

!!! WRITE YOUR NAME, STUDENT ID. BELOW !!!

NAME :

ID :

1 (15pts) For each of the following subsets of \mathbb{R}^3 , determine whether it is a vector subspace of \mathbb{R}^3 . Explain your reason.

(1) $\{(a, b, c); a + 99b = 101c\} = S_1$

(2) $\{(a, b, c); a^2 - b^2 = 0\} = S_2$

(3) $\{(a, b, c); a^2 + b^2 = 0\} = S_3$

(1) Yes. $S_1 = N((1 \ 99 \ -101))$

$$= \{(a, b, c) : (1 \ 99 \ -101) \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0\}$$

(5)

(2) No. $S_2 = \{(a+b)(a-b)=0\} = \{a+b=0\} \cup \{a-b=0\}$

(5)

Not closed under addition e.g. $(1, -1) + (1, 1) = (2, 0) \notin S_2$.

\uparrow \uparrow
 S_2 S_2

(3) Yes. $S_3 = \{a=b=0\} = \{(0, 0, c) : c \in \mathbb{R}\} = \text{Span} \left\{ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

(5)

3(25pts) Consider the following subset S of $P_3(\mathbb{R})$.

$$S = \{1-x, x+x^2, x^2+x^3, 1+x^3\}$$

- (1) Is S linearly dependent or linearly independent?
 (2) Is $x+x^2+2x^3$ contained in $\text{Span}(S)$? Explain your reason.

(1) Choose standard basis $\beta = \{1, x, x^2, x^3\}$ for $P_3(\mathbb{R})$. Consider:

$$\begin{aligned} (2) \quad A &= \left(\begin{array}{cccc|c} (1-x)_\beta & (x+x^2)_\beta & (x^2+x^3)_\beta & (1+x^3)_\beta & (x+x^2+2x^3)_\beta \end{array} \right) \\ &= \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ -1 & 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 2 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 & 2 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & 1 & 2 \end{array} \right) \\ &\rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 2 & 2 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} 1 & 0 & 0 & 0 & -1 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right). \end{aligned}$$

$\Rightarrow S$ is linearly independent $\left(\begin{array}{l} \#S=4=\dim P_3(\mathbb{R}) \\ \Rightarrow S \text{ is a basis for } P_3(\mathbb{R}) \end{array} \right)$

and $x+x^2+2x^3$ is contained in $\text{Span}(S) = P_3(\mathbb{R})$

check: $-1 \cdot (1-x) + 0 \cdot (x+x^2) + 1 \cdot (x^2+x^3) + 1 \cdot (1+x^3)$

$$= (-1+1) + x + 1 \cdot x^2 + (1+1)x^3 = x + x^2 + 2x^3 \quad \checkmark$$

3(20pts) Let r_1, r_2, r_3 be row vectors in \mathbf{R}^3 . Find the value of k that satisfies the following equality:

$$\det \begin{pmatrix} 3r_1 + r_2 \\ r_1 + r_3 \\ r_1 + 2r_2 \end{pmatrix} = k \cdot \det \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix}$$

$$\begin{aligned} \det \begin{pmatrix} 3r_1 + r_2 \\ r_1 + r_3 \\ r_1 + 2r_2 \end{pmatrix} &= \det \begin{pmatrix} 3r_1 \\ r_1 + r_3 \\ r_1 + 2r_2 \end{pmatrix} + \det \begin{pmatrix} r_2 \\ r_1 + r_3 \\ r_1 + 2r_2 \end{pmatrix} \\ &= \det \begin{pmatrix} 3r_1 \\ r_3 \\ 2r_2 \end{pmatrix} + \det \begin{pmatrix} r_2 \\ r_1 + r_3 \\ r_1 \end{pmatrix} \\ &= 6 \cdot \det \begin{pmatrix} r_1 \\ r_3 \\ r_2 \end{pmatrix} + \det \begin{pmatrix} r_2 \\ r_3 \\ r_1 \end{pmatrix} \\ &= -6 \cdot \det \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} - \det \begin{pmatrix} r_2 \\ r_1 \\ r_3 \end{pmatrix} \\ &= -6 \det \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} + \det \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} = -5 \det \begin{pmatrix} r_1 \\ r_2 \\ r_3 \end{pmatrix} \\ &\Rightarrow k = -5. \end{aligned}$$

4(25pts) Let A be a real square matrix. Assume that v_1 and v_2 are two eigenvectors associated with two different eigenvalues $\lambda_1 \neq \lambda_2$. Prove that v_1, v_2 are linearly independent. What else can you say if moreover A is symmetric?

