Solutions for Practice Test IB, Math 291 Spring 2011

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Let a = (1, 1, 1)
(a) Find a vector x such that

 $\mathbf{x} \times \mathbf{a} = (-7, 2, 5)$ and $\mathbf{x} \cdot \mathbf{a} = 0$.

(b) There is no vector **x** such that

 $\mathbf{x} \times \mathbf{a} = (1, 0, 0)$ and $\mathbf{x} \cdot \mathbf{a} = 0$.

Show that no such vector exists.

SOLUTION: For any vector **x**,

$$\mathbf{a} \times (\mathbf{a} \times \mathbf{x}) = -\|\mathbf{a}\|^2 \mathbf{x}_{\perp} ,$$

where \mathbf{x}_{\perp} is the component of \mathbf{x} orthogonal to \mathbf{a} . If $\mathbf{x} \cdot \mathbf{a} = 0$, this reduces to

$$\mathbf{x} = -\frac{1}{\|\mathbf{a}\|^2} (\mathbf{x} \times \mathbf{a}) \times \mathbf{a} = -\frac{1}{3} (-7, 2, 5) \times (1, 1, 1) = (-1, 4, -3) .$$

For (b), note that (1, 0, 0) is not orthogonal to **a**, and hence no vector can satisfy $\mathbf{x} \times \mathbf{a} = (1, 0, 0)$ since the cross product of two vectors is orthogonal to each of them.

2: Let P_1 denote the plane through the three points $\mathbf{a_1} = (1, 2, 1)$ $\mathbf{a_2} = (-1, 2, -3)$ and $\mathbf{a_3} = (2, -3, -2)$. Let P_2 denote the plane through the three points $\mathbf{b_1} = (1, 1, 0)$ $\mathbf{b_2} = (1, 0, 1)$ and $\mathbf{b_3} = (0, 1, 1)$.

(a) Find equations for the planes P_1 and P_2 .

(b) Parameterize the line given by $P_1 \cap P_2$, and find the distance between this line and the point \mathbf{a}_1 .

(c) Consider the line through $\mathbf{b_1}$ and $\mathbf{b_2}$. Determine the point of intersection of this line with the plane P_1 , and find a parametrization of the line given by reflecting this line off plane P_1 . That is, the direction vector of the reflected line is what you get by reflecting the direction vector of the original line using the unit normal direction \mathbf{u} to the plane.

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SOLUTION: We compute

$$(\mathbf{a}_2 - \mathbf{a}_2) \times (\mathbf{a}_3 - \mathbf{a}_1) = 10(-2, -1, 1)$$
.

Hence the equation is

$$(-2, -1, 1) \cdot (x - 1, y - 2, z - 1) = 0$$

which reduces to

$$2x + y - z = 3 .$$

In the same way, or by inspection using the symmetry, the equation of the other plane is

$$x + y + z = 2 \; .$$

For (b), looking for a solution \mathbf{x}_0 of the system 2x + y - z = 3 and x + y + z = 2 with x = 0, we find

$$\mathbf{x}_0 + \frac{1}{2}(0, 5, -1)$$
.

The direction vector \mathbf{v} is the cross product of the normal vectors to the planes: $\mathbf{v} = ((-2, -1, 1) \times (1, 1, 1) = (-2, 3, -1))$. Hence the parameterization is

$$\mathbf{x}(t) = \frac{1}{2}(0, 5, -1) + t(-2, 3, -1)$$
.

The equation of the line then is

$$(-2,3,-1) \times \left(\mathbf{x} - \frac{1}{2}(0,5,-1)\right) = \mathbf{0}$$

The distance in question therefore is

$$\frac{1}{\|(-2,3,-1)\|} \left\| (-2,3,-1) \times \left(\mathbf{a}_1 - \frac{1}{2}(0,5,-1) \right) \right\| = \frac{\|4,2,-2\|}{\|(-2,3,-1)\|} = 2\sqrt{3/7}$$

For (c), the line through \mathbf{b}_1 and \mathbf{b}_2 has direction vector $\mathbf{w} := \mathbf{b}_2 - \mathbf{b}_1 = (0, -1, 1)$. Hence this line is parameterized by

$$\mathbf{x}(t) = (1, 1, 0) + t(0, -1, 1) = (1, 1 - t, t)$$

Plugging this into the equation 2x + y - z = 3 for P_1 , we find t = 0; i.e., (1, 1, 0) is on the line and on the plane P_1 . So this is the reflection point.

The reflected line therefore has (1, 1, 0) as its base point, and has $\mathbf{h}_{\mathbf{u}}(\mathbf{w})$ as its direction vector, when \mathbf{u} is the unit normal to the plane P_1 . Then since

$$\mathbf{u} = \frac{1}{\sqrt{6}}(2, 1, -1)$$
 and $\mathbf{h}_{\mathbf{u}}(\mathbf{w}) = \mathbf{w} - 2(\mathbf{w} \cdot \mathbf{u})\mathbf{u}$,

we find

$$\mathbf{h}_{\mathbf{u}}(\mathbf{w}) = \frac{1}{3}(-4, 1, -1)$$
.

