

> read `Users/Deven/Desktop/Fall 2021/Dynamic Models of Biology/DMB.txt`  
First Written: Nov. 2021

*This is DMB.txt, A Maple package to explore Dynamical models in Biology (both discrete and continuous) accompanying the class Dynamical Models in Biology, Rutgers University. Taught by Dr. Z. (Doron Zeilbeger)*

*The most current version is available on WWW at:  
<http://sites.math.rutgers.edu/~zeilberg/tokhniot/DMB.txt> .  
Please report all bugs to: DoronZeil at gmail dot com .*

*For general help, and a list of the MAIN functions,  
type "Help():". For specific help type "Help(procedure\_name);"*

-----  
*For a list of the supporting functions type: Help1();  
For help with any of them type: Help(ProcedureName);*

-----  
*For a list of the functions that give examples of Discrete-time dynamical systems (some famous),  
type: HelpDDM());*

*For help with any of them type: Help(ProcedureName);*

-----  
*For a list of the functions continuous-time dynamical systems (some famous) type: HelpCDM();  
For help with any of them type: Help(ProcedureName);*

**(1)**

> # Deven Singh  
# Assignment 20  
#OK TO POST

> # Question 1: When Beta = 0.3

> # (i)

> Help(SIRS);

*SIRS(s,i,beta,gamma,nu,N): The SIRS dynamical model with parameters beta,gamma, nu,N (see section 6.6 of Edelstein-Keshet), s is the number of Susceptibles, i is the number of infected, (the number of removed is given by N-s-i). N is the total population. Try:*

*SIRS(s,i,beta,gamma,nu,N);* (2)

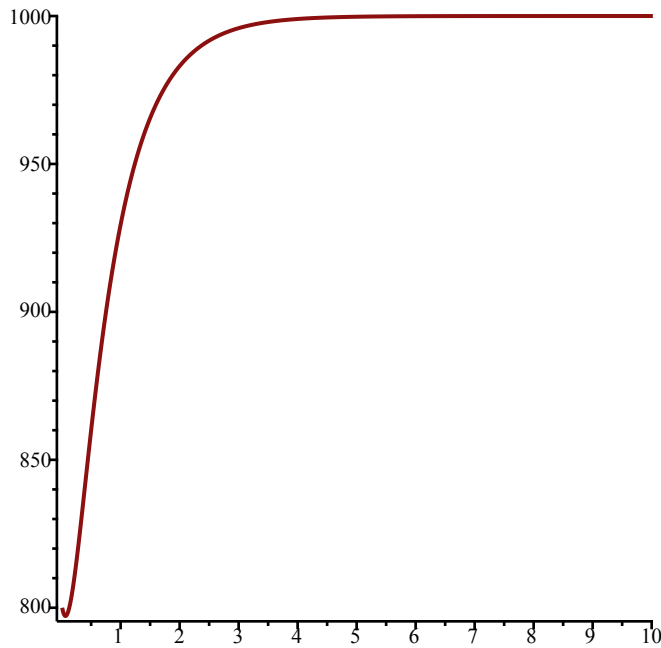
> *N := 1000 ;*  
*nu := 2 ;*

*F := SIRS*(*s, i,  $\frac{0.3 \cdot nu}{N}$ , 5, nu, N*);  
*F := [-0.0006000000000 s i + 5000 - 5 s - 5 i, 0.0006000000000 s i - 2 i]* (3)

> *EquP(F, [s, i]);*  
*{ [1000., 0.], [3333.333333, -1666.666667] }* (4)

> *SEquP(F, [s, i]);*  
*{ [1000., 0.] }* (5)

> *TimeSeries(F, [s, i], [800, 200], .01, 10, 1);*



> *Help(PhaseDiag);*

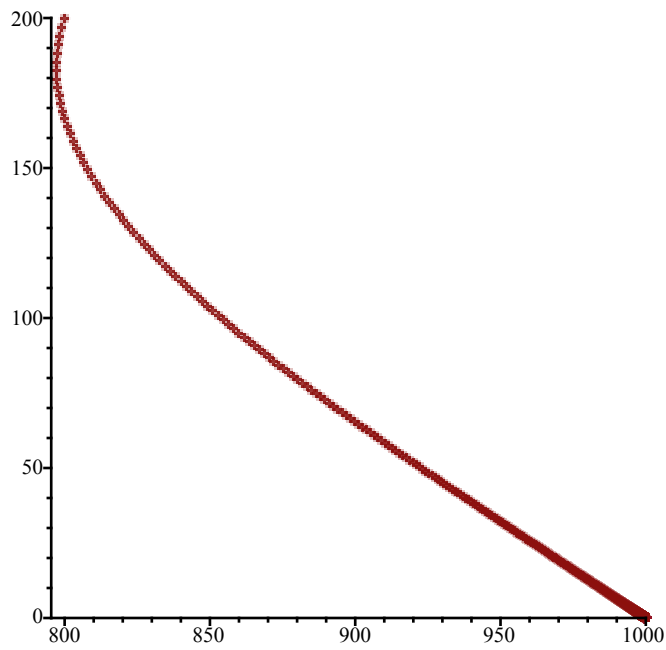
*PhaseDiag(F,x,pt,h,A):* Inputs a transformation *F* in the list of variables *x* (of length 2), i.e. a mapping from  $R^2$  to  $R^2$  gives the

*The phase diagram of the solution with initial condition  $x(0)=pt$   
 $dx/dt=F[1](x(t))$  by a discrete time dynamical system with step-size *h* from  $t=0$  to  $t=A$*

*Try:*

*PhaseDiag([x\*(1-y),y\*(1-x)],[x,y],[0.5,0.5], 0.01, 10);* (6)

> *PhaseDiag(F, [s, i], [800, 200], 0.01, 10);*



> # (ii)

>  $N := 1000$  :

$\nu := 3$  :

$$F := \text{SIRS}\left(s, i, \frac{0.3 \cdot \nu}{N}, 6, \nu, N\right);$$

$$F := [-0.000900000000000 \, s \, i + 6000 - 6 \, s - 6 \, i, 0.000900000000000 \, s \, i - 3 \, i] \quad (7)$$

