

Dynamical Modeling HW15 - okay to Post

$$2) (i) \quad x(n) = \frac{x(n-1) + 2x(n-2) + 3x(n-3) + 11x(n-4)}{x(n-1) + x(n-3)}$$

$$x_1(n) = \frac{x_1(n-1) + 2x_1(n-2) + 3x_1(n-3) + 11x_1(n-4)}{x_1(n-1) + x_1(n-3)}$$

$$x_2(n) = x_1(n-1)$$

$$x_3(n) = x_1(n-2)$$

$$x_4(n) = x_1(n-3)$$

$$x_1(n) = \frac{x_1(n-1) + 2x_2(n-1) + 3x_3(n-1) + 11x_4(n-1)}{x_1(n-1) + x_3(n-1)}$$

$$x_2(n) = x_1(n-1)$$

$$x_3(n) = x_1(n-2)$$

$$x_4(n) = x_1(n-3)$$

$$(ii) \quad f = \frac{z[1] + 2 \cdot z[2] + 3 \cdot z[3] + 11 \cdot z[4]}{z[1] + z[3]}$$

$$k = 4$$

$$|N| = [1, 5, 5, 2]$$

output provided in Maple

some
=> don't
duplicate

some
=> don't
duplicate

some
=> don't
duplicate

4)

Parent Genotype	Frequency	Offspring Genotype Frequencies		
		AA	Aa	aa
Mom = AA, Dad = AA	u^2	u^2	0	0
Mom = AA, Dad = Aa	$2uv$	uv	uv	0
Mom = Aa, Dad = AA	$2uv$	uv	uv	0
Mom = AA, Dad = aa	$2uw$	0	$2uw$	0
Mom = aa, Dad = AA	$2uw$	0	$2uw$	0
Mom = Aa, Dad = Aa	v^2	$v^2/4$	$v^2/2$	$v^2/4$
Mom = Aa, Dad = aa	$2vw$	0	vw	vw
Mom = aa, Dad = Aa	$2vw$	0	vw	vw
Mom = aa, Dad = aa	w^2	0	0	w^2
Total		$u^2 + uv + \frac{v^2}{4}$	$uv + 2uw + vw + \frac{v^2}{2}$	$\frac{v^2}{4} + vw + w^2$

↑
S3(a)

↑
S3(b)

↑
S3(c)

> # Nikita John, Assignment 15 (Okay to Post)
#October 25th, 2021

> #M15.txt: Maple code for Lecture 15 of Dynamical Models in Biology, Fall 2021 (taught by Dr. Z.)

```
Help15 := proc ( ) : print( ` HW3(u,v,w), HW2(u,v) , Dis1(F,y,y0,h,A), ToSys(k,z,f,INI) ` ) :end:
```

#ToSys(k,z,f,INI): converts the kth order difference equation $x(n)=f(x[n-1],x[n-2],\dots,x[n-k])$ to a first-order system

```
#x1(n)=F(x1(n-1),x2(n-1), ...,xk(n-1))
```

```
#x2(n)=x1(n-1)
```

```
#...
```

#xk(n)=x[k-1](n-1). It gives the underlying transformation phrased in terms of $z[1],\dots,z[k]$, followed by the initial conditions. Try:

```
#ToSys:=proc(2,z,z[1]+z[2],[1,1])
```

```
ToSys := proc(k, z, f, INI) local i :
```

```
[f, seq(z[i-1], i=2 ..k)], INI :
```

```
end:
```

#HW3(u,v,w): The Hardy-Weinberg underlying transformation with (u,v,w) , Eqs. (53a,53b, 53c) in Edelestein-Keshet Ch. 3

```
HW3 := proc(u, v, w) : [u^2 + u*v + (1/4)*v^2, u*v + 2*u*w + 1/2*v^2 + v*w, 1/4*v^2 + v*w + w^2] :end:
```