Proof: $Av_1 = \lambda_1 v_1$, $Av_2 = \lambda_2 v_2$, $\lambda_1 \neq \lambda_2$, $v_1 \neq 0, v_2 \neq 0$.

Assume $a_1 v_1 + a_2 v_2 = 0$. Then

$$0 = A(a_1 v_1 + a_2 v_2) = a_1 A(v_1) + a_2 A(v_2) = a_1 \lambda_1 v_1 + a_2 \lambda_2 v_2$$

$$\text{So: } \begin{cases} a_1 v_1 + a_2 v_2 = 0 \\ a_1 \lambda_1 v_1 + a_2 \lambda_2 v_2 = 0 \end{cases} \Rightarrow \begin{cases} a_1 \lambda_1 v_1 + a_2 \lambda_1 v_2 = 0 \\ a_1 \lambda_1 v_1 + a_2 \lambda_2 v_2 = 0 \end{cases}$$

$$\Rightarrow \underbrace{(a_2 \lambda_2 - a_2 \lambda_1)}_{\parallel} v_2 = 0 \xrightarrow{\lambda_1 \neq \lambda_2} a_2 \cdot v_2 = 0 \xrightarrow{v_2 \neq 0} a_2 = 0$$

$$a_2 (\lambda_2 - \lambda_1) v_2$$

$$\Rightarrow a_1 v_1 = 0 \xrightarrow{v_1 \neq 0} a_1 = 0.$$

So $\{v_1, v_2\}$ is linearly independent.

If A is symmetric, then v_1 is orthogonal to v_2 :

$$\text{Pf: } \langle Av_1, v_2 \rangle = (Av_1)^T v_2 = v_1^T A^T v_2 \stackrel{A^T=A}{=} v_1^T A v_2$$

$$\langle \lambda_1 v_1, v_2 \rangle = \lambda_1 \langle v_1, v_2 \rangle \quad \lambda_2 \langle v_1, v_2 \rangle = v_1^T (A v_2)$$

$$\Rightarrow (\lambda_2 - \lambda_1) \langle v_1, v_2 \rangle = 0 \xrightarrow{\lambda_1 \neq \lambda_2} \langle v_1, v_2 \rangle = 0.$$

5(25pts) (1) Use the Gram-Schmidt process to $\{1, x, x^2\}$ to find an orthonormal basis β of $P_2(\mathbb{R})$ with respect to the inner product $\langle f, g \rangle = \int_{-2}^2 f(x)g(x)dx$.

(2) Find the Fourier coefficients of $h(x) = x^2$ with respect to β .

$$(1) v_1 = w_1 = 1, \quad \|w_1\|^2 = \int_{-2}^2 1 \cdot 1 dx = 4 = \|v_1\|^2 \quad (5)$$

$$w_2 = x, \quad v_2 = w_2 - \frac{\langle w_2, v_1 \rangle}{\|v_1\|^2} v_1 \quad \langle w_2, v_1 \rangle = \int_{-2}^2 x \cdot 1 dx = \frac{x^2}{2} \Big|_{-2}^2 = 0.$$

$$\Rightarrow v_2 = x - \frac{0}{4} \cdot v_1 = x. \quad \|v_2\|^2 = \int_{-2}^2 x \cdot x dx = \frac{x^3}{3} \Big|_{-2}^2 = \frac{16}{3} \quad (5)$$

$$v_3 = w_3 - \frac{\langle w_3, v_1 \rangle}{\|v_1\|^2} v_1 - \frac{\langle w_3, v_2 \rangle}{\|v_2\|^2} v_2$$

$$\langle w_3, v_1 \rangle = \int_{-2}^2 x^2 \cdot 1 dx = \frac{x^3}{3} \Big|_{-2}^2 = \frac{16}{3}, \quad \langle w_3, v_2 \rangle = \int_{-2}^2 x^2 \cdot x dx = \frac{x^4}{4} \Big|_{-2}^2 = 0.$$

$$\Rightarrow v_3 = x^2 - \frac{\frac{16}{3}}{4} \cdot 1 = x^2 - \frac{4}{3} \quad (5)$$

$$\|v_3\|^2 = \int_{-2}^2 \left(x^2 - \frac{4}{3}\right)^2 dx = 2 \cdot \int_0^2 \left(x^4 - \frac{8}{3}x^2 + \frac{16}{9}\right) dx = 2 \cdot \left(\frac{x^5}{5} - \frac{8}{9}x^3 + \frac{16}{9}x\right) \Big|_0^2$$

even fun.

