

## Solutions for the even numbered exercises from Chapter 4

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**4.2** Let  $\mathbf{v}_1 = (1, 1)$  and  $\mathbf{v}_2 = (3, 1)$ . Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be differentiable, and suppose that for some  $\mathbf{x}_0 \in \mathbb{R}^2$ ,  $\mathbf{v}_1 \cdot \nabla f(\mathbf{x}_0) = -2$  and  $\mathbf{v}_2 \cdot \nabla f(\mathbf{x}_0) = 3$ .

For  $\mathbf{v} = (1, -1)$ , compute  $\mathbf{v} \cdot \nabla f(\mathbf{x}_0)$ .

**SOLUTION** We will use the information  $\mathbf{v}_1 \cdot \nabla f(\mathbf{x}_0) = -2$  and  $\mathbf{v}_2 \cdot \nabla f(\mathbf{x}_0) = 3$  to determine  $\nabla f(\mathbf{x}_0)$ . Let  $a$  and  $b$  be such that  $\nabla f(\mathbf{x}_0) = (a, b)$ . Then these equations become

$$\begin{aligned} a + b &= -2 \\ 3a + b &= 3 . \end{aligned}$$

Subtracting the first equation from the second,  $2a = 5$  so  $a = 5/2$  and then  $b = -9/2$ . Thus,

$$\nabla f(\mathbf{x}_0) = \frac{1}{2}(5, -9) .$$

Thus,

$$(1, -1) \cdot \nabla f(\mathbf{x}_0) = \frac{1}{2}(1, -1) \cdot (5, -9) = 7 .$$

**4.4** Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be given by  $f(x, y) = x^2y + yx - xy^2$ . Let  $\mathbf{x}(t)$  be given by  $\mathbf{x}(t) = (t, t^2)$ . Compute  $\left. \frac{d}{dt} f(\mathbf{x}(t)) \right|_{t=1}$ .

**SOLUTION** We use the chain rule:

$$\left. \frac{d}{dt} f(\mathbf{x}(t)) \right|_{t=1} = \nabla f(\mathbf{x}(1)) \cdot \mathbf{x}'(1) .$$

We then compute

$$\mathbf{x}(1) = (1, 1) \quad \text{and} \quad \mathbf{x}'(t) = (1, 2t) ,$$

and then

$$\nabla f(x, y) = (2xy + y - y^2, x^2 + x - 2xy) ,$$

so that

$$\nabla f(\mathbf{x}(1)) = (2, 0) .$$

Therefore,

$$\left. \frac{d}{dt} f(\mathbf{x}(t)) \right|_{t=1} = (2, 0) \cdot (1, 2) = 2 .$$

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**4.6** Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be given by  $f(x, y) = x^2y + yx - xy^2$ .

(a) Compute the gradient of  $f$ , and find all critical points of  $f$ .

(b) Find the equation of the tangent plane to the graph  $f$  at the point  $(1, 1)$ .

**SOLUTION** We compute, as above,  $\nabla f(x, y) = (2xy + y - y^2, x^2 + x - 2xy)$ . Thus,  $(x, y)$  is a critical point when

$$\begin{aligned} 2xy + y - y^2 &= 0 \\ x^2 + x - 2xy &= 0. \end{aligned}$$

To solve this system, suppose that  $x = 0$ . Then, from the first equation,  $y = y^2$ , so either  $y = 0$  or  $y = 1$ . This gives us two solutions so far:  $(0, 0)$  and  $(0, 1)$ .

Now let us look for solutions with  $x \neq 0$ . Then we may divide the second equation through by  $x$  to obtain  $x + 1 - 2y = 0$ , or

$$x = 2y - 1. \quad (0.1)$$

Using this to eliminate  $x$  from the first equation, we obtain

$$3y^2 - 2y + y = 0.$$

This quadratic equation has two roots, namely,  $2/3$  and  $-1$ . For these values of  $y$ , we use (0.1) to determine the corresponding  $x$  values. Thus we get the two additional solutions  $(1/3, 2/3)$  and  $(-3, -1)$ . Altogether, we have four critical points which are

$$(0, 0), \quad (0, 1), \quad (1/3, 2/3), \quad (-3, -1).$$

Next, since  $f(1, 1) = 1$  and  $\nabla f(1, 1) = (2, 0)$ , the best affine approximation of  $f$  at  $(1, 1)$  is given by

$$h(x, y) = f(1, 1) + \nabla f(1, 1) \cdot (x - 1, y - 1) = 1 + (2, 0) \cdot (x - 1, y - 1) = 2x - 1.$$

The tangent plane is the graph of  $z = h(x, y)$ , so it has the equation  $z = 2x - 1$ , or  $2x - z = 1$ .