#HW2(u,v): The Hardy-Weinberg underlying transformation with (u,v,w) , Eqs. (53a,53b,53c) in Edelestein-Keshet Ch. 3 using the fact that $u+v+w=1$

```
HW2 := proc(u, v) : expand([u^2 + u*v + (1/4)*v^2, u*v + 2*u*(1-u-v) + 1/2*v^2 + v*(1-u-v)]) :end:
```

#Dis1(F,y,y0,h,A): The approximate orbit of the Dynamical system approximating the 1D for the autonomous continuous dynamical process $dy/dt=F(y(t))$, $y(0)=y0$ with mesh size h from $t=0$ to $t=A$

```
Dis1 := proc(F, y, y0, h, A) local L, x, i :
```

```
L := Orb(x + h*subs(y=x, F), x, y0, 0, trunc(A/h)) :
```

```
L := [seq([i*h, L[i]], i=1 ..nops(L))] :
```

```
end:
```

```
##old stuff
```

#M13.txt: Maple code for Lecture 13 of Dynamical Models in Biology, Fall 2021 (taught by Dr. Z.)

```
Help13 := proc( ) :  
    print( `RT2(x,y,d,K), Orb2(F,x,y,pt0,K1,K2), FP2(F,x,y), SFP2(F,x,y), PlotOrb2(L), FP2drz  
    (F,x,y), SFP2drz(F,x,y) `) :end:
```

```
with(LinearAlgebra) :
```

#RT2(x,y,d,K): A random rational transformation of degree d from R^2 to R^2 with positive integer coefficients from 1 to K. The inputs are variables x and y and

#the output is a pair of expressions of (x,y) representing functions. It is for generating examples

#Try:

```
#RT2(x,y,2,10);
```

```
RT2 := proc(x, y, d, K) local ra, i, j, f, g :
```

```
ra := rand(1..K) : #random integer from -K to K
```

```
f := add(add(ra( ) * x^i * y^j, j=0..d-i), i=0..d) / add(add(ra( ) * x^i * y^j, j=0..d-i), i=0  
..d) :
```

```
g := add(add(ra( ) * x^i * y^j, j=0..d-i), i=0..d) / add(add(ra( ) * x^i * y^j, j=0..d-i), i=0  
..d) :
```

```
[f, g] :
```

```
end:
```

#Orb2(F,x,y,pt,K1,K2): Inputs a mapping $F=[f,g]$ from R^2 to R^2 where f and g describe functions of x and y, an initial point $pt0=[x0,y0]$

#outputs the orbit starting at discrete time K1 and ending in discrete time K2. Try

```
#F:=RT2(x,y,2,10);
```

```
#Orb2(F,x,y,[1.1,1.2],1000,1010);
```

```
Orb2 := proc(F, x, y, pt0, K1, K2) local pt, L, i :
```

```
pt := pt0 :
```

```
for i from 1 to K1-1 do
```

```
pt := subs( {x=pt[1], y=pt[2]}, F) :
```

```
od:
```

```
L := [ ] :
```

```
for i from K1 to K2 do
```

```
L := [op(L), pt] :
```

```
pt := subs( {x=pt[1], y=pt[2]}, F) :
```

```
od:
```

```
L :
```

```
end:
```