$$= 2 \cdot \left(\frac{32}{5} - \frac{64}{9} + \frac{32}{9}\right) = 64 \cdot \left(\frac{1}{5} - \frac{1}{9}\right) = \frac{256}{45} = \frac{16^2}{3^2} \cdot \frac{1}{5}$$

$$\Rightarrow u_1 = \frac{v_1}{\|v_1\|} = \frac{1}{2}, \quad u_2 = \frac{v_2}{\|v_2\|} = \frac{\sqrt{3}}{4} x, \quad u_3 = \frac{v_3}{\|v_3\|} = \frac{3\sqrt{5}}{16} \left(x^2 - \frac{4}{3}\right)$$

$$\text{form an orthonormal basis for } P_2(\mathbb{R}). \quad \sqrt{5} \left(\frac{3}{16}x^2 - \frac{1}{4}\right)$$

$$(2) \quad x^2 = x^2 - \frac{4}{3} + \frac{4}{3}$$

$$= \frac{16}{3\sqrt{5}} \cdot \frac{3\sqrt{5}}{16} \left(x^2 - \frac{4}{3}\right) + \frac{4 \cdot 2}{3} \cdot \frac{1}{2}$$

$$= \frac{16}{3\sqrt{5}} \cdot u_3 + \frac{8}{3} \cdot u_1$$

$$= \frac{8}{3} u_1 + 0 \cdot u_2 + \frac{16}{3\sqrt{5}} u_3$$

Fourier coefficients: $\frac{8}{3}$, 0 , $\frac{16}{3\sqrt{5}} = \frac{16}{15}\sqrt{5}$

\parallel \parallel \parallel
 $\langle h, u_1 \rangle$ $\langle h, u_2 \rangle$ $\langle h, u_3 \rangle$.

OR: $\langle h, u_1 \rangle = \frac{\langle h, v_1 \rangle}{\|v_1\|} = \frac{16}{3} \cdot \frac{1}{2} = \frac{8}{3}$

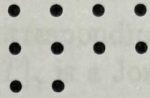
$$\langle h, v_1 \rangle = \int_{-2}^2 x^2 \cdot 1 \, dx = \left. \frac{x^3}{3} \right|_{-2}^2 = \frac{16}{3}$$

$$\langle h, u_2 \rangle = \frac{\langle h, v_2 \rangle}{\|v_2\|} = 0, \quad \langle h, v_2 \rangle = \int_{-2}^2 x^2 \cdot x \, dx = \left. \frac{x^4}{4} \right|_{-2}^2 = 0$$

$$\langle h, u_3 \rangle = \frac{\langle h, v_3 \rangle}{\|v_3\|} = \frac{\frac{256}{45}}{\frac{16}{3} \cdot \frac{1}{\sqrt{5}}} = \frac{16}{15} \sqrt{5}$$

$$\langle h, v_3 \rangle = \int_{-2}^2 x^2 \cdot \left(x^2 - \frac{4}{3}\right) dx = 2 \cdot \left[\frac{x^5}{5} - \frac{4}{9} x^3 \right]_0^2 = 64 \cdot \frac{4}{45} = \frac{256}{45}$$

7(25pts) Let A be a square matrix with characteristic polynomial equal to $(t-2)^{10}$. Assume that the dot diagram of A is the following:



- (1) Write down the Jordan canonical form of A .
- (2) Calculate $\dim R(A-2I)$ and $\dim R((A-2I)^2)$.

$$(1) \quad J(A) = \begin{pmatrix} \boxed{\begin{matrix} 2 & 1 \\ & 2 \end{matrix}} & & & \\ & \boxed{\begin{matrix} 2 & 1 \\ & 2 \end{matrix}} & & \\ & & \boxed{\begin{matrix} 2 & 1 \\ & 2 \end{matrix}} & \\ & & & \boxed{\begin{matrix} 2 & 1 \\ & 2 \end{matrix}} \end{pmatrix}$$

$$(2) \quad \dim N(A-2I) = \# \text{ dots in 1st. row} = 4 \quad \textcircled{4}$$

$$\dim N(A-2I)^2 = \# \text{ dots in first 2 rows} = 8 \quad \textcircled{4}$$

$$\Rightarrow \dim R(A-2I) = 10 - \dim N(A-2I) = 10 - 4 = 6 \quad \textcircled{4}$$

$$\dim R(A-2I)^2 = 10 - \dim N(A-2I)^2 = 10 - 8 = 2. \quad \textcircled{4}$$

8(25pts) Consider the linear transformation:

$$T : P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R}), \quad T(f(x)) = f''(x) + f'(x) + f(0).$$

- (1) Find all eigenvalues of T and the corresponding dot diagrams.
- (2) Find a basis γ of $P_2(\mathbb{R})$ such that $[T]_\gamma$ is a Jordan canonical form.

