \end{pmatrix} = x_B = B^{-1} b \quad (\Leftrightarrow B \cdot x_B = b).$$

$$\begin{matrix} x_1 \dots x_{i_1-1} & \boxed{x_{i_1}} & x_{i_1+1} \dots \dots \dots \boxed{x_{i_m}} & \dots \dots \dots \boxed{x_{i_m}} & \dots \end{matrix}$$

$$\rightsquigarrow (0, \dots, 0, x_{B i_1}, 0, \dots, 0, x_{B i_2}, \dots, x_{B i_m}, 0, \dots, 0)$$

Ex:

$$A = \begin{pmatrix} 1 & 1 & 1 & 1 & 0 \\ 1 & 3 & 3 & 0 & 1 \end{pmatrix} \quad B = (A_1 A_3) = \begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix}$$

$$\begin{matrix} \uparrow & \uparrow \\ \underline{A_1} & \underline{A_3} \end{matrix}$$

$$B \cdot x = b = \begin{pmatrix} 12 \\ 24 \end{pmatrix} \Rightarrow x_B = \begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 12 \\ 24 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 3 \end{pmatrix}^{-1} \cdot x = \frac{1}{2} \cdot \begin{pmatrix} 3 & -1 \\ -1 & 1 \end{pmatrix} \cdot \begin{pmatrix} 12 \\ 24 \end{pmatrix} = \begin{pmatrix} 6 \\ 6 \end{pmatrix}.$$

$$\Rightarrow x = \begin{pmatrix} 6 & 0 & 6 & 0 & 0 \end{pmatrix} \quad \begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \end{matrix} \Leftrightarrow (A_1 A_3)$$

$Bx = b$ feasible $x_i \geq 0$. basic feasible solution.

$\begin{matrix} \uparrow \\ \text{basic} \end{matrix}$ $\begin{matrix} \uparrow \\ x_i \geq 0 \end{matrix}$ $\text{feasible solution.} \leftarrow Ax = b.$

$$\underline{\text{Ex:}} \quad A = \begin{pmatrix} 2 & 3 & 1 & 0 & 0 \\ -1 & 1 & 0 & 2 & 1 \\ 0 & 6 & 1 & 0 & 3 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}.$$

$\uparrow \qquad \qquad \qquad \uparrow \quad 3 \times 5$

$$\underline{x = (1, 0, -1, 1, 0)}.$$

$$Ax = 1 \cdot \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} - 1 \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 2-1+0 \\ -1-0+2 \\ 0-1+0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \neq b.$$

$$\underline{x = (0, 2, -5, 0, 1)}$$

$$Ax = 2 \cdot \begin{pmatrix} 3 \\ 1 \\ 6 \end{pmatrix} - 5 \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - 1 \cdot \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 6-5-0 \\ 2-0-1 \\ 12-5-3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix} = b.$$

$$B = \begin{pmatrix} 3 & 1 & 0 \\ 1 & 0 & 1 \\ 6 & 1 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & -3 \\ 1 & 0 & 1 \\ 0 & 1 & -3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{pmatrix}$$

Not a basic solution.

$$\begin{matrix} x_1 & x_2 & x_3 & x_4 & x_5 \\ x = (0, 0, 1, 0, 1) \end{matrix}$$

$$Ax = 1 \cdot \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + 1 \cdot \begin{pmatrix} 0 \\ 1 \\ 3 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}$$

3 cases: ① x_1, x_2 : nonbasic variable.

$\underline{x_3, x_4, x_5}$: basic variables.