**4.8** Let  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  be given by  $f(x, y) = x^3 + y^3 + 3xy$ .

(a) Compute the gradient of  $f$ , and find all points  $(x, y)$  at which the tangent plane to the graph of  $f$  is horizontal.

(b) Find the equation of the tangent plane to the graph of  $f$  at the point  $(1, 2)$ .

(c) If you were standing at the point  $(1, 1)$  and wanted to climb uphill as directly as possible, in which compass direction would you head? For purposes of this question, take the direction  $\mathbf{e}_1$  to be East, and the direction  $\mathbf{e}_2$  to be North.

**SOLUTION** We compute  $\nabla f(x, y) = (3x^2 + y, y^2 + x)$ . The tangent plane at  $(x, y)$  is horizontal if and only if  $\nabla f(x, y) = 0$ , so we have to find the critical points of  $f$ . That is, we have to solve

$$\begin{aligned} x^2 + y &= 0 \\ x + y^2 &= 0. \end{aligned}$$

From the first equation  $y = -x^2$ . Using this to eliminate  $y$  from the second equation, we get  $x + x^4 = 0$ . Since  $x + x^4 = x(1 + x^3)$ , the two real solutions are  $x = 0$  and  $x = -1$ . Then from  $y = -x^2$ , we get the two critical points

$$(0, 0) \quad \text{and} \quad (-1, -1) .$$

Next, we compute

$$f(1, 2) = 15 \quad \text{and} \quad \nabla f(1, 2) = (9, 15) .$$

Thus, near  $(1, 2)$ ,

$$f(x, y) \approx 15 + (9, 15) \cdot (x - 1, y - 2) = 9x + 15y - 24 .$$

The equation of the tangent plane then is

$$9x + 15y - z = 24 .$$

Finally, the steepest downhill direction is the direction of  $-\nabla f(1, 2) = (-9, -15)$ , which points Southwest.

**4.10** Let  $A := \begin{bmatrix} 5 & 2 \\ 2 & 1 \end{bmatrix}$ .

(a) Compute  $\det(A)$  and the matrix inverse of  $A$ .

(b) Find all solutions of the equation  $A\mathbf{x} = (1, 2)$ .

**SOLUTION** We compute  $\det(A) = 5 - 4 = 1$ , and

$$A^{-1} = \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} .$$

Since  $A$  is invertible, there is exactly one solution of  $A\mathbf{x} = (1, 2)$ , which is

$$A^{-1}(1, 2) = \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix} (1, 2) = (-3, 8) .$$

You can easily check that this is a solution.

**4.12** Let  $A := \begin{bmatrix} 2 & 0 & 3 \\ -1 & 2 & 1 \\ 1 & 1 & 3 \end{bmatrix}$ .

(a) Compute  $\det(A)$  and the matrix inverse of  $A$ .

(b) Find all solutions of the equation  $A\mathbf{x} = (1, 2, 3)$ .

**SOLUTION** We define  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  to be the columns of  $A$  so that  $A = [\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3]$ . We then compute

$$\mathbf{v}_2 \times \mathbf{v}_3 = (5, 3, -6) \quad \mathbf{v}_3 \times \mathbf{v}_1 = (4, 3, -5) \quad \text{and} \quad \mathbf{v}_1 \times \mathbf{v}_2 = (-3, -2, 4) .$$

It then follows that

$$\det(A) = \mathbf{v}_1 \cdot \mathbf{v}_2 \times \mathbf{v}_3 = 1 ,$$

and then that

$$A^{-1} = \begin{bmatrix} 5 & 2 & -6 \\ 4 & 3 & -5 \\ -3 & -2 & 4 \end{bmatrix} .$$

Since  $A$  is invertible, there is exactly one solution of  $A\mathbf{x} = (1, 2, 3)$ , which is

$$A^{-1}(1, 2, 3) = \begin{bmatrix} 5 & 2 & -6 \\ 4 & 3 & -5 \\ -3 & -2 & 4 \end{bmatrix} (1, 2, 3) = (-7, -5, 5) .$$

You can easily check that this is a solution.