Thus, the reflected line is given by

$$\mathbf{x}(t) = (1,1,0) + \frac{1}{3}(-4,1,-1)$$

3: Let $\mathbf{x}(t)$ be the curve given by

$$\mathbf{x}(t) = (e^t \cos(t), e^t \sin(t), e^t) \; .$$

(a) Compute the arc length s(t) as a function of t, measured from the starting point $\mathbf{x}(0)$, and find an arc length parameterization of this curve

(b) Compute curvature $\kappa(t)$ as a function of t.

(c) Find an equation for the osculating plane at time t = 0

SOLUTION: We compute

$$\mathbf{v}(t) = \mathbf{x}'(t) = e^t(\cos t - \sin t, \cos t + \sin t, 1) \quad \text{and hence} \quad v(t) = \sqrt{3}e^t \; .$$

Thus,

$$s(t) = \int_0^t \sqrt{3}e^u du = \sqrt{3}(e^t - 1);$$

Solving $s = \sqrt{3}(e^t - 1)$, we find

$$t(s) = \ln\left(\frac{s}{\sqrt{3}} + 1\right) \;.$$

The arc length parameterization is then given by $\mathbf{x}(t(s))$, which is

$$\left(\frac{s}{\sqrt{3}}+1\right)\left(\cos\left(\ln\left(\frac{s}{\sqrt{3}}+1\right)\right),\sin\left(\ln\left(\frac{s}{\sqrt{3}}+1\right)\right),1\right)$$
.

Next, to find the curvature, we compute

$$\mathbf{a}(t) = \mathbf{v}'(t) = e^t(-2\sin t, 2\cos t, 1)$$

and

$$\mathbf{v}(t) \times \mathbf{a}(t) = e^{2t} (\sin t - \cos t, -\sin t - \cos t, 2) \; .$$

Thus, $\|\mathbf{v}(t) \times \mathbf{a}(t)\| = 6e^{2t}$. The curvature is

$$\kappa(t) = \frac{\|\mathbf{v}(t) \times \mathbf{a}(t)\|}{v^3(t)} = \frac{2}{\sqrt{3}}e^{-t}$$

Finally, the normal to the osculating plane at t = 0 is

$$\mathbf{v}(0) \times \mathbf{a}(0) = (-1, -1, 2)$$
.

We take $\mathbf{x}(0) = (1, 0, 1)$ as the base point. The equation then is

$$-x - y + 2z = 1 \ .$$

4: (a) Let f(x, y) be given by

$$f(x,y) = \begin{cases} \frac{xy}{|x| + |y|} & (x,y) \neq (0,0) \\ 0 & (x,y) \neq (0,0) \end{cases}$$

Does

$$\lim_{(x,y)\to(0,0)} f(x,y)$$

exist? If so, evaluate the limit. If not, explain why not.(b) Let g(x, y) be given by

$$g(x,y) = \begin{cases} \frac{x^2 + y^2}{\sqrt{x^2 + y^4 + 1} - 1} & (x,y) \neq (0,0) \\ 0 & (x,y) = (0,0) \end{cases}$$

Does

$$\lim_{(x,y)\to(0,0)}g(x,y)$$

exist? If so, evaluate the limit. If not, explain why not.

SOLUTION: For (a),

$$0 \le |f(x,y)| = \frac{|x||y|}{|x| + |y|} \le \frac{|x||y|}{|x|} = |y| \le ||\mathbf{x}|| .$$

Hence, by the squeeze principle,

$$\lim_{(x,y)\to(0,0)} f(x,y) = 0 \; .$$

For (b), Note thas as (x, y) approaches (0, 0), both the numerator and the denominator tend to zero. Since y^4 goes to zero more quickly than y^2 as **x** tends to zero, let us look at what happens as **x** approaches (0, 0) along the y-axis:

$$g(0,y) = \frac{y^2}{\sqrt{1+y^4}-1}$$
.

Two applications of l'Hospital's rule show that

$$\lim_{y \to 0} g(0, y) = \infty \; .$$

The function is not continuous at (0, 0).

5: Let $f : \mathbb{R}^2 \to \mathbb{R}$ be given by

$$f(x,y) = x^2y + yx - xy^2 .$$

(a) Compute the gradient of f, and find all critical points of f.

(b) Find the equation of the tangent plane to the graph f at the point (1,1).

(c) Let
$$\mathbf{x}(t) = (1 + t - t^3, 2 - t + t^2)$$
. Compute $\frac{d}{dt} f(\mathbf{x}(t)) \Big|_{t=0}$

(d) Find all points (x, y) at which the tangent plane to the graph of f is orthogonal to the line parameterized by t(1, 0, 1).