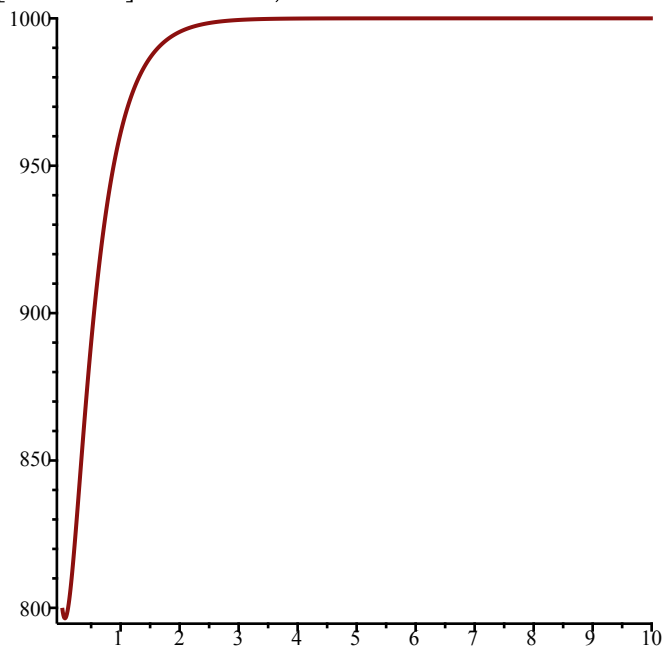
>  $\text{EquP}(F, [s, i]);$

$$\{[1000., 0.], [3333.333333, -1555.555556]\} \quad (8)$$

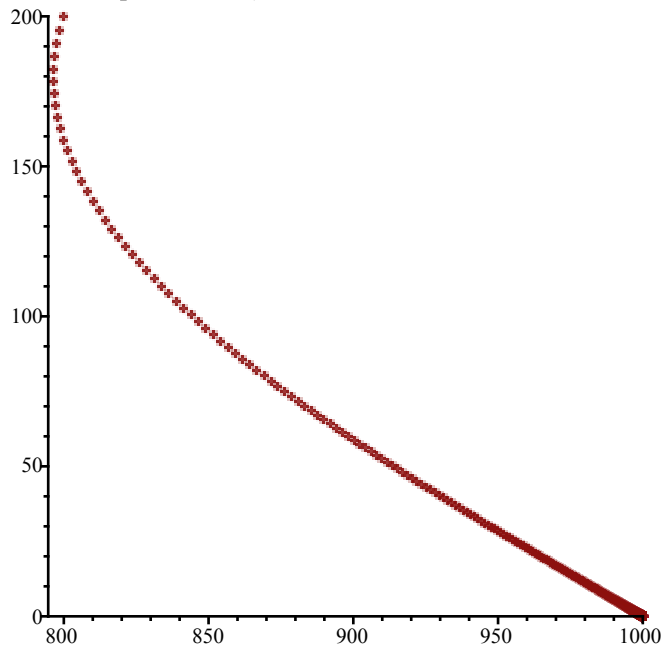
>  $\text{SEquP}(F, [s, i]);$

$$\{[1000., 0.]\} \quad (9)$$

>  $\text{TimeSeries}(F, [s, i], [800, 200], .01, 10, 1);$



> *PhaseDiag*(*F*, [*s*, *i*], [800, 200], 0.01, 10);



> #(iii)

> *N* := 1000 :

*nu* := 4 :

*F* := *SIRS*(*s*, *i*,  $\frac{0.3 \cdot \text{nu}}{N}$ , 1, *nu*, *N*);

*F* := [-0.001200000000 *s i* + 1000 - *s* - *i*, 0.001200000000 *s i* - 4 *i*] **(10)**

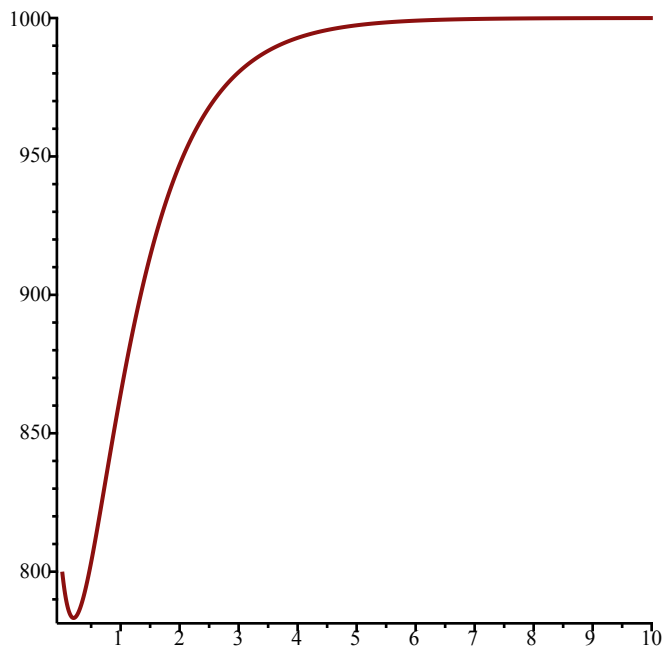
> *EquP*(*F*, [*s*, *i*]);

{[1000., 0.], [3333.333333, -466.6666667]} **(11)**

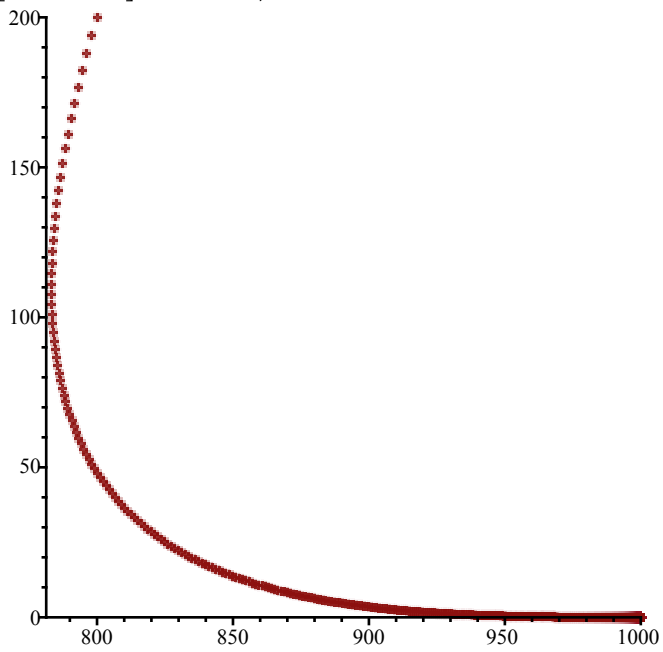
> *SEquP*(*F*, [*s*, *i*]);

{[1000., 0.]} **(12)**

> *TimeSeries*(*F*, [*s*, *i*], [800, 200], .01, 10, 1);



> `PhaseDiag(F, [s, i], [800, 200], 0.01, 10);`



> `#(iv)`

> `N := 1000 :`

`nu := 7 :`

`F := SIRS(s, i,  $\frac{0.3 \cdot \text{nu}}{N}$ , 10, nu, N);`

`F := [-0.002100000000 s i + 10000 - 10 s - 10 i, 0.002100000000 s i - 7 i]` **(13)**