#FP2(F,x,y): The list of fixed points of the transformation $[x,y] \rightarrow F$. Try

```
#FP2([x-y,x=y],x,y);
```

```
FP2 := proc(F, x, y) local L, i :
```

```
L := [solve( {F[1]=x, F[2]=y}, {x, y} )]:
```

```
[seq(subs(L[i], [x, y]), i = 1 ..nops(L))]:
```

```
end:
```

```
#SFP2(F,x,y): The list of Stable fixed points of the transformation [x,y]->F. Try
```

```
#SFP2([(1+x)/(1+y), (1+7*y)/(4+x)],x,y);
```

```
SFP2 := proc(F, x, y) local L, J, S, J0, i, pt, EV:
```

```
L := evalf(FP2(F, x, y)):
```

```
#F is the list of ALL fixed points of the transformation [x,y]->F using the previous procedure  
FP2(F,x,y), but since we are interested in numbers we take the floating point version using  
evalf
```

```
J := Matrix(normal([ [diff(F[1], x), diff(F[1], y)], [diff(F[2], x), diff(F[2], y)] ])):
```

```
#J is the Jacobian matrix in general (in terms of the variables x and y). Note that J is a  
SYMBOLIC matrix featuring variables x and y
```

```
S := []: #S is the list of stable fixed points that starts out empty
```

```
for i from 1 to nops(L) do #we examine it case by case
```

```
pt := L[i]: #pt is the current fixed point to be examined
```

```
J0 := subs( {x=pt[1], y=pt[2]}, J):
```

```
#J0 is the NUMERICAL matrix obtained by plugging-in the examined fixed pt
```

```
EV := Eigenvalues(J0):
```

```
# We used Maple's command Eigenvalues to find the eigenvalues of this 2 by 2 matrix
```

```
if abs(EV[1]) < 1 and abs(EV[2]) < 1 then
```

```
S := [op(S), pt]:
```

```
#If both eigenvalues have absolute value less than 1 it means that they are stable, so we  
append the examined fixed point, pt, to the list of fixed points
```

```
fi:
```

```
od:
```

```
S: #the output is S
```

```
end:
```

```
###added Oct. 17, 20221
```

```
with(plots):
```

```
PlotOrb1 := proc(L) local i, d:
```

```
d := textplot([L[1], 0, 0]):
```

```

for i from 2 to nops(L) do
d := d, textplot([L[i], 0, i-1]) :
od:
display(d) :
end:

```

```

PlotOrb2 := proc(L) local i, d :

```

```

d := textplot([op(L[1]), 0]) :

```

```

for i from 2 to nops(L) do
d := d, textplot([op(L[i]), i-1]) :
od:
display(d) :
end:
###End added Oct. 17, 20221

```

```

###old stuff

```

```

#M11.txt: Maple code for Lecture 11 of Dynamical Models in Biology taught by Dr. Z.

```

```

Help11 := proc ( ) : print( `SFPe(f,x), Orbk(k,z,f,INI,K1,K2) `) end:

```

SFPe(f,x): The set of fixed points of $x \rightarrow f(x)$ done exactly (and allowing symbolic parameters), followed by the condition of stability (if it is between -1 and 1 it is stable)

```

#Try: FPe(k*x*(1-x),x);

```

```

#VERSION OF Oct. 12, 2021 (avoiding division by 0)

```

```

SFPe := proc(f, x) local f1, L, i, M :

```

```

f1 := normal(diff(f, x)) :

```

```

L := [solve(numer(f-x), x)] :

```

```

M := [ ] :

```

```

for i from 1 to nops(L) do
if subs(x = L[i], denom(f1)) ≠ 0 then
  M := [op(M), [L[i], normal(subs(x = L[i], f1))]] :
fi:
od:
M:
end:

```

```

#Added after class

```

Orbk(k,z,f,INI,K1,K2): Given a positive integer k , a letter (symbol), z , an expression f of z [1], ..., z [k] (representing a multi-variable function of the variables z [1], ..., z [k])