**4.14** Let  $f(x, y) = x^2y + (x - 1)(y - 1)^2$ .

(a) Find the equations for the tangent planes to the graph of  $z = f(x, y)$  at  $\mathbf{x}_1 = (2, -1)$  and at  $\mathbf{x}_2 = (-1, 1)$ .

(b) Parameterize the line that is the intersection of the two planes found in (a).

(c) Let  $\mathbf{x}_0 = (-3, 0, 5)$ . Compute the distance from  $\mathbf{x}_0$  to the line found in (b), and from  $\mathbf{x}_0$  to the second tangent plane found in (a). The distance to the plane should be smaller than the distance to the line. Explain why.

**SOLUTION** For (a), we compute  $\nabla f(x, y) = (2xy + (y - 1)^2, x^2 + 2(x - 1)(y - 1))$ . We then evaluate

$$\nabla f(2, -1) = (0, 0) \quad \text{and} \quad \nabla f(-1, 1) = (-2, 1)$$

and

$$f(2, -1) = 0 \quad \text{and} \quad f(-1, 1) = 1 .$$

Thus the equation for the tangent plane at  $(2, -1)$  is

$$z = 0$$

and the equation for the tangent plane at  $(-1, 1)$  is

$$z = 1 + (-2, 1) \cdot (x + 1, y - 1) = -2x + y - 2 .$$

For (b), we substitute  $z = 0$  into  $z = -2x + y - 2$  to learn  $y = 2(x + 1)$ . Thus every point on the line has the form  $(x, 2(x + 1), 0)$ , and the parameterization is

$$\mathbf{x}(t) = (t, 2(t + 1), 0) .$$

For (c), Note the  $\mathbf{x}(0) := (0, 2, 0)$  is on the plane, and therefore on both lines. We may take this as the base point for both the plane and the line. Since the normal vector to the plane is  $(-2, 1, -1)$ , the distance from  $(-3, 0, 5)$  to the plane is

$$\frac{|((-3, 0, 5) - (0, 2, 0)) \cdot (-2, 1, -1)|}{\|(-2, 1, -1)\|} = \frac{1}{\sqrt{6}} .$$

Since the direction vector of the line is  $(1, 2, 0)$ , the distance from  $(-3, 0, 5)$  to the line is

$$\frac{|((-3, 0, 5) - (0, 2, 0)) \times (1, 2, 0)|}{\|(1, 2, 0)\|} = \frac{\|(-10, 5, -4)\|}{\|(1, 2, 0)\|} = \frac{\sqrt{141}}{\sqrt{5}} .$$

The distance to the plane is smaller. This is because the distance to plane is then minimum of

$$\|\mathbf{x} - (-3, 0, 5)\| = \sqrt{(x+3)^2 + y^2 + (z-5)^2},$$

where  $(x, y, z)$  ranges over the plane, while the distance to the line is the minimum of the *same function* over the line only, which is a subset of the plane. For any non-empty sets  $A \subset B$  on which any real valued function  $f$  is defined, the greatest lower bound of  $f$  on  $B$  is certainly a lower bound of  $f$  on the smaller set  $A$ , and hence is no greater than the greatest lower bound of  $f$  on  $A$ . If  $f$  has minimizers in both  $A$  and  $B$ , this means that the minimum of  $f$  on  $B$  is no greater than the minimum of  $f$  on  $A$ .

**4.16** Let  $\mathbf{f}(\mathbf{x}) = (f(\mathbf{x}), g(\mathbf{x}))$  where  $f(x, y) = x^3 + xy$ , and  $g(x, y) = 1 - 4y^2 - x^2$ . Let  $\mathbf{x}_0 = \mathbf{e}_1$ .

(a) Compute  $[D_{\mathbf{f}}(\mathbf{x})]$  and  $[D_{\mathbf{f}}(\mathbf{x}_0)]$ .

(b) Use  $\mathbf{x}_0$  as a starting point for Newton's method, and compute the next approximate solution  $\mathbf{x}_1$ .

(c) Evaluate  $\mathbf{f}(\mathbf{x}_1)$ , and compare this with  $\mathbf{f}(\mathbf{x}_0)$ .