(2) + (1) $\beta = \{1, x, x^2\}$ standard basis for $P_2(\mathbb{R})$.

$$[T]_\beta = \begin{pmatrix} [T(1)]_\beta & [T(x)]_\beta & [T(x^2)]_\beta \end{pmatrix} = \begin{pmatrix} [1]_\beta & [1]_\beta & [2+2x]_\beta \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} = A$$

$$|A - \lambda I| = \begin{vmatrix} 1-\lambda & 1 & 2 \\ 0 & -\lambda & 2 \\ 0 & 0 & -\lambda \end{vmatrix} = \lambda^2(1-\lambda) = 0 \Rightarrow \begin{matrix} \lambda=0, m_0=2 \\ \lambda=1, m_1=1 \end{matrix}$$

$$\lambda=0: A - 0I = \begin{pmatrix} 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow E_0 = \text{Span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \right\}$$

$\dim E_0 = 1 \Rightarrow$ dot diagram for $\lambda=0$: $\begin{matrix} \bullet v_1 \\ \bullet v_2 \end{matrix}$

choose $v_1 = \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix}$ solve: $(A - 0I)v_2 = v_1$:

$$\begin{pmatrix} 1 & 1 & 2 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & -1 \\ 0 & 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 0 & -\frac{3}{2} \\ 0 & 0 & 1 & \frac{1}{2} \\ 0 & 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{choose } v_2 = \begin{pmatrix} -2 \\ 0 \\ \frac{1}{2} \end{pmatrix}$$

$$\lambda=1: A - 1I = \begin{pmatrix} 0 & 1 & 2 \\ 0 & -1 & 2 \\ 0 & 0 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} 0 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \Rightarrow E_1 = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\} \Rightarrow \bullet v_3$$

\Rightarrow Jordan canonical basis $\gamma = \left\{ \overset{f_1}{-1+x}, \overset{f_2}{-2+\frac{1}{2}x^2}, \overset{f_3}{1} \right\}$ satisfies

$$[T]_\gamma = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

check $T(-1+x) = 0 + 1 + (-1) = 0 \cdot f_1$
 $T(-2 + \frac{1}{2}x^2) = 1 + x - 2 = x - 1 = 1 \cdot f_1 + 0 \cdot f_2 \checkmark$
 $T(1) = 1 = 1 \cdot f_3$

9(20pts) Find the linear function $f(t) = c_0 + c_1 t$ that has the best fit to the data:

$$\{(0,0), (1,2), (2,1), (3,-1), (4,0)\} = \{(t_i, y_i); 1 \leq i \leq 5\}.$$

with respect to the error: $E = \sum_{i=1}^5 (c_0 + c_1 t_i - y_i)^2$.

$$\text{Set } A = \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{pmatrix} \quad y = \begin{pmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{pmatrix} = \begin{pmatrix} 5 & 10 \\ 10 & 30 \end{pmatrix} = 5 \cdot \begin{pmatrix} 1 & 2 \\ 2 & 6 \end{pmatrix}$$

\uparrow
 $1+4+9+16$

$$(A^T A)^{-1} = \frac{1}{5} \cdot \frac{1}{6-4} \begin{pmatrix} 6 & -2 \\ -2 & 1 \end{pmatrix} = \frac{1}{10} \begin{pmatrix} 6 & -2 \\ -2 & 1 \end{pmatrix}.$$

$$A^T y = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} = \frac{1}{10} \begin{pmatrix} 6 & -2 \\ -2 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \frac{1}{10} \begin{pmatrix} 10 \\ -3 \end{pmatrix} = \begin{pmatrix} 1 \\ -\frac{3}{10} \end{pmatrix}$$

$\Rightarrow f(t) = 1 - \frac{3}{10} t$ has the best fit to the data.

