

Thm: If $V = \text{Span}(S)$ and $\#S$ is finite. Then
 $\uparrow$
 number of vectors in S

There is a subset of S that is a basis for V .

Pf: Assume $S = \{v_1, \dots, v_n\}$ $v_i \neq v_j$ if $i \neq j$.

We construct a subset of S by the following process:

step 1: if $v_1 \neq 0$, then set $S_1 = \{v_1\}$, otherwise set $S_1 = \emptyset$.

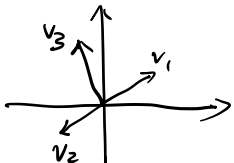
step 2: if $v_2 \notin \text{Span}(S_1)$, then set $S_2 = S_1 \cup \{v_2\}$. Otherwise set $S_2 = S_1$.

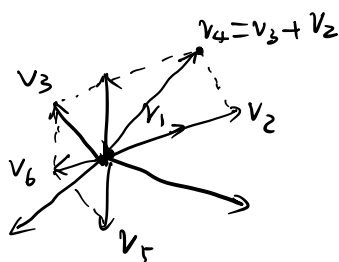
step 3: if $v_3 \notin \text{Span}(S_2)$, then set $S_3 = S_2 \cup \{v_3\}$, Otherwise set $S_3 = S_2$.

$\vdots$
step n: if $v_n \notin \text{Span}(S_{n-1})$, then set $S_n = S_{n-1} \cup \{v_n\}$. Otherwise set $S_n = S_{n-1}$.

At each step, we get a linearly independent subset. and $\text{Span}(S_n) = \text{Span}(S)$
 $\uparrow$
 $\checkmark$

So S_n is a basis for V .

Ex:  $S = \{v_1, v_2, v_3\} \rightarrow S_1 = \{v_1\}, S_2 = \{v_1\}, S_3 = \{v_1, v_2\}$
 $\uparrow$
 basis for $\mathbb{R}^3$.



$S = \{v_1, v_2, v_3, v_4, v_5\}$

$S_1 = \{v_1\}, S_2 = \{v_1\}, S_3 = \{v_1, v_3\}, S_4 = \{v_1, v_3\}$

$S_5 = \{v_1, v_3, v_5\}, S_6 = \{v_1, v_3, v_5\}$
 $\uparrow$
 a basis for $\mathbb{R}^3$.

We assume that V is spanned by a finite subset.

Thm A: Any two bases for a vector space contain the same number of vectors.

We can now define $\dim V = \# \beta$ if β is a basis for V .
 $\# \beta'$ for any other basis β'

V is spanned by a finite subset $\Rightarrow \dim V < \infty$ (finite dimension)

Thm B. 1. If $V = \text{Span}(S)$, then $\#S \geq \dim V$

2. If $V = \text{Span}(S)$ and $\#S = \dim V$, then S is a basis

3. If S is linearly independent and $\#S = \dim V$, then S is a basis.

4. If S is linearly independent then $\#S \leq \dim V$.

Moreover S can be extended to become a basis for V .

(i.e. $\exists u_1, \dots, u_k \in V$ s.t. $S \cup \{u_1, \dots, u_k\}$ is a basis)

Ex: We can use Thm B.3 to verify whether a subset is a basis or not

For example, let $S = \left\{ \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ -4 \\ -3 \end{pmatrix}, \begin{pmatrix} -3 \\ 8 \\ 2 \end{pmatrix} \right\}$, $\#S = 3$.

To check whether S is a basis or not, just need to check whether S is linearly independent.
 S is linearly independent iff the following system has only 0 solution.

$$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = a_1 \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} 2 \\ -4 \\ -3 \end{pmatrix} + a_3 \begin{pmatrix} -3 \\ 8 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 & 2 & -3 \\ 3 & -4 & 8 \\ 1 & -3 & 2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$$

Use Gauss-Elimination method:

$$\begin{pmatrix} -1 & 2 & -3 \\ 3 & -4 & 8 \\ 1 & -3 & 2 \end{pmatrix} \xrightarrow[\textcircled{1} + \textcircled{3}]{\textcircled{1} \cdot 3 + \textcircled{2}} \begin{pmatrix} -1 & 2 & -3 \\ 0 & 2 & -1 \\ 0 & -1 & -1 \end{pmatrix} \xrightarrow[\textcircled{2} \leftrightarrow \textcircled{3}]{\textcircled{2} \cdot 2 + \textcircled{1}} \begin{pmatrix} -1 & 2 & -3 \\ 0 & -1 & -1 \\ 0 & 0 & -3 \end{pmatrix} \Rightarrow \text{no free variables}$$

$\downarrow$
only zero solution

So S is linearly indep. and $\# S = 3 = \dim \mathbb{R}^3$

$$\begin{cases} -a_1 + a_2 - 3a_3 = 0 \\ -a_2 - a_3 = 0 \\ -3a_3 = 0 \end{cases} \Rightarrow a_3 = a_2 = a_1 = 0.$$

$\# \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

By Thm B.3, S is indeed a basis.