a vector INI representing the initial values [x [1], ..., x [k]], and (in applications) positive

```

integes K1 and K2, outputs the

#values of the sequence starting at n=K1 and ending at n=K2. of the sequence satisfying the
difference equation
##x[n]=f(x[n-1],x[n-2],..., x[n-k+1]):

#This is a generalization to higher-order difference equation of procedure Orb(f,x,x0,K1,K2)
. For example
#Orbk(1,z,5/2*z[1]*(1-z[1]),[0.5],1000,1010); should be the same as
#Orb(5/2*z[1]*(1-z[1]),z[1],[0,5],1000,1010);
#Try:
#Orbk(2,z,(5/4)*z[1]-(3/8)*z[2],[1,2],1000,1010);
Orbk := proc(k, z, f, INI, K1, K2) local L, i, newguy :
L := INI: #We start out with the list of initial values

if not (type(k, integer) and type(z, symbol) and type(INI, list) and nops(INI) = k and type(K1,
integer) and type(K2, integer) and K1 > 0 and K2 > K1) then
#checking that the input is OK
print(`bad input`):
RETURN(FAIL):
fi:

while nops(L) < K2 do
newguy := subs( {seq(z[i] = L[-i], i = 1 ..k) }, f) :
#Using what we know about the value yesterday, the day before yesterday, ... up to k days
before yesterday we find the value of the sequence today
L := [op(L), newguy]: #we append the new value to the running list of values of our sequence
od:

[op(K1 ..K2, L)]:

end:

#####STAF FROM M9.txt
#M9.txt: Maple Code for "Dynamical models in Biology" (Math 336) taught by Dr. Z., Lecture 9

Help9 := proc( ):
print(`Orb(f,x,x0,K1,K2), Orb2D(f,x,x0,K) , FP(f,x) , SFP(f,x) , Comp(f,x) `) :end:

#Orb(f,x,x0,K1,K2): Inputs an expression f in x (desccribing) a function of x, an initial point,
x0, and a positive integer K, outputs
#the values of x[n] from n=K1 to n=K2. Try: where x[n]=f(x[n-1]), . Try:
#Orb(2*x*(1-x),x,0.4,1000,2000);
Orb := proc( f, x, x0, K1, K2) local x1, i, L :
x1 := x0 :

for i from 1 to K1 do

```

```
x1 := subs(x=x1,f) :  
#we don't record the first values of K1, since we are interested in the long-time behavior of  
the orbit
```

```
od:
```

```
L := [x1] :
```

```
for i from K1 to K2 do
```

```
x1 := subs(x=x1,f) : #we compute the next member of the orbit
```

```
L := [op(L), x1] : #we append it to the list
```

```
od:
```

```
L : #that's the output
```

```
end:
```

```
#Orb2D(f,x,x0,K): 2D version of Orb(f,x,x0,0,K), just for illustration
```

```
Orb2D := proc(f, x, x0, K) local L, L1, i :
```

```
L := Orb(f, x, x0, 0, K) :
```

```
L1 := [[L[1], 0], [L[1], L[2]], [L[2], L[2]]] :
```

```
for i from 3 to nops(L) do
```

```
L1 := [op(L1), [L[i-1], L[i]], [L[i], L[i]]] :
```

```
od:
```

```
L1 :
```

```
end:
```

```
#FP(f,x): The list of fixed points of the map  $x \rightarrow f$  where  $f$  is an expression in  $x$ . Try:
```

```
#FP(2*x*(1-x),x);
```

```
FP := proc(f, x)
```

```
evalf([solve(f=x, x)]) :
```

```
end:
```

```
#SFP(f,x): The list of stable fixed points of the map  $x \rightarrow f$  where  $f$  is an expression in  $x$ . Try:
```

```
#SFP(2*x*(1-x),x);
```

```
SFP := proc(f, x) local L, i, f1, pt, Ls :
```

```
L := FP(f, x) : #The list of fixed points (including complex ones)
```

```
Ls := [] : #Ls is the list of stable fixed points, that starts out as the empty list
```

```
f1 := diff(f, x) : #The derivative of the function  $f$  w.r.t.  $x$ 
```

```
for i from 1 to nops(L) do
```

```
pt := L[i] :
```

```
if abs(subs(x=pt,f1)) < 1 then
```

```
Ls := [op(Ls), pt] : # if  $pt$ , is stable we add it to the list of stable points
```


fi:

od:

Ls : #The last line is the output

end:

#Comp(f,x): f(f(x))

*Comp := **proc**(f, x) : normal(subs(x=f, f)) : **end:***

##added Oct. 17, 2021

#FP2drz(F,x,y): The list of fixed points of the transformation [x,y]->F. Dr. Z.'s way

#FP2([x-y,x+y],x,y);