**SOLUTION** We compute  $\nabla f(x, y) = (3x^2 + y, x)$  and  $\nabla g(x, y) = (-2x, -8y)$ . Therefore

$$[D_{\mathbf{f}}(\mathbf{x})] = \begin{bmatrix} \nabla f(\mathbf{x}) \\ \nabla g(\mathbf{x}) \end{bmatrix} = \begin{bmatrix} 3x^2 + y & x \\ -2x & -8y \end{bmatrix}.$$

Evaluating at  $x = 1, y = 0$ , we find

$$[D_{\mathbf{f}}(\mathbf{x}_0)] = \begin{bmatrix} 3 & 1 \\ -2 & 0 \end{bmatrix}.$$

We next compute  $\mathbf{f}(\mathbf{x}_0) = (f(1, 0), g(1, 0)) = (1, 0)$ , which is not really close to  $\mathbf{0}$ . To (hopefully) get a better approximation, we solve for

$$\begin{aligned} \mathbf{x}_1 &= (1, 0) - \begin{bmatrix} 3 & 1 \\ -2 & 0 \end{bmatrix}^{-1} (1, 0) \\ &= (1, 0) - \frac{1}{2} \begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} (1, 0) \\ &= (1, -1). \end{aligned}$$

We now evaluate  $\mathbf{f}(\mathbf{x}_1) = (f(1, -1), g(1, -1)) = (0, -4)$ . This is not great. Getting a reasonably good starting point, by graphical methods for example, is important.

**4.17** Let  $\mathbf{f}(\mathbf{x}) = (f(\mathbf{x}), g(\mathbf{x}))$  where  $f(x, y) = \sqrt{x} + \sqrt{y} - 3$ , and  $g(x, y) = x^2 + y^2 - 18$ . Compute  $\mathbf{f}(\mathbf{x}_0)$  for  $\mathbf{x}_0 = (3, 3)$ . Does this look like a reasonable starting point? Compute  $[D_{\mathbf{f}}(\mathbf{x}_0)]$ . What happens if you try to use  $\mathbf{x}_0$  as your starting point for Newton's method?

**SOLUTION** We compute  $\mathbf{f}(3, 3) = (2\sqrt{3} - 3, 0)$ . Since  $2\sqrt{3} - 3 \approx 0.54$ , this looks reasonable.

Writing  $\mathbf{f} = (f, g)$ , we compute  $\nabla f(x, y) = (x^{-1/2}/2, y^{-1/2}/2)$  and  $\nabla g(x, y) = (2x, 2y)$ . Thus,  $\nabla f(3, 3) = (3^{-1/2}/2, 3^{-1/2}/2)$  and  $\nabla g(3, 3) = (6, 6)$ , and

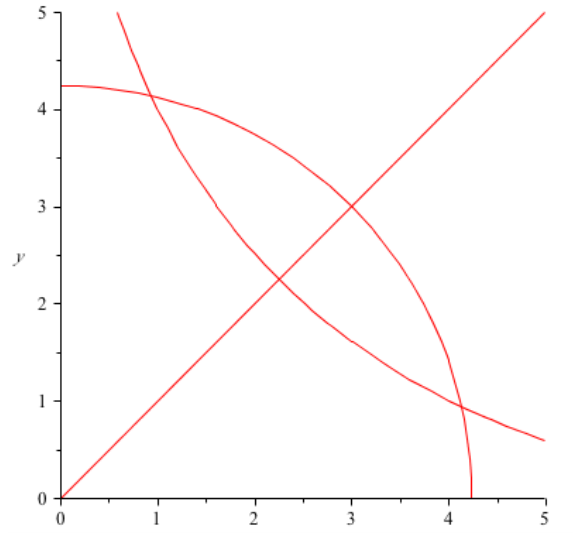
$$[D_{\mathbf{f}}(\mathbf{x}_0)] = \begin{bmatrix} 3^{-1/2}/2 & 3^{-1/2}/2 \\ 6 & 6 \end{bmatrix}.$$

The determinant of this matrix is zero, and even worse,

$$[D_{\mathbf{f}}(\mathbf{x}_0)](\mathbf{x} - \mathbf{x}_0) = -\mathbf{f}(\mathbf{x}_0)$$

has no solution. So for this starting point, Newton's method breaks down at the first step. It was not a good starting point after all.

The reason for this is not hard to see. Both functions  $f$  and  $g$  are symmetric in  $x$  and  $y$ : That is, for all  $(a, b) \in \mathbb{R}^2$ ,  $f(a, b) = f(b, a)$  and  $g(a, b) = g(b, a)$ . Therefore, if  $(a, b)$  is a solution of the system, so is  $(b, a)$ , its reflection about the line  $y = x$ . Indeed, here is a plot of the solutions sets of  $f(x, y) = 0$ ,  $g(x, y) = 0$  and the line  $y = x$ .