8(20pts) Find the linear function $f(t) = c_0 + c_1 t$ that has the best fit to the data:

$$\{(0, 0), (1, 2), (2, 1), (3, -1), (4, 0)\} = \{(t_i, y_i); 1 \leq i \leq 5\}.$$

with respect to the error: $\mathbf{E} = \sum_{i=1}^5 (c_0 + c_1 t_i - y_i)^2$.

$$E = \left\| \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \begin{pmatrix} t_1 \\ t_2 \\ t_3 \\ t_4 \\ t_5 \end{pmatrix} \begin{pmatrix} c_0 \\ c_1 \end{pmatrix} - \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \end{pmatrix} \right\|^2 = \|A \cdot v - y\|^2.$$

Find orthogonal projection of y to column space of A

Use Gram-Schmidt: $\text{Span} \left\{ \underbrace{\begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}}_{w_1}, \underbrace{\begin{pmatrix} 0 \\ 2 \\ 3 \\ 4 \end{pmatrix}}_{w_2} \right\}$

$$v_1 = w_1, \|v_1\|^2 = 5, \langle w_2, v_1 \rangle = 10.$$

$$v_2 = w_2 - \frac{\langle w_2, v_1 \rangle}{\|v_1\|^2} v_1 = \begin{pmatrix} 0 \\ 2 \\ 3 \\ 4 \end{pmatrix} - \frac{10}{5} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ -1 \\ 0 \\ 2 \end{pmatrix}, \|v_2\|^2 = 4 + 1 + 1 + 4 = 10$$

$$\Rightarrow u_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{5}} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}, u_2 = \frac{1}{\sqrt{10}} \begin{pmatrix} -2 \\ -1 \\ 0 \\ 2 \end{pmatrix}, y = \begin{pmatrix} 0 \\ 2 \\ 1 \\ -1 \\ 0 \end{pmatrix}, \langle y, u_1 \rangle = \frac{1}{\sqrt{5}} \cdot 2$$

$$\langle y, u_2 \rangle = \frac{1}{\sqrt{10}} \cdot (0 - 2 + 0 - 1 + 0) = -\frac{3}{\sqrt{10}}$$

$$\text{Orthogonal Projection: } \langle y, u_1 \rangle u_1 + \langle y, u_2 \rangle u_2 = \frac{1}{5} \cdot 2 \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{3}{10} \cdot \begin{pmatrix} -2 \\ -1 \\ 0 \\ 2 \end{pmatrix} = \frac{1}{10} \begin{pmatrix} 10 \\ 7 \\ 4 \\ -1 \\ -2 \end{pmatrix} = y_1$$

Solve $A \cdot v = y_1$

$$\left(\begin{array}{cc|c} 1 & 0 & 10 \\ 1 & 1 & 7 \\ 1 & 2 & 4 \\ 1 & 3 & 1 \\ 1 & 4 & -2 \end{array} \right) = \left(\begin{array}{cc|c} 1 & 0 & 10 \\ 0 & 1 & -3 \\ 0 & 2 & -6 \\ 0 & 3 & -9 \\ 0 & 4 & -12 \end{array} \right) \Rightarrow v = \frac{1}{10} \begin{pmatrix} 10 \\ -3 \end{pmatrix} \Rightarrow y = \frac{1}{10} (10 - 3t) \text{ is the best linear approximation.}$$

9(20pts) Let $S : V \rightarrow W$ and $T : W \rightarrow V$ be linear transformations between two vector spaces V and W . Let $T \circ S : V \rightarrow V$ be the composition.

- (1) Prove that if S is surjective (i.e. onto), then $\text{Rank}(T \circ S) = \text{Rank}(T)$.
- (2) If S is injective (i.e. one-to-one), is $\text{Rank}(T \circ S) = \text{Rank}(T)$ always true? Prove this statement or find a counterexample.

(1) Proof: $\text{Rank}(T \circ S) = \dim R(T \circ S)$.

$$\begin{aligned} \text{If } S \text{ is onto, then } R(T \circ S) &= \{T \circ S(v) = T(S(v)) : v \in V\} \\ &= \{T(w) : w \in W\} = R(T) \end{aligned}$$

$$\Rightarrow \dim R(T \circ S) = \dim R(T) = \text{Rank}(T).$$

(2) Not always true.

Example: $S : \mathbb{R} \rightarrow \mathbb{R}^2$, $T = \text{Id} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $x \mapsto (x, 0)$ $(x, y) \mapsto (x, y)$

$$\text{Rank}(T \circ S) = 1 < \text{Rank}(T) = 2.$$