*FP2drz := **proc**(F, x, y) **local** eq, i, L, S1 :*

eq := [numer(F[1]-x), numer(F[2]-y)] :

L := Groebner[Basis](eq, plex(x, y)) :

S1 := evalf([solve(L[1], y)]) :

[seq([solve(subs(y=S1[i], L[2]), x), S1[i]), i = 1 ..nops(S1)])] :

end:

#SFP2drz(F,x,y): The list of Stable fixed points of the transformation [x,y]->F. Try

*#SFP2drz([(1+x)/(1+y), (1+7*y)/(4+x)],x,y);*

*SFP2drz := **proc**(F, x, y) **local** L, J, S, J0, i, pt, EV :*

L := FP2drz(F, x, y) :

#F is the list of ALL fixed points of the transformation [x,y]->F using the previous procedure

FP2(F,x,y), but since we are interested in numbers we take the floating point version using evalf

J := Matrix(normal([[diff(F[1], x), diff(F[2], x)], [diff(F[1], y), diff(F[2], y)]])) :

#J is the Jacobian matrix in general (in terms of the variables x and y). Note that J is a SYMBOLIC matrix featuring variables x and y

S := [] : #S is the list of stable fixed points that starts out empty

for *i from 1 to nops(L) do* *#we examine it case by case*

pt := L[i] : #pt is the current fixed point to be examined

J0 := subs({x=pt[1], y=pt[2]}, J) :

#J0 is the NUMERICAL matrix obtained by plugging-in the examined fixed pt

EV := Eigenvalues(J0) :

We used Maple's command Eigenvalues to find the eigenvalues of this 2 by 2 matrix

if abs(EV[1]) < 1 **and** abs(EV[2]) < 1 **then**

$S := [op(S), pt]:$

#If both eigenvalues have absolute value less than 1 it means that they are stable, so we append the examined fixed point, pt, to the list of fixed points

fi:

od:

S : #the output is S

end:

> #1 (i)

first eq: a3 = 4, a4 = 2, a7 = 8

$F := dsolve\left(\left\{diff(x(t), t) = (4 - x(t)) \cdot (2 - x(t)) \cdot (8 - x(t)), x(0) = \frac{(4 + 2)}{2}\right\}, x(t)\right);$

$$F := x(t) = \frac{2 \cdot 5^{2/3} \left((e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{5} - 1}} + 1 \right) \left(\frac{(e^t)^{24}}{5} - 1 \right)^2 \right)^{1/3}}{5 \left(\frac{(e^t)^{24}}{5} - 1 \right)}$$

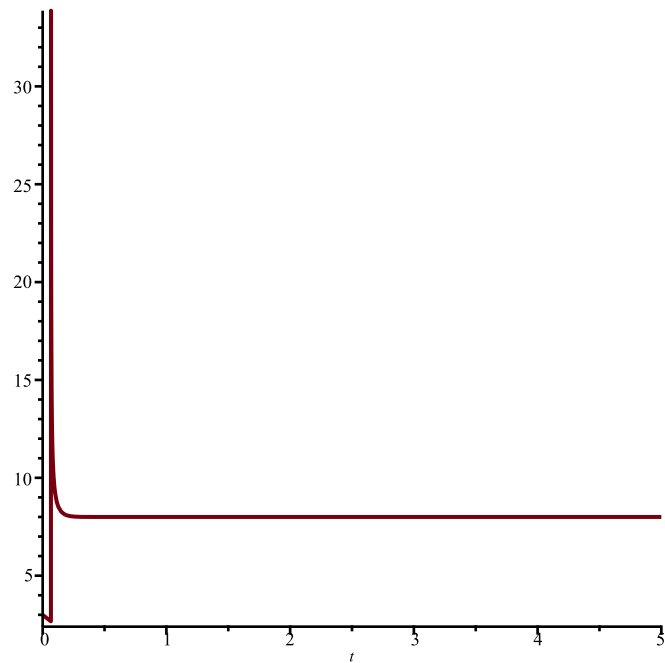
$$+ \frac{2 (e^t)^{24} 5^{1/3}}{5 \left((e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{5} - 1}} + 1 \right) \left(\frac{(e^t)^{24}}{5} - 1 \right)^2 \right)^{1/3}} + 4$$