You see there are exactly two solutions, where the two curves intersect. Both of them are equidistant from the starting point  $(3, 3)$  which is here the line intersects the circle. There is a dilemma: Should then next point move closer to the solution above the line  $y = x$ , or the solution below this line?

This dilemma is seen to be unresolvable, since again by symmetry it is clear the the gradients of both  $f$  and  $g$  at any point along the line  $y = x$  are multiples of  $(1, 1)$ . Hence the Jacobian of  $\mathbf{f}$  cannot be invertible.

**4.18:** Let  $f(x, y)$  and  $g(x, y)$  be given by

$$f(x, y) = (x + 1)^2 + (y + 1)^2 - 4 \quad \text{and} \quad g(x, y) = 4(x - 1)^2 + (y - 1)^2 - 5 .$$

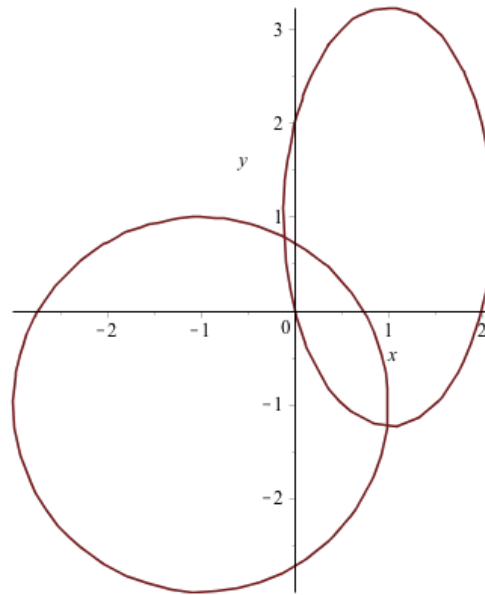
(a) The equation  $f(x, y) = 0$  describes a circle. The equation  $g(x, y) = 0$  describes an ellipse. Sketch a plot of the circle and the ellipse, and determine how many solutions there are of the system

$$\mathbf{f}(x, y) := (f(x, y), g(x, y)) = \mathbf{0} .$$

**Note:** It is possible to exactly solve this system by algebraic means, but that is not what is being asked for here.

(b) Your sketch should show one solution of the system in the lower right hand quadrant not too far from  $(1, -1)$ . Use  $\mathbf{x}_0 = (1, -1)$  as a starting point, and apply one step of Newton's method to find  $\mathbf{x}_1$ , a better approximate solution, and compute  $f(\mathbf{x}_1)$  and  $g(\mathbf{x}_1)$ .

**SOLUTION** It is easy to plot ellipses, and even easier when they are circles: Mark the points where the major and minor axes cross the ellipse, and draw an ellipse through these four points. Here is what you get in the case at hand:



Since there are two points of intersection, there are two solutions to the system of equations. This can be seen from even a rather rough sketch.

For **(b)**, indeed we see one point of intersection close to  $\mathbf{x}_0 := (1, -1)$ . We compute

$$\nabla f(x, y) = 2(x + 1, y + 1) \quad \text{and} \quad \nabla g(x, y) = 2(4x - 4, y - 1) ,$$

and evaluate

$$\nabla f(1, -1) = (4, 0) \quad \text{and} \quad \nabla g(1, -1) = (0, -4) .$$

Hence

$$[D_{\mathbf{f}}(1, -1)] = \begin{bmatrix} 4 & 0 \\ 0 & -4 \end{bmatrix} \quad \text{and} \quad [D_{\mathbf{f}}(1, -1)]^{-1} = \frac{1}{4} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} .$$

We then evaluate

$$\mathbf{f}(\mathbf{x}_0) = (f(1, -1), g(1, -1)) = (0, -1) ,$$

and

$$\mathbf{x}_1 = \mathbf{x}_0 - [D_{\mathbf{f}}(1, -1)]^{-1} \mathbf{f}(\mathbf{x}_0) = (1, -5/4) .$$

Note from the graph that  $\mathbf{x}_1$  is much closer to the solution closest to  $\mathbf{x}_0$  than  $\mathbf{x}_0$  is. Indeed,  $f(\mathbf{x}_1) = g(\mathbf{x}_1) = 1/16$ .