Ex: $V = P_2(\mathbb{R})$,

$$S = \{-1 + 3x + x^2, 2 - 4x - 3x^2, -1 + 5x\}$$

check whether S is lin. indep or not: Find if there are nontrivial rep. of 0.

$$\begin{aligned} 0 &= a_1(-1 + 3x + x^2) + a_2(2 - 4x - 3x^2) + a_3(-1 + 5x) \\ &= (-a_1 + 2a_2 - a_3) + (3a_1 - 4a_2 + 5a_3)x + (a_1 - 3a_2)x^2 \end{aligned}$$

$$\Leftrightarrow \begin{pmatrix} -1 & 2 & -1 \\ 3 & -4 & 5 \\ 1 & -3 & 0 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} -1 & 2 & -1 \\ 3 & -4 & 5 \\ 1 & -3 & 0 \end{pmatrix} \xrightarrow[\textcircled{1} + \textcircled{3}]{\textcircled{1} \cdot 3 + \textcircled{2}} \begin{pmatrix} -1 & 2 & -1 \\ 0 & 2 & 2 \\ 0 & -1 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 2 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

$\exists$ free variable $\downarrow$ non zero solution

$\Rightarrow S$ is not linearly indep. $\Rightarrow S$ is not a basis for V .

Mother Thm (Replacement Theorem).

Assume: $\bullet V = \text{Span}(G), \quad G = n$

• L is linearly independent subset of V , $\# L = m$.

Then conclusions: • $n \geq m$

- $\exists (n-m)$ vectors (distinct) $v_1, \dots, v_{n-m}$ of G

s.t. $LU\{v_1, \dots, v_{n-m}\}$ spans V .

In other words, if we write $G = \{v_1, \dots, v_{n-m}, u_1, \dots, u_m\}$.

Then if we replace $\{u_1, \dots, u_m\}$ of G by L , we still get a spanning subset $\{v_1, \dots, v_{n-m}\} \cup L$.

the Replacement Then implies Then A, Then B. 1-4.

For example: Pf. of Thm A: Let β_1, β_2 be two bases.

$G \leftarrow \beta_1 \Rightarrow \# \beta_1 \geq \# \beta_2$ Changing the row of β_1, β_2 . Let $\# \beta_2 \geq \# \beta_1$
 $L \leftarrow \beta_2$ so $\# \beta_1 = \# \beta_2$

pf of Thm B.4: S linearly independent. let β be a basis.

$$\begin{array}{l} G \leftarrow \beta \\ L \leftarrow S \end{array} \xrightarrow[\text{Then}]{\text{Replacement}} \begin{array}{l} \# \beta \geq \# S. \text{ and } \exists \{v_1, \dots, v_{n-m}\} \subseteq \beta \text{ s.t.} \\ // \quad // \\ n \quad m \\ S \cup \{v_1, \dots, v_{n-m}\} \text{ is a basis.} \end{array}$$

Proof of the Replacement Thm: Induction on m .

• When $m=0$, $L=\emptyset$, $\emptyset \cup C_1 = C_1$ spans V .
 $\uparrow$ $\uparrow$
 empty set. $\#C_1 = n = n-0$

• Assume that the Thm is already proved for $m-1$, for $m \geq 1$.

Want to prove the conclusion when $\#L=m$.

Write $L = L_1 \cup \{u\}$ with $\#L_1 = m-1$, and $u \notin \text{Span}(L_1)$.

By the induction assumption, there exist $\{v_1, \dots, v_{n-(m-1)}\} \subseteq C_1$
 $n \geq m-1$.

Set. $L_1 \cup \{v_1, \dots, v_{n-m+1}\}$ spans V .

In particular, $u \in \text{Span}(L_1 \cup \{v_1, \dots, v_{n-m+1}\})$. So $\exists u_1, \dots, u_k \in L_1$ s.t.
 $a_1, \dots, a_k \in F$

$$u = a_1 u_1 + \dots + a_k u_k + b_1 v_1 + \dots + b_{n-m+1} v_{n-m+1} \quad \text{and } b_1, \dots, b_{n-m+1} \in F$$

If $n-(m-1)=0$, then $u \in \text{Span}\{u_1, \dots, u_k\} \subseteq \text{Span}(L_1)$ contradicting $u \notin \text{Span}(L_1)$

so $n-(m-1) > 0 \Rightarrow n \geq m$. and $b_1, \dots, b_{n-m+1}$ not all 0.

By reordering $v_1, \dots, v_{n-m+1}$, we can assume that $b_{n-m+1} \neq 0$.

$$\text{then } v_{n-m+1} = b_{n-m+1}^{-1} (-u + a_1 u_1 + \dots + a_k u_k + b_1 v_1 + \dots + b_{n-m} v_{n-m})$$

implies $\underline{v_{n-m+1}} \in \text{Span}\{u, u_1, \dots, u_k, v_1, \dots, v_{n-m}\}$

$$\text{so } \text{span}\{L_1 \cup \{v_1, \dots, \underline{v_{n-m+1}}\}\} \subseteq \text{Span}\{L_1 \cup \{u\} \cup \{v_1, \dots, v_{n-m}\}\}$$

$$\quad \quad \quad \parallel \quad \quad \quad \parallel$$

$$\quad \quad \quad V \quad \quad \quad \text{Span}\{L \cup \{v_1, \dots, v_{n-m}\}\}$$

$$\Rightarrow \text{Span}(L \cup \{v_1, \dots, v_{n-m}\}) = V \quad \text{as wanted} \quad \blacksquare$$