> plot

$$\left(\frac{2 \cdot 5^{2/3} \left((e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{5} - 1}} + 1 \right) \left(\frac{(e^t)^{24}}{5} - 1 \right)^2 \right)^{1/3}}{5 \left(\frac{(e^t)^{24}}{5} - 1 \right)} \right.$$

$$\left. + \frac{2 (e^t)^{24} 5^{1/3}}{5 \left((e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{5} - 1}} + 1 \right) \left(\frac{(e^t)^{24}}{5} - 1 \right)^2 \right)^{1/3}} + 4, t=0..5 \right);$$

(1)



> #second eq

$$G := dsolve\left(\left\{diff(x(t), t) = (4 - x(t)) \cdot (2 - x(t)) \cdot (8 - x(t)), x(0) = \frac{(8 + 2)}{2}\right\}, x(t)\right);$$

$$G := x(t) = - \frac{\left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{(e^t)^{24}} + 1} - \frac{(e^t)^{24}}{27} - 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2 \right)^{1/3}}{27} - \frac{(e^t)^{24}}{27} - 1}{(e^t)^{24}} + \frac{\left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{(e^t)^{24}} + 1} - \frac{(e^t)^{24}}{27} - 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2 \right)^{1/3}}{27} - \frac{(e^t)^{24}}{27} - 1}{(e^t)^{24}} \quad (2)$$

$$+ I\sqrt{3} \left[\frac{\left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}}{-\frac{(e^t)^{24}}{27} - 1} \right]$$

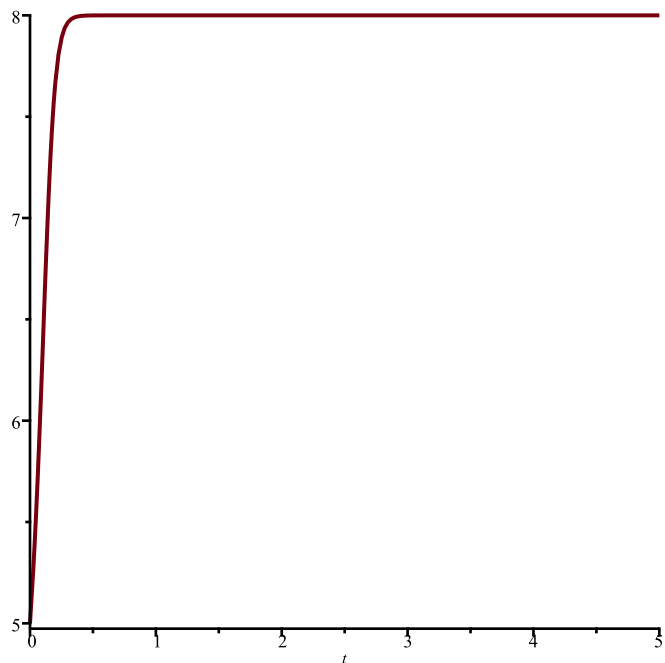
$$+ \frac{(e^t)^{24}}{27 \left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}} + 4$$

> plot

$$\left[\frac{\left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}}{-\frac{(e^t)^{24}}{27} - 1} \right]$$

$$+ \frac{(e^t)^{24}}{27 \left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}}$$