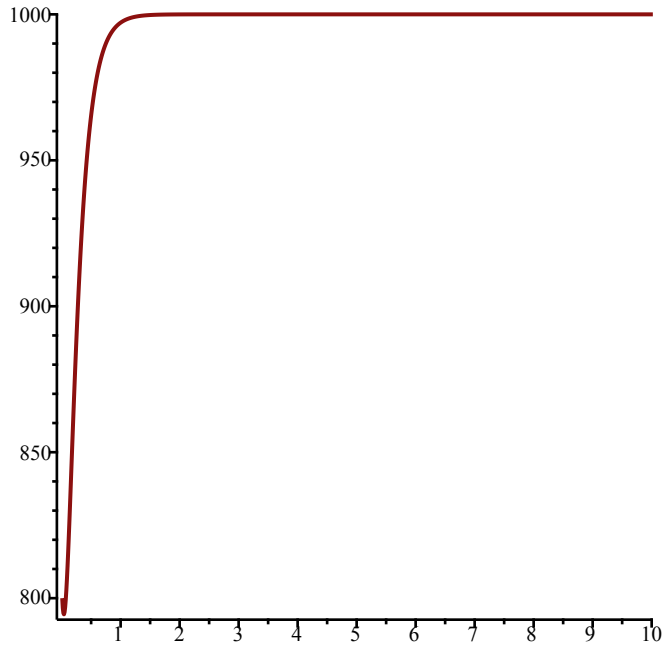
> `EquP(F, [s, i]);`

`{[1000., 0.], [3333.333333, -1372.549020]}` **(14)**

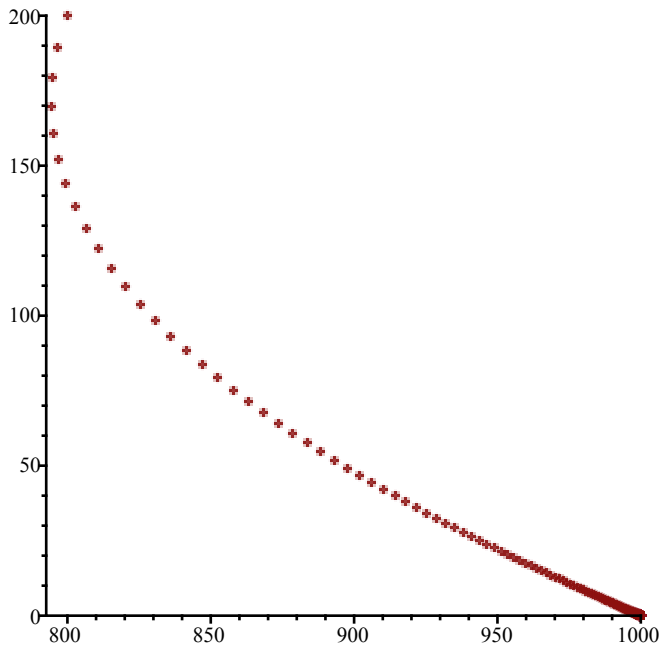
> `SEquP(F, [s, i]);`

`{[1000., 0.]}` **(15)**

> `TimeSeries(F, [s, i], [800, 200], .01, 10, 1);`



> `PhaseDiag(F, [s, i], [800, 200], 0.01, 10);`



> `#Question 1: When Beta = 0.9`

> `#(i)`

> `N := 1000 :`

`nu := 2 :`

`F := SIRS(s, i,  $\frac{0.9 \cdot \text{nu}}{N}$ , 5, nu, N);`

`F := [-0.001800000000 s i + 5000 - 5 s - 5 i, 0.001800000000 s i - 2 i]` (16)

> `EquP(F, [s, i]);`

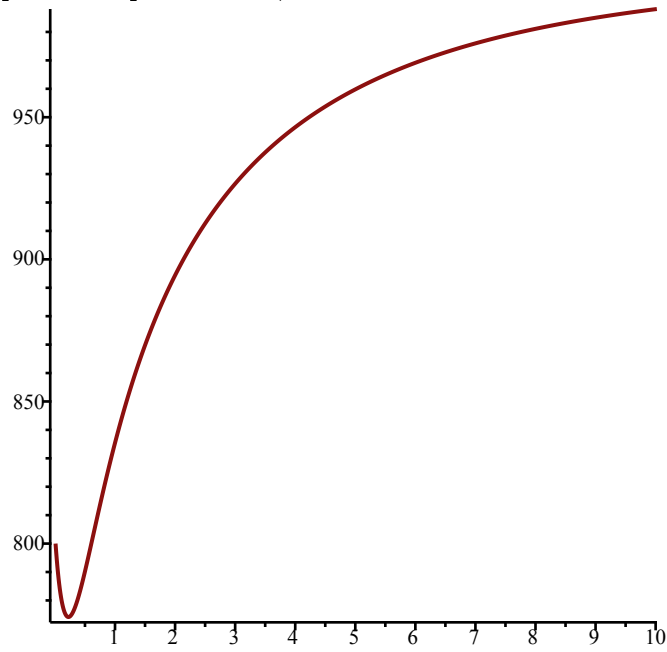
`{[1000., 0.], [1111.111111, -79.36507937]}` (17)

> *SEquP*(*F*, [*s*, *i*]);

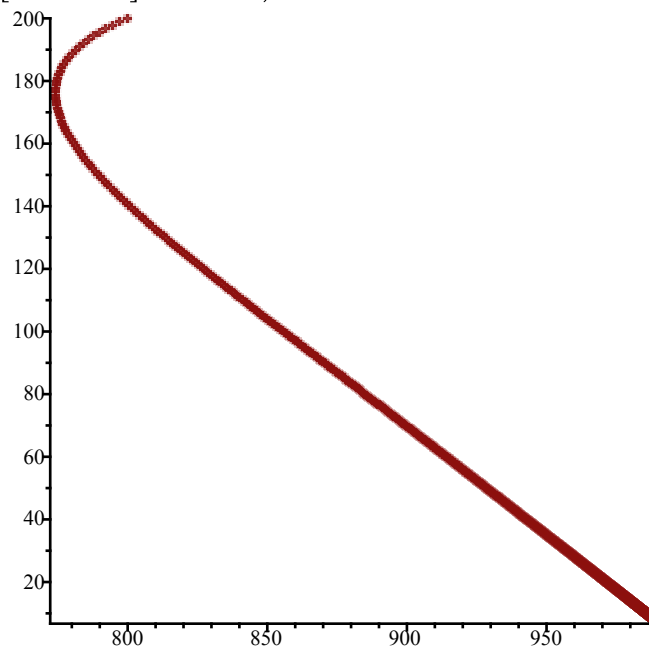
{[1000., 0.]}

(18)

> *TimeSeries*(*F*, [*s*, *i*], [800, 200], .01, 10, 1);



> *PhaseDiag*(*F*, [*s*, *i*], [800, 200], 0.01, 10);



> #(ii)

> *N* := 1000 :

*nu* := 3 :

*F* := *SIRS*(*s*, *i*,  $\frac{0.9 \cdot \text{nu}}{N}$ , 6, *nu*, *N*);

*F* := [-0.002700000000 *s i* + 6000 - 6 *s* - 6 *i*, 0.002700000000 *s i* - 3 *i*]

(19)

> *EquP*(*F*, [*s*, *i*]);