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 1 & 0 & 3 \end{pmatrix}$$

$\downarrow$

x is a basic solution

i.f. x_3, x_4, x_5 are basic variables. $\underline{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{pmatrix}}$ invertible

2. x_1, x_4 : nonbasic variable
 $\underline{x_2}, \underline{x_3}, \underline{x_5}$: basic variables.

$$A = \begin{pmatrix} 2 & 3 & 1 & 0 & 0 \\ -1 & 1 & 0 & 2 & 1 \\ 0 & 6 & 1 & 0 & 3 \end{pmatrix}$$

$$B = \begin{pmatrix} 3 & 1 & 0 \\ 1 & 0 & 1 \\ 6 & 1 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & -3 \\ 1 & 0 & 1 \\ 0 & 1 & -3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{rk} = 2 < 3$$

Not a basic solution if x_2, x_3, x_5 are basic var.

(3) x_2, x_4 : nonbasic var.

$$x = (0, 0, 1, 0, 1)$$

$\nwarrow$ $\nearrow$
 basic
 $\uparrow$ $\downarrow$
 nonbasic

$\underline{x_1}, \underline{x_3}, \underline{x_5}$: basic var.

$$B = \begin{pmatrix} 2 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & 1 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & 2 \\ 1 & 0 & -1 \\ 0 & 1 & 3 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{invertible}$$

$\Rightarrow x$ is a basic solution if x_1, x_3, x_5 are basic variables.

Thm: LPP in canonical form:

$$D = \{x \in \mathbb{R}^n : \underline{Ax = b}, x \geq 0\} = \text{set of feasible solution.}$$

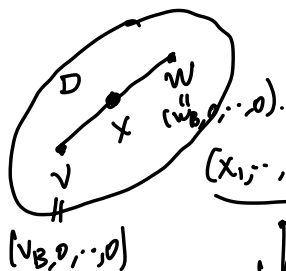
A point $x = (x_1, \dots, x_n) \in D$ is an extremal point.

if and only if it is a basic feasible solution.

Pf: basic feasible solution $\Rightarrow$ extremal point.

$$x = (x_1, \dots, x_m, 0, \dots, 0) \text{ solves } Bx = b, B = (A_1 A_2 \dots A_m). \\ x_i \geq 0, i=1, \dots, m.$$

WLOG



$$x = (1-t)v + t \cdot w \quad (0 < t < 1)$$

$$(x_1, \dots, x_m, 0, \dots, 0) = (1-t) \overset{R}{(v_1, \dots, v_m, v_{m+1}, \dots, v_n)} + t \cdot \overset{R}{(w_1, \dots, w_m, w_{m+1}, \dots, w_n)}$$

$$\begin{cases} (x_1, \dots, x_m) = (1-t)(v_1, \dots, v_m) + t(w_1, \dots, w_m) \\ (0, \dots, 0) = (1-t)(\underbrace{v_{m+1}, \dots, v_n}_0) + t(\underbrace{w_{m+1}, \dots, w_n}_0) \end{cases}$$

$$\underbrace{b = B \cdot x_B}_{\substack{\uparrow \\ \text{invertible}}} = B \cdot v_B = B \cdot w_B \Rightarrow v_B = x_B = w_B.$$

$$\Downarrow$$

$$v = x = w.$$

Extremal point of $D \Rightarrow$ basic feasible solution.

$$x = (\underbrace{x_1, \dots, x_k}_0, \underbrace{0, \dots, 0}_0) \Rightarrow \underbrace{A_1, \dots, A_k}_{\text{linearly independent}} \quad \text{Claim}$$

$$(A_1 \dots A_k \quad A_{k+1} \dots A_m) \begin{pmatrix} x_1 \\ \vdots \\ x_k \\ 0 \\ \vdots \\ 0 \end{pmatrix} = b$$

If not linearly independent. $c_1 A_1 + c_2 A_2 + \dots + c_k A_k = 0$

$c_i \neq 0$.

$$x_1 A_1 + x_2 A_2 + \dots + x_k A_k = b$$

$$\underbrace{(x_1 + c_1 \epsilon)}_0 A_1 + \underbrace{(x_2 + c_2 \epsilon)}_0 A_2 + \dots + \underbrace{(x_k + c_k \epsilon)}_0 A_k = b \quad |\epsilon| < 1.$$

