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> # Attendance Question 1, who was sir ronald ross? why was he famous
   Ronald Ross was a Medical Doctor
       and researcher who demonstrated the life cycle of the malaria virus in mosquitos
       . For this he was the first British Nobel laureate in 1902 for Physiology or Medicine.
   # Attendance Question 2, Copy and paste maple code
   a := \mathbf{proc}(n):
   if n = 0 then
   0:
   elif n = 1 then
   1:
   elif n = 2 then
   4:
   else
   3*a(n-1)-3*a(n-2)+a(n-3):
   end:
   a(100);
       #i stopped it at 274.59s but i get the point! The other day doing the homework I tried to do a
       plot which plots all the p values on the interval .001 from 0 to 1.5, and a similar run time
       situation happened and it ended up corrupting my file as I could not save it or halt the
       current operation!
   #Attendance Question 3, use ruid solve diff eq
   #My ruid number is 166002193
   #USE MAPLE TO solve the differential equation y'(t) = \frac{0 \cdot t^0}{v_0^6}, y(1) = 6.
   dsolve\left\{ diff(y(t), t) = \frac{0 \cdot t^{6}}{y^{6}}, y(1) = 6 \right\}, y(t) 
                                                                                                        (1)
> # Attendance Question 4,
   # a1:=father age
   # a2:=mother age
   # a3:=younger sibling's age
   # Let A be the 3 by 3 matrix [[a1,a2,a3],[a2,a3,a1],[a3,a2,a1]]
       # find (float) the SECOND largest eigenvalue (in absolute value) and the corresponding
       eigenvector
   with(LinearAlgebra);
```

[&x, Add, Adjoint, BackwardSubstitute, BandMatrix, Basis, BezoutMatrix, BidiagonalForm, **(2)** BilinearForm, CARE, CharacteristicMatrix, CharacteristicPolynomial, Column, ColumnDimension, ColumnOperation, ColumnSpace, CompanionMatrix, CompressedSparseForm, ConditionNumber, ConstantMatrix, ConstantVector, Copy, CreatePermutation, CrossProduct, DARE, DeleteColumn, DeleteRow, Determinant, Diagonal, Diagonal Matrix, Dimension, Dimensions, DotProduct, EigenConditionNumbers, Eigenvalues, Eigenvectors, Equal, ForwardSubstitute, FrobeniusForm, FromCompressedSparseForm, FromSplitForm, GaussianElimination, GenerateEquations, GenerateMatrix, Generic, GetResultDataType, GetResultShape, GivensRotationMatrix, GramSchmidt, HankelMatrix, HermiteForm, HermitianTranspose, HessenbergForm, HilbertMatrix, HouseholderMatrix, IdentityMatrix, IntersectionBasis, IsDefinite, IsOrthogonal, IsSimilar, IsUnitary, JordanBlockMatrix, JordanForm, KroneckerProduct, LA Main, LUDecomposition, LeastSquares, LinearSolve, LyapunovSolve, Map, Map2, MatrixAdd, MatrixExponential, MatrixFunction, MatrixInverse, MatrixMatrixMultiply, MatrixNorm, MatrixPower, MatrixScalarMultiply, MatrixVectorMultiply, MinimalPolynomial, Minor, Modular, Multiply, NoUserValue, Norm, Normalize, NullSpace, OuterProductMatrix, Permanent, Pivot, PopovForm, ProjectionMatrix, QRDecomposition, RandomMatrix, RandomVector, Rank, RationalCanonicalForm, ReducedRowEchelonForm, Row, RowDimension, RowOperation, RowSpace, ScalarMatrix, ScalarMultiply, ScalarVector, SchurForm, SingularValues, SmithForm, SplitForm, StronglyConnectedBlocks, SubMatrix, SubVector, SumBasis, SylvesterMatrix, SylvesterSolve, ToeplitzMatrix, Trace, Transpose, TridiagonalForm, UnitVector, VandermondeMatrix, VectorAdd, VectorAngle, VectorMatrixMultiply, VectorNorm, VectorScalarMultiply, ZeroMatrix, ZeroVector, Zip]

> A := Matrix([[67, 55, 0], [55, 0, 67], [0, 55, 67]])

$$A := \begin{bmatrix} 67 & 55 & 0 \\ 55 & 0 & 67 \\ 0 & 55 & 67 \end{bmatrix}$$
 (3)

> evalf(Eigenvalues(A));

> evalf(Eigenvectors(A));

$$\begin{bmatrix} -55. \\ 122. \\ 67. \end{bmatrix}, \begin{bmatrix} 1. & 1. & -1.218181818 \\ -2.218181818 & 1. & 0. \\ 1. & 1. & 1. \end{bmatrix}$$
(5)