(20)

```
{[1000., 0.], [1111.111111, -74.07407407]}
```

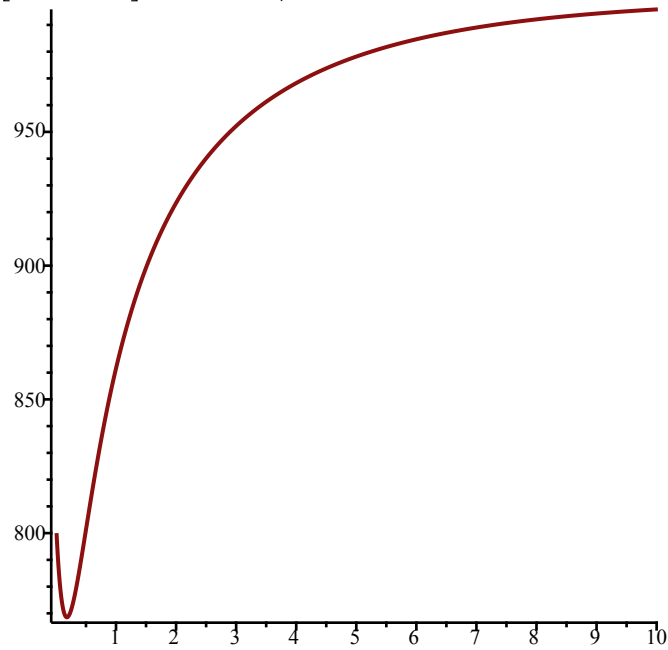
 (20)

```
> SEquP(F, [s, i]);
```

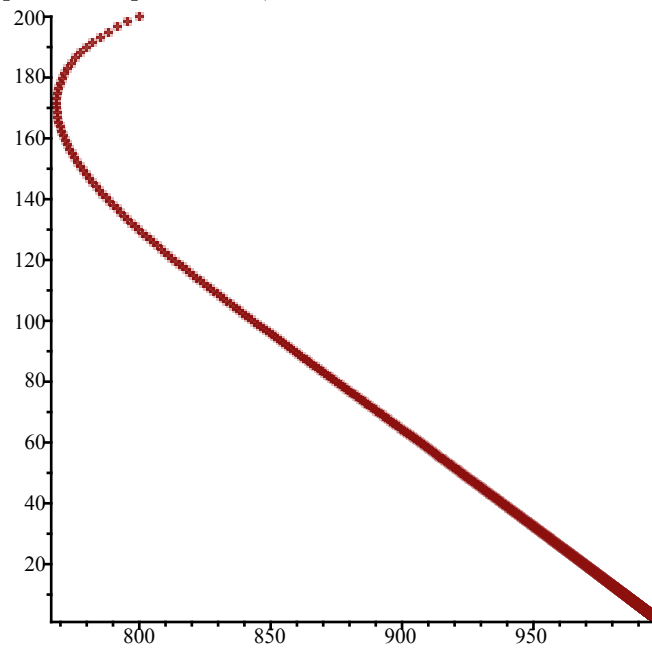
```
{[1000., 0.]}
```

 (21)

```
> TimeSeries(F, [s, i], [800, 200], .01, 10, 1);
```



```
> PhaseDiag(F, [s, i], [800, 200], 0.01, 10);
```



```
> #(iii)
```

```
> N := 1000 :
```

```
nu := 4 :
```

```
F := SIRS(s, i,  $\frac{0.9 \cdot \text{nu}}{N}$ , 1, nu, N);
```

```
F := [-0.003600000000 s i + 1000 - s - i, 0.003600000000 s i - 4 i]
```

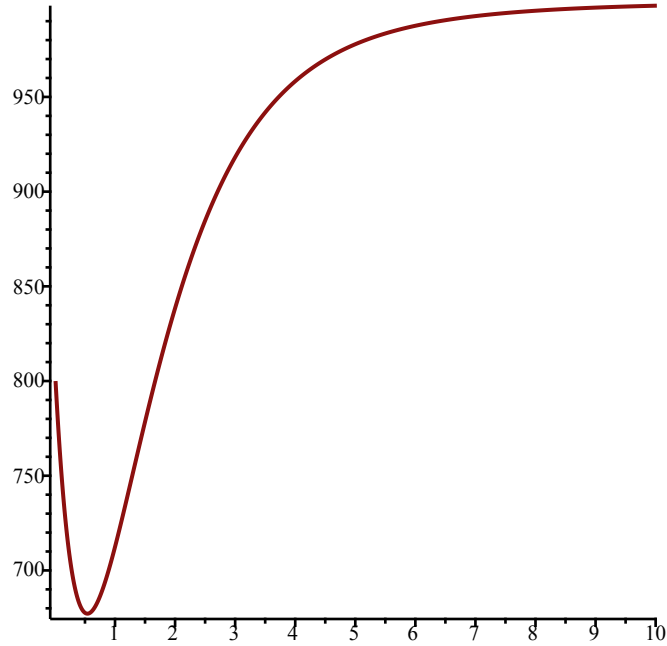
 (22)



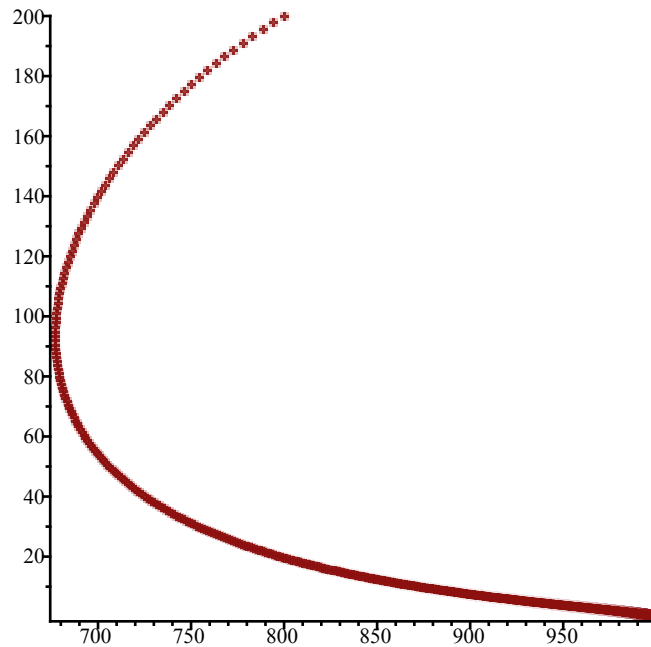
>  $EquP(F, [s, i]);$   
 $\{[1000., 0.], [1111.111111, -22.22222222]\}$  (23)

>  $SEquP(F, [s, i]);$   
 $\{[1000., 0.]\}$  (24)

>  $TimeSeries(F, [s, i], [800, 200], .01, 10, 1);$



>  $PhaseDiag(F, [s, i], [800, 200], 0.01, 10);$



>  $\#(iv)$

>  $N := 1000 :$

$nu := 7 :$

$F := SIRS\left(s, i, \frac{0.9 \cdot nu}{N}, 10, nu, N\right);$

(25)

$$F := [-0.006300000000 s i + 10000 - 10 s - 10 i, 0.006300000000 s i - 7 i] \quad (25)$$