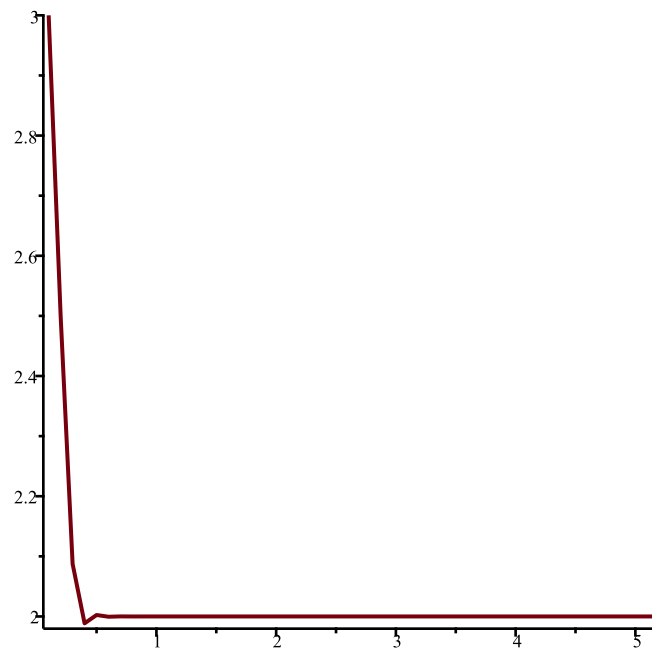
$$\begin{aligned}
 & + I\sqrt{3} \left(\frac{\left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{-\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}}{-\frac{(e^t)^{24}}{27} - 1} \right. \\
 & \left. + \frac{(e^t)^{24}}{27 \left(\frac{(e^t)^{24} \left(\sqrt{-\frac{1}{-\frac{(e^t)^{24}}{27} - 1}} + 1 \right) \left(-\frac{(e^t)^{24}}{27} - 1 \right)^2}{27} \right)^{1/3}} \right) + 4, t=0..5 ;
 \end{aligned}$$



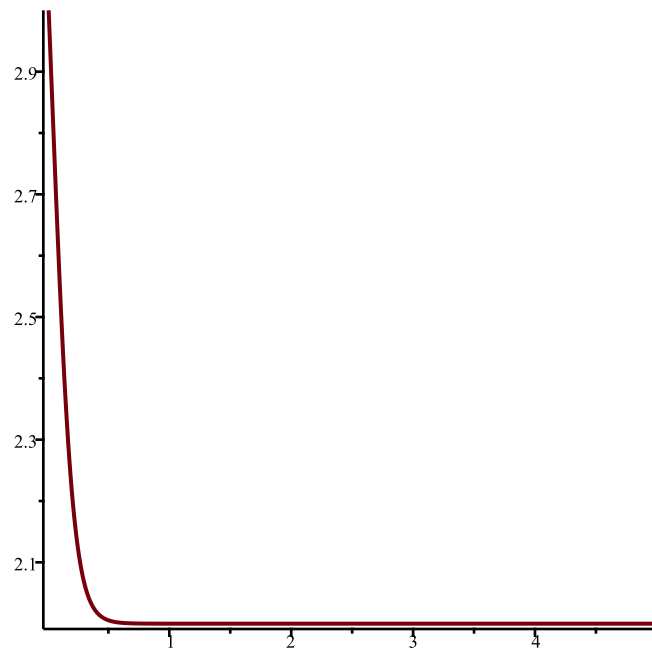
```

> #1 (ii)
#first eq
Dis1((4 - y) * (2 - y) * (8 - y), y, (4 + 2)/2, 0.1, 5) :
plot(%);

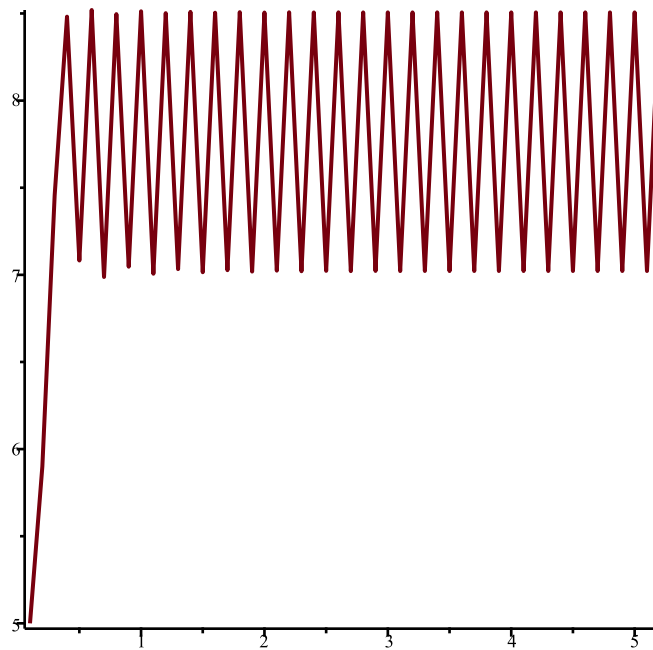
```



