

# Lie Groups, Homogeneous Manifolds and Model Geometries

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Klein's **Erlangen Program** proposed that geometries should be characterized using the concept of symmetries

Klein described it as "Given a manifold[ness] and a group of transformations of the same; to develop the theory of invariants relating to that group"

# Klein Geometries

A **Klein Geometry** is a pair  $(G, H)$  where  $G$  is a Lie Group and  $H$  is a closed Lie subgroup of  $G$  such that the coset space  $G/H$  is connected.

The space  $X = G/H$  is a smooth manifold with dimension  
 $\dim X = \dim G - \dim H$

An example of a Klein geometry is spherical geometry  $S^n$  which group  $G$  is  $O(n+1)$  and  $H$  is  $O(n)$ . Invariants include circles and angles.

More specifically, these are homogeneous spaces

# Homogeneous Manifolds

A **homogeneous manifold**  $X$  has a group  $G$  which acts on it transitively

The elements of  $G$  are the symmetries of  $X$

An example of a homogeneous space is Spherical space  $\mathbb{S}^{n-1}$

Group  $G$ :  $O(n)$ , Stabilizer  $H$ :  $O(n-1)$

# Stabilizers

Let  $\varphi$  be a (left or right) action of a group  $G$  on a set  $M$

For any  $g \in G$  and  $p \in M$  the element  $\varphi(g)(p) \in M$  will also be denoted as " $g \star p$ "

For any  $p \in M$  the set  $G_p = \{g \in G \mid g \star p = p\}$  is called the **stabilizer** of  $p$

A **manifold** is a second countable Hausdorff space locally Euclidean space

A **Lie group** is a group with a manifold structure

Examples of Lie Groups include

- $GL_n$ :  $n \times n$  invertible matrices
- $SL_n$   $n \times n$  matrices with determinant 1

# Riemannian Metric

Let  $M$  be a manifold. A **Riemannian metric** on  $M$  is a choice for each  $p \in M$  of an inner product,  $\langle \cdot, \cdot \rangle_p$  on  $T_p M$  that "varies smoothly with  $p$  in the following sense: for any pair  $X$  and  $Y$  of smooth vector fields on  $M$ , the map  $p \mapsto \langle X(p), Y(p) \rangle_p$  is a smooth function from  $M$  to  $\mathbb{R}$ . A manifold together with a Riemannian metric is called a **Riemannian manifold**

# Geometrization Conjecture

Thurston's **Geometrization Conjecture**: Let  $M$  be a closed, orientable, prime 3-manifold. Then there is an embedding of a disjoint union of 2-tori and Klein bottles  $\amalg_i T_i^2 \subset M$  such that every component of the complement admits a locally homogeneous Riemannian metric of finite volume

# The Eight Model Geometries

A **model geometry**  $(G, X)$  is a manifold  $X$  together with a Lie group  $G$  for diffeomorphisms of  $X$  such that:

- $X$  is connected and simply connected
- $G$  acts transitively on  $X$  with compact point stabilizers
- $G$  is not contained in any larger group of diffeomorphisms of  $X$  with compact stabilizers of points
- there exists at least one compact manifold modeled on  $(G, X)$

# The Eight Model Geometries

There are eight three-dimensional model geometries  $(G, X)$

- If the point stabilizers are three-dimensional,  $X$  is  $S^3$ ,  $E^3$  or  $H^3$
- If the point stabilizers are one-dimensional,  $X$  fibers over one of the two-dimensional model geometries in a way that is invariant under  $G$ . There is a  $G$ -invariant Riemannian metric on  $X$  such that the connection orthogonal to the fibers has curvature 0 or 1
  - If the curvature is zero,  $X$  is  $S^2 \times E^1$  or  $H^2 \times E^1$
  - If the curvature is one, it is nilgeometry which fibers over  $E^2$  or the geometry of  $\tilde{SL}(2, R)$
- If the stabilizers are zero-dimensional, the geometry is solvegeometry which fibers over the line

# Proof of 3 of the Model Geometries

If  $G'$  acts with stabilizer  $SO(3)$ , any tangent two-plane at any point can be taken by  $G$  to any tangent two-plane at any other point, so the metric has constant sectional curvature. Same as the two-dimensional case, the geometry is either spherical, Euclidean, or hyperbolic.

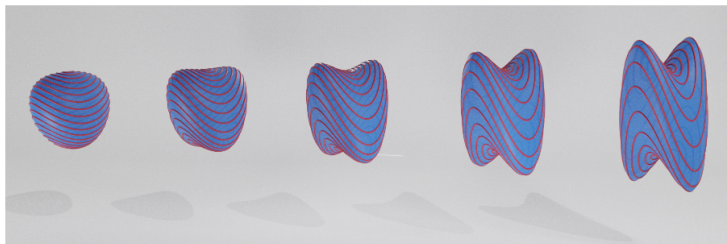
**Nilgeometry** is the geometry of the Heisenberg Group.

The **Heisenberg Group** is the group of 3x3 matrices of the form

$$\begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix}$$

The Heisenberg group is **nilpotent**. It is the only three-dimensional nilpotent but non-Abelian connected and simply connected Lie group.

# Nilgeometry



The spheres of radius 1, 2, 3, 4 and 5 in the Heisenberg model of Nil. The spheres have been rescaled to have approximately the same size. Image credit : © Rémi Coulon

# References

“Es ist eine Mannigfaltigkeit und in derselben eine Transformationsgruppe gegeben. Man soll [...] die Theorie der Beziehungen, welche relativ zur Gruppe invariant sind, untersuchen.” - The translation given is by M. W. Haskell and authorized by Klein; cf. New York Math. Soc. 2, 215-249 (1892/93).

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