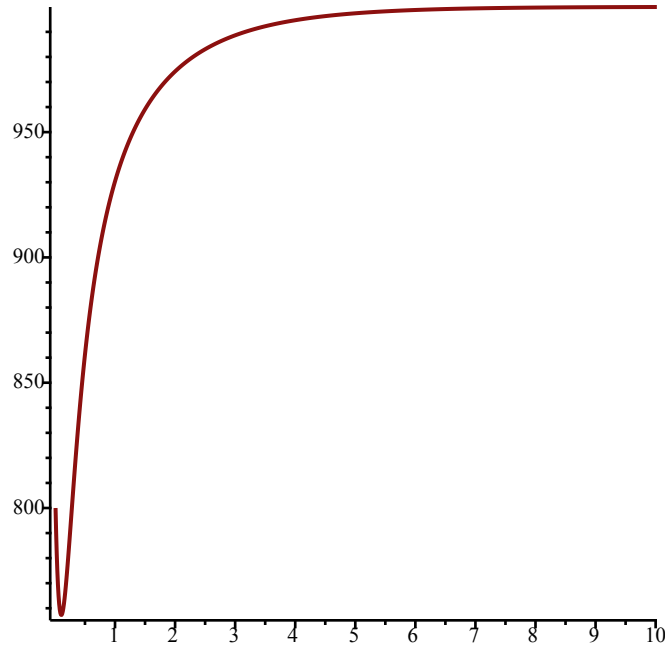
> *EquP*(*F*, [*s*, *i*]);

$$\{[1000., 0.], [1111.111111, -65.35947712]\} \quad (26)$$

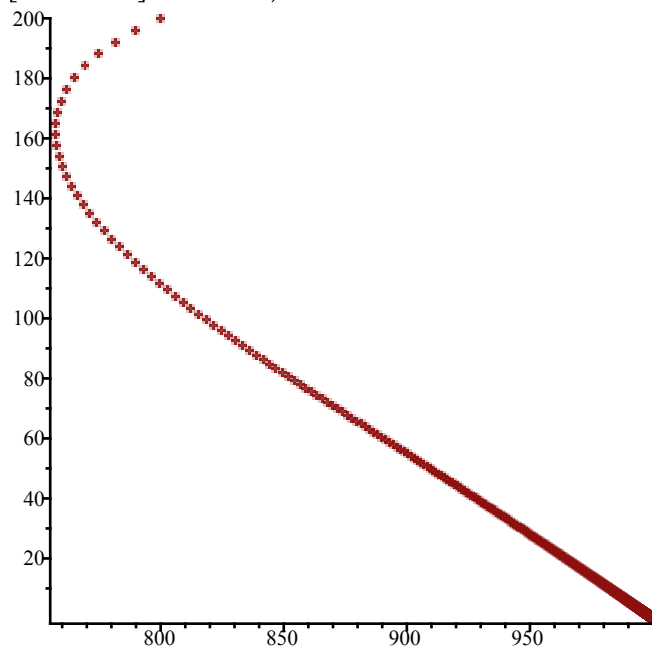
> *SEquP*(*F*, [*s*, *i*]);

$$\{[1000., 0.]\} \quad (27)$$

> *TimeSeries*(*F*, [*s*, *i*], [800, 200], .01, 10, 1);



> *PhaseDiag*(*F*, [*s*, *i*], [800, 200], 0.01, 10);



> #Question 1: When Beta = 3.9

> #(i)

> N := 1000 :

nu := 2 :

$$F := \text{SIRS}\left(s, i, \frac{3.9 \cdot \text{nu}}{N}, 5, \text{nu}, N\right);$$

$$F := [-0.007800000000 s i + 5000 - 5 s - 5 i, 0.007800000000 s i - 2 i] \quad (28)$$

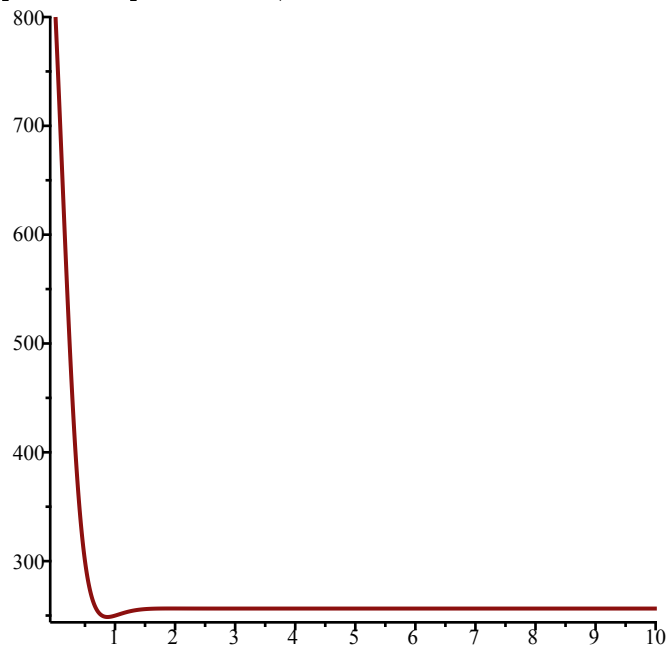
> EquP(F, [s, i]);

$$\{[256.4102564, 531.1355311], [1000., 0.]\} \quad (29)$$

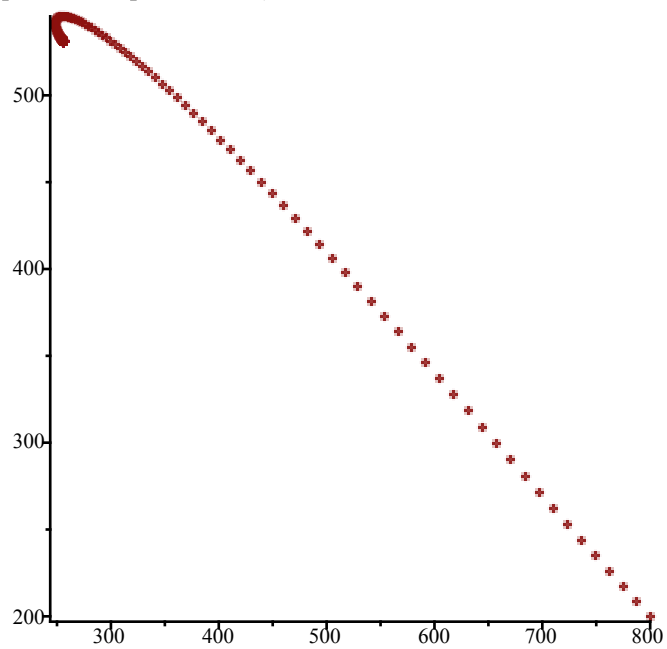
> SEquP(F, [s, i]);

$$\{[256.4102564, 531.1355311]\} \quad (30)$$

> TimeSeries(F, [s, i], [800, 200], .01, 10, 1);



> PhaseDiag(F, [s, i], [800, 200], 0.01, 10);



> #(ii)

> N := 1000 :

nu := 3 :

$$F := SIRS\left(s, i, \frac{3.9 \cdot \text{nu}}{N}, 6, \text{nu}, N\right);$$

$$F := [-0.01170000000 s i + 6000 - 6 s - 6 i, 0.01170000000 s i - 3 i] \quad (31)$$