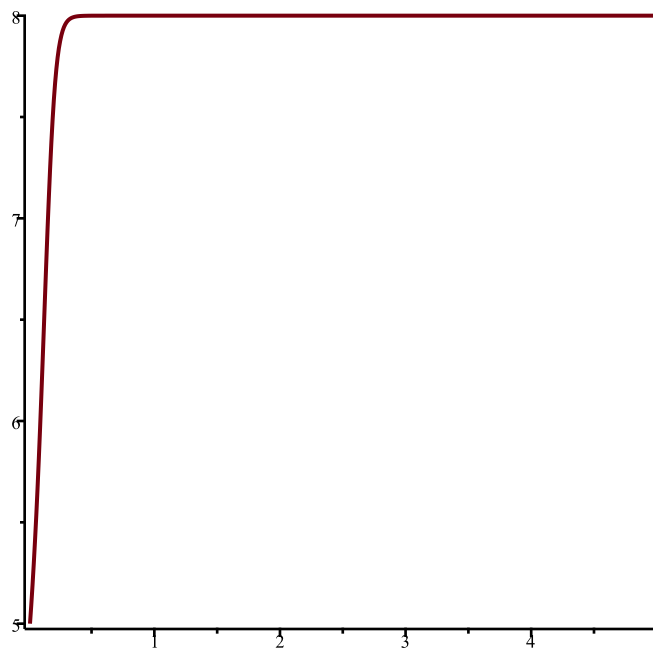
> $DisI\left((4 - y) * (2 - y) * (8 - y), y, \frac{(4 + 2)}{2}, 0.01, 5\right) :$
 $plot(\%);$



> #second eq
 $DisI\left((4 - y) * (2 - y) * (8 - y), y, \frac{(8 + 2)}{2}, 0.1, 5\right) :$
 $plot(\%);$



> $DisI\left((4 - y) * (2 - y) * (8 - y), y, \frac{(8 + 2)}{2}, 0.01, 5\right):$
 $plot(\%);$



> #2 (ii) confirming converting fourth order to first order set using Maple

$ToSys\left(4, z, \frac{(z[1] + 2 \cdot z[2] + 3 \cdot z[3] + 11 \cdot z[4])}{z[1] + z[3]}, [1, 5, 5, 2]\right);$

$\left[\frac{z_1 + 2 z_2 + 3 z_3 + 11 z_4}{z_1 + z_3}, z_1, z_2, z_3\right], [1, 5, 5, 2]$

(3)

> #3

$Orbk(2, z, (1 - z[1]) \cdot (1 - z[2]), [2.5, 2.7], 1000, 1010);$

$\#The\ fixed\ point\ given\ is\ (0.381966, 0.381966)$

(4)

```

[0.3819660113, 0.3819660113, 0.3819660112, 0.3819660113, 0.3819660113, 0.3819660112,
0.3819660113, 0.3819660113, 0.3819660112, 0.3819660113, 0.3819660113] (4)
> ToSys(2, z, (1 - z[1]) · (1 - z[2]), [2.5, 2.7]);
      [(1 - z1) (1 - z2), z1], [2.5, 2.7] (5)
> SFP2([(1 - z[1]) · (1 - z[2]), z[1]], z[1], z[2]);
      [[0.3819660113, 0.3819660113]] (6)
>

```