Eigenvalues and Eigenvectors of 2×2 matrices

by Edinah K. Gnang

Definition 0

A 2×2 square matrix ${\bf A}$ is a table of the form

$$\mathbf{A} := \begin{bmatrix} a_{1,1} & a_{1,2} \\ a_{2,1} & a_{2,2} \end{bmatrix},\tag{1}$$

such a matrix induces a function

$$f_{\mathbf{A}}: \mathbb{R}^2 \to \mathbb{R}^2$$

which takes vectors $\mathbf{x} \in \mathbb{R}^2$ as input and outputs a new vector $f_{\mathbf{A}}(\mathbf{x}) \in \mathbb{R}^2$. Let

$$\mathbf{x} := \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \tag{2}$$

the function $f_{\mathbf{A}}\left(\mathbf{x}\right)$ induced by the matrix \mathbf{A} is expressed by

$$f_{\mathbf{A}}(\mathbf{x}) := \mathbf{A} \cdot \mathbf{x} = \begin{bmatrix} a_{1,1} \cdot x_1 + a_{1,2} \cdot x_2 \\ a_{2,1} \cdot x_1 + a_{2,2} \cdot x_2 \end{bmatrix}$$
(3)

Example 0

Let **A** denote a 2×2 matrix expressed by

$$\mathbf{A} = \begin{bmatrix} 1 & 2\\ 3 & 4 \end{bmatrix} \tag{4}$$

and let $f_{\mathbf{A}}(\mathbf{x})$ denote the corresponding induced function of $\mathbf{x} := \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ expressed by

$$f_{\mathbf{A}}(\mathbf{x}) := \mathbf{A} \cdot \mathbf{x} = \begin{bmatrix} x_1 + 2x_2 \\ 3x_1 + 4x_2 \end{bmatrix}$$
(5)

incidentally $f\left(\left[\begin{array}{c} 5\\ 6 \end{array} \right] \right)$ for instance is

$$f\left(\left[\begin{array}{c}5\\6\end{array}\right]\right) = \left[\begin{array}{c}1&2\\3&4\end{array}\right] \cdot \left[\begin{array}{c}5\\6\end{array}\right] = \left[\begin{array}{c}1\times5+2\times6\\3\times5+4\times6\end{array}\right] = \left[\begin{array}{c}17\\39\end{array}\right]$$
(6)

Definition 1

A nonzero vector **x** is an *eigenvector* of **A** if there exists a constant λ , called an *eigenvalue*, such that

$$f(\mathbf{x}) = \lambda \, \mathbf{x} \Leftrightarrow \mathbf{A} \cdot \mathbf{x} = \lambda \, \mathbf{x} \tag{7}$$

0.1 Solving for the Eigenvalues of 2×2 matrices

To obtain the eigenvalues for a 2×2 matrix **A** we solve the polynomial equation $det(\lambda I - A) = \mathbf{0}$:

$$\det\left(\left[\begin{array}{cc}\lambda-a_{1,1}&-a_{1,2}\\-a_{2,1}&\lambda-a_{2,2}\end{array}\right]\right)=0\tag{8}$$

in other words we solve the *characteristic equation* expressed by

$$p_{\mathbf{A}}(\lambda) = (\lambda - a_{1,1}) \left(\lambda - a_{2,2}\right) - a_{1,2} a_{2,1} = \lambda^2 - (a_{1,1} + a_{2,2}) \lambda + (a_{1,1}a_{2,2} - a_{1,2}a_{2,1})$$
(9)

Example 1 (part 1)

Let **A** denote the 2×2 matrix expressed by

$$\mathbf{A} = \left[\begin{array}{cc} 0 & -6 \\ 1 & 5 \end{array} \right],$$

the corresponding eigenvalues are found by solving the equation

$$p(\lambda) = \det\left(\begin{bmatrix} \lambda - 0 & 6\\ -1 & \lambda - 5 \end{bmatrix}\right) = 0$$
$$p(\lambda) = \lambda^2 - 5\lambda + 6$$

from which it follows that the eigenvalues are determined by solving the equation

$$\lambda^2 - 5\lambda + 6 = 0$$

whose solution is expressed by

$$\lambda \in \{2, 3\}$$

0.2 Solving for the Eigenvectors of 2×2 matrices

Once we have solved for the eigenvalues, the eigenvectors are computed by solving linear system of equations

$$f_{\mathbf{A}}\left(\mathbf{x}\right) = \lambda \mathbf{x} \Leftrightarrow \mathbf{A} \cdot \mathbf{x} = \lambda \,\mathbf{x} \tag{10}$$

for each one of the eigenvalues.

Example 1 (part 2)

We recall that in *Example part 1* we have determined that the eigenvalues of

$$\mathbf{A} = \left[\begin{array}{cc} 0 & -6 \\ 1 & 5 \end{array} \right]$$

are given by

$$\left\{\lambda_1=2,\quad \lambda_2=3\right\}.$$

The eigenvector corresponding to the eigenvalue $\lambda_1 = 2$ is given by solving the system

$$\begin{bmatrix} 0 & -6 \\ 1 & 5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}$$

equivalently written as

$$\begin{cases} -6x_2 = 2x_1\\ x_1 + 5x_2 = 2x_2 \end{cases}$$
$$\Rightarrow \begin{cases} -2x_1 - 6x_2 = 0\\ x_1 + 3x_2 = 0 \end{cases}$$

substitution or elimination yields

$$x_1 = -3 x_2$$

hence the corresponding eigenvector space is determined by the parametric line $\forall s \in \mathbb{R}$

$$\begin{cases} x_1 = -3s \\ x_2 = s \end{cases}$$

The eigenvector space associated with the eigenvalue $\lambda_1 = 2$ is the vector space specified by

$$s \mathbf{v}_1 = s \begin{bmatrix} -3\\1 \end{bmatrix} \tag{11}$$

.

similarly we solve for the eigenvector corresponding to the eigenvalue $\lambda_2=3$

$$\begin{bmatrix} 0 & -6 \\ 1 & 5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 x_1 \\ 3 x_2 \end{bmatrix}$$

equivalently written as

$$\begin{cases} -6x_2 = 3x_1 \\ x_1 + 5x_2 = 3x_2 \end{cases}$$
$$\Rightarrow \begin{cases} -3x_1 - 6x_2 = 0 \\ x_1 + 2x_2 = 0 \end{cases}$$

substitution or elimination yields

$$x_1 = -2 x_2$$

hence the corresponding eigenvectors space is determined by the parametric line $\forall t \in \mathbb{R}$

$$\begin{cases} x_1 = -2t \\ x_2 = t \end{cases}$$

The eigenvector space associated with the eigenvalue $\lambda_2 = 3$ is the vector space specified by

$$t \mathbf{v}_2 = t \begin{bmatrix} -2\\ 1 \end{bmatrix}. \tag{12}$$

In summary we say that the matrix

$$\mathbf{A} = \left[\begin{array}{cc} 0 & -6 \\ 1 & 5 \end{array} \right]$$

has eigenvalues/eigenvector pairs or equivalently we say that the spectrum of ${\bf A}$ denoted ${\rm Spec}({\bf A})$ is expressed by

Spec (**A**) =
$$\left\{ \left(\lambda_1 = 2, \mathbf{v}_1 = \frac{1}{\sqrt{10}} \begin{bmatrix} -3\\ 1 \end{bmatrix} \right), \left(\lambda_2 = 3, \mathbf{v}_2 = \frac{1}{\sqrt{5}} \begin{bmatrix} -2\\ 1 \end{bmatrix} \right) \right\}$$