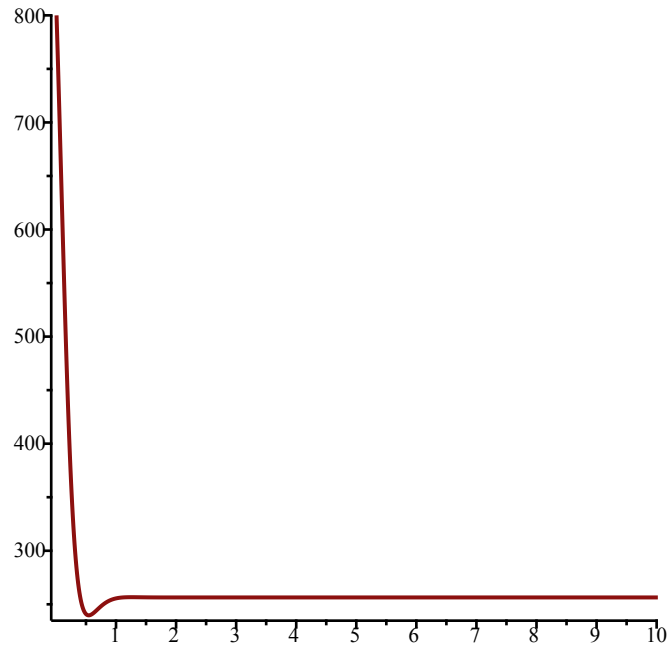
> EquP(F, [s, i]);

$$\{[256.4102564, 495.7264957], [1000., 0.]\} \quad (32)$$

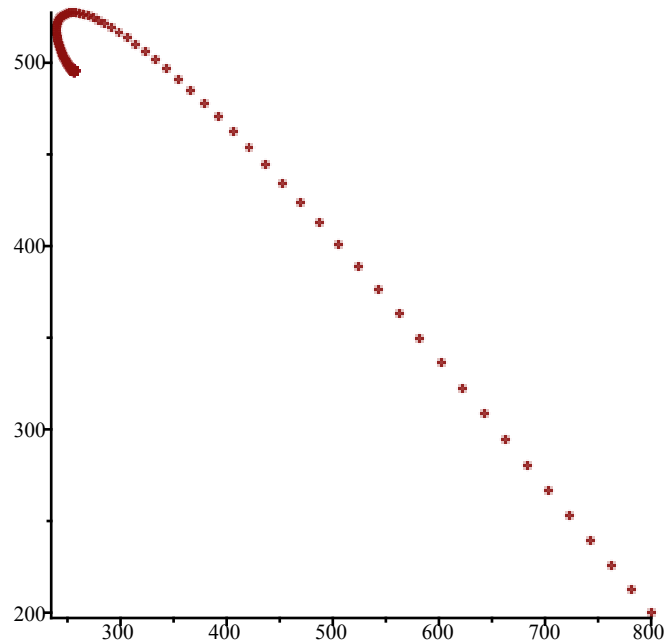
> SEquP(F, [s, i]);

$$\{[256.4102564, 495.7264957]\} \quad (33)$$

> TimeSeries(F, [s, i], [800, 200], .01, 10, 1);



> PhaseDiag(F, [s, i], [800, 200], 0.01, 10);



> #(iii)

```
> N := 1000 :
nu := 4 :
F := SIRS(s, i,  $\frac{3.9 \cdot \text{nu}}{N}$ , 1, nu, N);
F := [-0.01560000000 s i + 1000 - s - i, 0.01560000000 s i - 4 i]
```

**(34)**

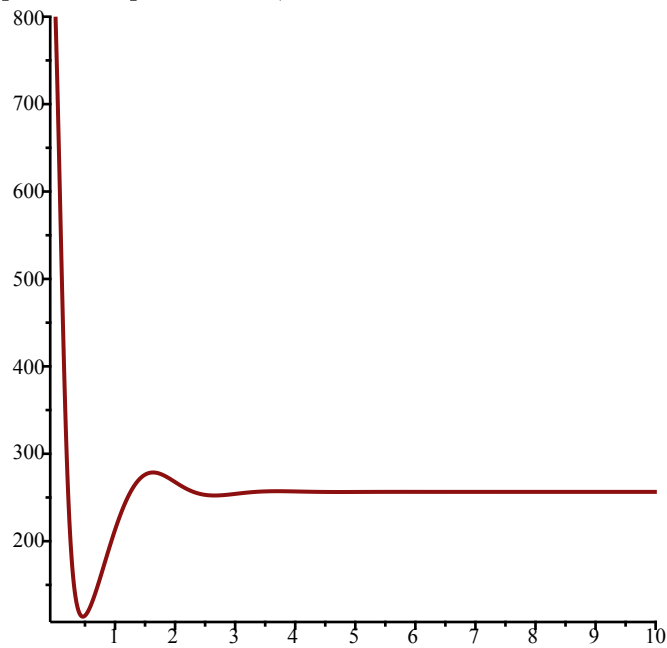
```
> EquP(F, [s, i]);
{[256.4102564, 148.7179487], [1000., 0.]}
```

**(35)**

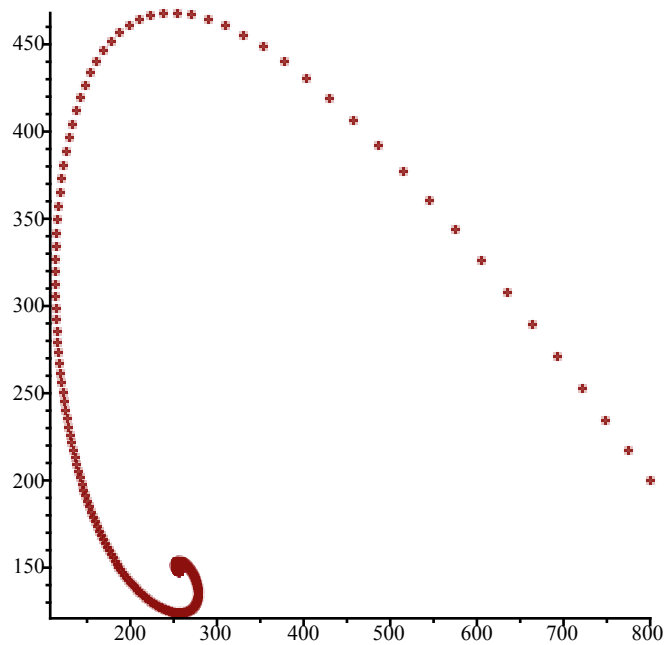
```
> SEquP(F, [s, i]);
{[256.4102564, 148.7179487]}
```

**(36)**

```
> TimeSeries(F, [s, i], [800, 200], .01, 10, 1);
```



```
> PhaseDiag(F, [s, i], [800, 200], 0.01, 10);
```



```

> #(iv)
> N := 1000 :
nu := 7 :
F := SIRS(s, i,  $\frac{3.9 \cdot \text{nu}}{N}$ , 10, nu, N);
F := [-0.02730000000 s i + 10000 - 10 s - 10 i, 0.02730000000 s i - 7 i]