SOLUTION: For (a), we compute

$$\nabla f(x,y) = ((2x - y + 1)y, (x - 2y + 1)x).$$

To find the critical points, we solve

$$(2x - y + 1)y = 0$$

(x - 2y + 1)x = 0

We can solve the first equation by taking y = 0 or y = 2x + 1. If y = 0, the second equation becomes (x + 1)x = 0 which is solved by x = -1 and x = 0. Hence (-1, 0) and (0, 0) are critical points. If y = 2x + 1, the second equation becomes (3x + 1)x = 0, which is solved by x = 0 and x = -1/2. Thus (0, 1) and (-1/3, 1/3) are critical points. The four that we have listed above constitute the complete set of critical points.

For (b), we compute $\nabla f(1,1) = (2,0)$ and f(1,1) = 1 Hence

$$z = f(x, y) \approx 1 + (2, 0) \cdot (x - 1, y - 1) = 2x - 1$$
.

The equation is z = 2x - 1, or equivalently,

$$2x - z = 1 \; .$$

For (c) we compute

$$\mathbf{x}(0) = (1,2)$$
 $\mathbf{x}'(0) = (1,-1)$ and $\nabla f(1,2) = (2,-2)$.

Hence

$$\left. \frac{\mathrm{d}}{\mathrm{d}t} f(\mathbf{x}(t)) \right|_{t=0} = \nabla f(\mathbf{x}(0)) \cdot \mathbf{x}'(0) = (2, -2) \cdot (1, -1) = 4 \; .$$

For (d) we note that the normal vector to the tangent plane at (x, y, f(x, y)) is

$$((2x - y + 1)y, (x - 2y + 1)x), -1)$$
.

Setting this equal to a(1,0,1), we see we must have a = -1, and hence

$$(2x - y + 1)y = -1 (x - 2y + 1)x = 0$$

From the second equation we have that either x = 0 or x = 2y - 1. If x = 0, then the first equation becomes (-y + 1)y = -1 which has the roots $y = (1 \pm \sqrt{5})/2$. Hence we have the points

$$\left(0, \frac{1-\sqrt{5}}{2}\right)$$
 and $\left(0, \frac{1+\sqrt{5}}{2}\right)$.

If x = 2y - 1, the second equation becomes $3y^2 - y = 1$, which has no real roots. Hence there are only two such points, which are listed above.

Extra Credit: Let \mathbf{w}_1 , \mathbf{w}_2 and \mathbf{w}_3 be three vectors in \mathbb{R}^3 such that $\mathbf{w}_2 \times \mathbf{w}_3 \neq \mathbf{0}$. Consider the curve

$$\mathbf{x}(t) = t\mathbf{w}_1 + t^2\mathbf{w}_2 + t^3\mathbf{w}_3 \; .$$

Show that this curve is planar if $\mathbf{w}_1 \cdot \mathbf{w}_2 \times \mathbf{w}_3 = 0$, and for more extra credit, show that "if" can be upgraded to "if and only if".

SOLUTION: We compute

$$\mathbf{v}(t) = \mathbf{w}_1 + 2t\mathbf{w}_2 + 3t^2\mathbf{w}_3$$
 and $\mathbf{a}(t) = 2\mathbf{w}_2 + 6t\mathbf{w}_3$.

Now, $\mathbf{w}_1 \cdot \mathbf{w}_2 \times \mathbf{w}_3 = 0$ if and only if \mathbf{w}_1 lies in the plane spanned by \mathbf{w}_2 and \mathbf{w}_3 . In this case, we see from the calculation obove that for all t, (t) and $\mathbf{a}(t)$ belong to the plane given by

$$(\mathbf{w}_2 \times \mathbf{w}_3) \cdot \mathbf{x} = 0$$
.

This means that

$$\mathbf{B}(t) = \pm \frac{\mathbf{w}_2 \times \mathbf{w}_3}{\|\mathbf{w}_2 \times \mathbf{w}_3\|} \; .$$

Hence the torsion is zero, and the curve is planar.

Conversely., if the curve is planar, for all t, $\mathbf{v}(t) \times \mathbf{a}(t)$ is a multiple of $\mathbf{v}(0) \times \mathbf{a}(0) = \mathbf{w}_1 \times \mathbf{w}_2$. But then $\mathbf{w}_2 \times \mathbf{w}_3$ and $\mathbf{w}_3 \times \mathbf{w}_1$ must also be multiples of $\mathbf{w}_1 \times \mathbf{w}_2$. Therefore,

$$(\mathbf{w}_2 \times \mathbf{w}_3) \cdot [(\mathbf{w}_3 \times \mathbf{w}_1) \times (\mathbf{w}_1 \times \mathbf{w}_2)] = 0$$
.

Now recall the identity proved in Exercise 1.37:

$$(\mathbf{b} imes \mathbf{c}) \cdot [(\mathbf{c} imes \mathbf{a}) imes (\mathbf{a} imes \mathbf{b})] = |\mathbf{a} \cdot (\mathbf{b} imes \mathbf{c})|^2$$
 .

Applying this inequality, we see that

$$|\mathbf{w}_1 \cdot (\mathbf{w}_2 \times \mathbf{w}_3)|^2 = 0.$$