```

**(37)**

```

> EquP(F, [s, i]);

```

**(38)**

```

> SEquP(F, [s, i]);

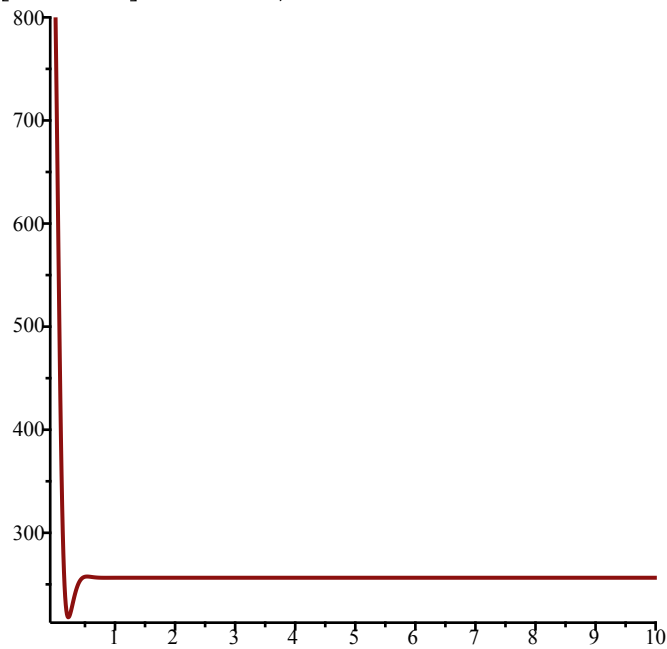
```

**(39)**

```

> TimeSeries(F, [s, i], [800, 200], .01, 10, 1);

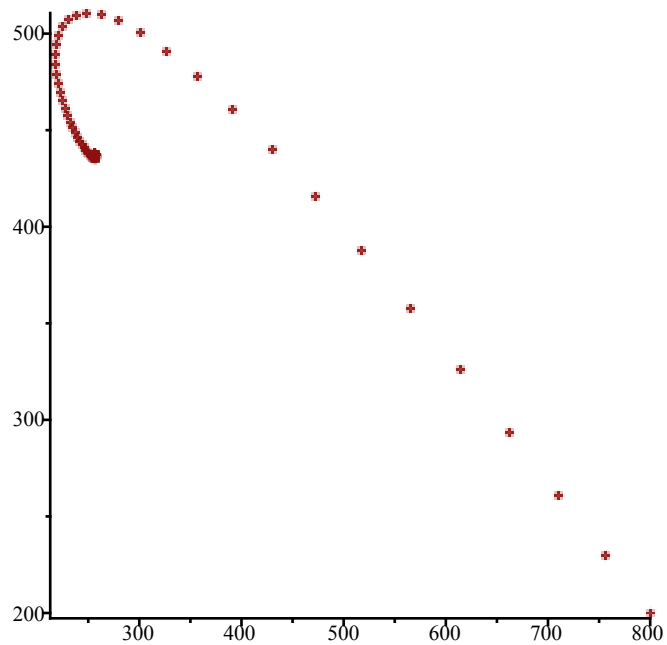
```



```

> PhaseDiag(F, [s, i], [800, 200], 0.01, 10);

```



> #Question 2

>  $F1 := \text{RandNice}([x, y], 3);$   
 $F1 := [(3 - 3x - y)(2 - x - y), (2 - 2x - 3y)(3 - 2x - 2y)]$  (40)

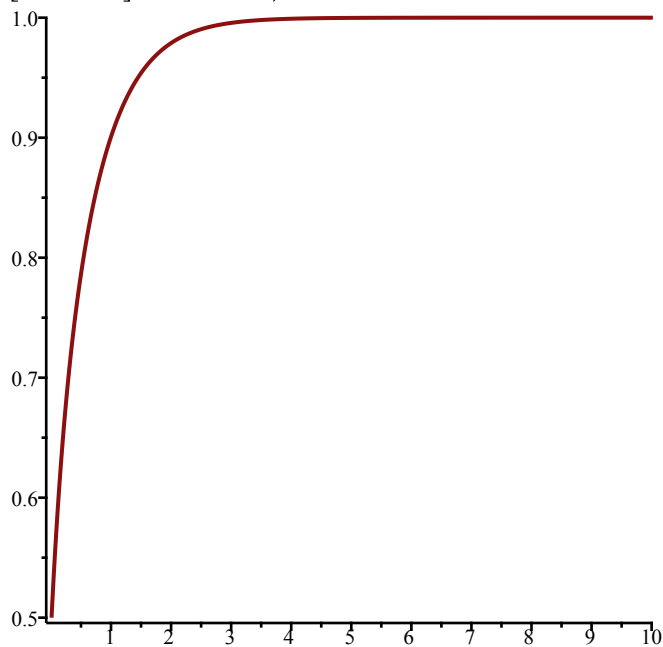
>  $\text{EquP}(F1, [x, y]);$

$\left\{ [1, 0], [4, -2], \left[ \frac{3}{4}, \frac{3}{4} \right] \right\}$  (41)

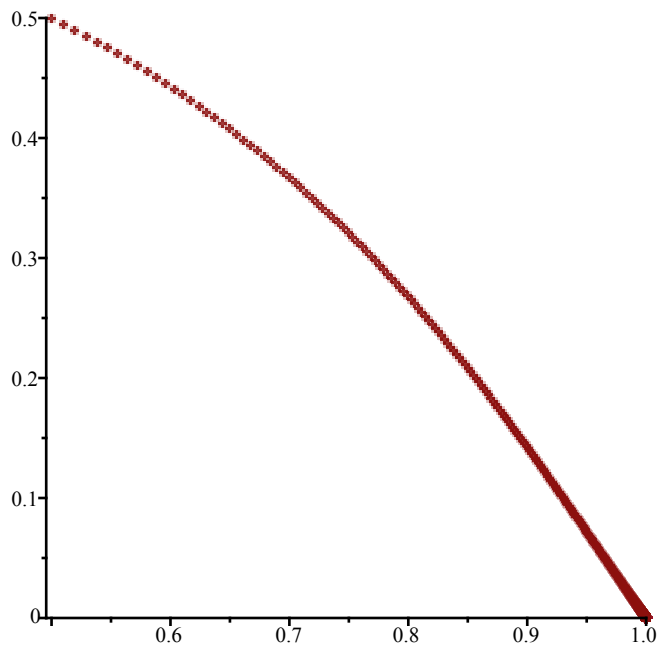
>  $\text{SEquP}(F1, [x, y]);$

$\{ [1., 0.] \}$  (42)

>  $\text{TimeSeries}(F1, [x, y], [0.5, 0.5], .01, 10, 1);$



>  $\text{PhaseDiag}(F1, [x, y], [0.5, 0.5], 0.01, 10);$

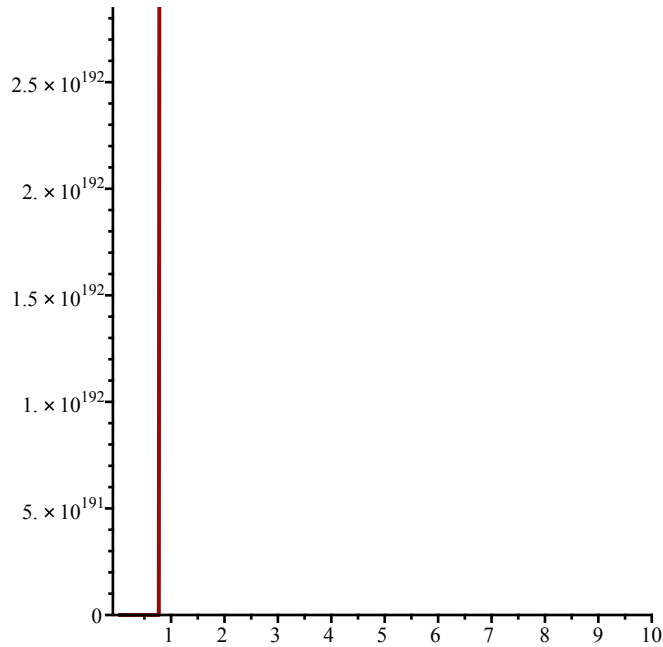


>  $F2 := \text{RandNice}([x, y], 3);$   
 $F2 := [(1 - 2x - y)(2 - 3x - 3y), (3 - 2x - y)(3 - 3x - 3y)]$  (43)

>  $\text{EquP}(F2, [x, y]);$   
 $\left\{ [0, 1], \left[ \frac{7}{3}, -\frac{5}{3} \right] \right\}$  (44)

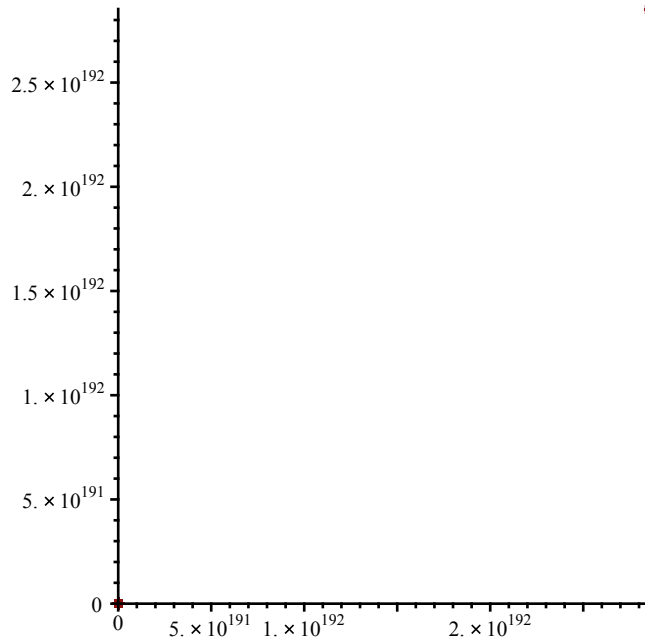
>  $\text{SEquP}(F2, [x, y]);$   
 $\emptyset$  (45)

>  $\text{TimeSeries}(F2, [x, y], [0.5, 0.5], .01, 10, 1);$



>  $\text{PhaseDiag}(F2, [x, y], [0.5, 0.5], 0.01, 10);$



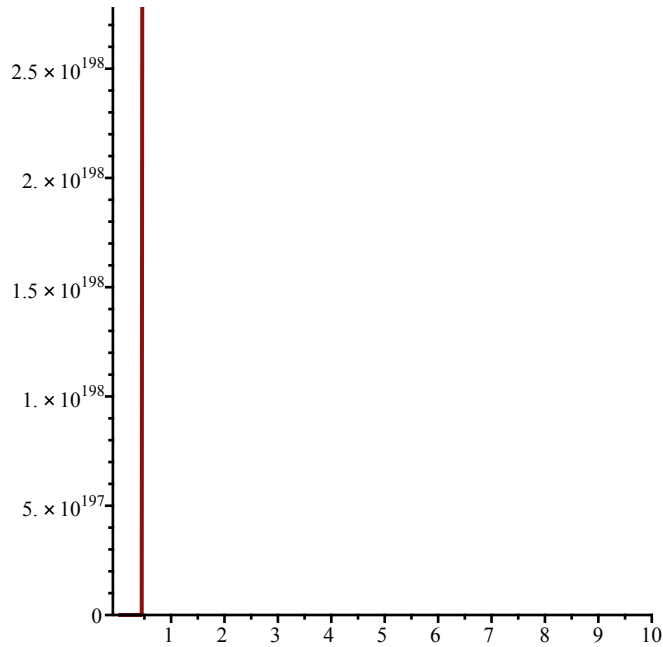


>  $F3 := \text{RandNice}([x, y], 3);$   
 $F3 := [(1 - 3x - 3y)(2 - 3x - y), (1 - 3x - y)(1 - 2x - 2y)]$  (46)

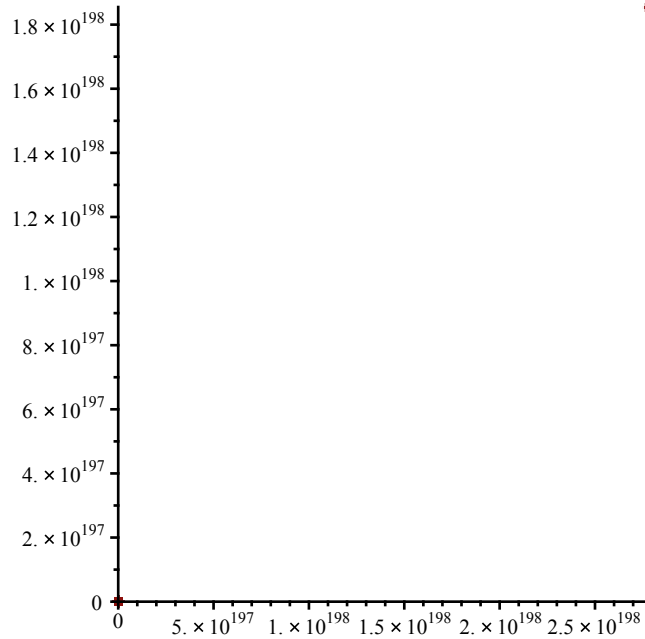
>  $\text{EquP}(F3, [x, y]);$   
 $\left\{ \left[ \frac{1}{3}, 0 \right], \left[ \frac{3}{4}, -\frac{1}{4} \right] \right\}$  (47)

>  $\text{SEquP}(F3, [x, y]);$   
 $\emptyset$  (48)

>  $\text{TimeSeries}(F3, [x, y], [0.5, 0.5], .01, 10, 1);$



>  $\text{PhaseDiag}(F3, [x, y], [0.5, 0.5], 0.01, 10);$



> #Question 3

> # 
$$\frac{x(n) = 3 + x(n-2) + x(n-3) + x(n-4)}{(1 + x(n-1) + x(n-3))}$$

> # Orbk takes too long to compute past K2=40. I am trying to figure out a solution to this problem

> evalf(Orbk(4, z,  $\frac{3 + z[3] + z[2] + z[1]}{1 + z[4] + z[2]}$ , [1, 4, 19, 32], 30, 40));

[1.835435444, 1.819261539, 1.822007470, 1.826194343, 1.818049841, 1.822480262,  
1.824702558, 1.820999184, 1.823957273, 1.823989772, 1.821803818] (49)

> E := ToSys(4, z,  $\frac{3 + z[3] + z[2] + z[1]}{1 + z[4] + z[2]}$ );

$$E := \left[ \frac{3 + z_3 + z_2 + z_1}{1 + z_4 + z_2}, z_1, z_2, z_3 \right], [z_1, z_2, z_3, z_4]$$
 (50)

> SFP(E);

{[1.822875656, 1.822875656, 1.822875656, 1.822875656]} (51)

>