

OK to post

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1. (i)

$$x = x^3 - 6x^2 + 12x - 6$$

$$x^3 - 6x^2 + 11x - 6 = 0$$

(by guessing roots)

$$= (x-1)(x-2)(x-3)$$

so 1, 2, and 3 are fixed points.

$$f'(x) = 3x^2 - 12x + 12$$

$|f'(1)| = 3$, so 1 is not stable.

$|f'(2)| = 12 - 24 + 12 = 0 < 1$, so 2 is stable.

$|f'(3)| = 27 - 36 + 12 = 3$ so 3 is not stable.

$$(ii) \quad x \rightarrow x^4 - \frac{13x^2}{36} + x + \frac{1}{36}$$

$$y = x^4 - \frac{13x^2}{36} + x + \frac{1}{36}$$

$$\Rightarrow 0 = 36x^4 - 13x^2 + 1$$

$$\Rightarrow 0 = 36x^4 - 9x^2 - 4x^2 + 1$$

$$\Rightarrow 0 = 9x^2(4x^2 - 1) - 1(4x^2 - 1)$$

$$\Rightarrow 0 = (9x^2 - 1)(4x^2 - 1)$$

$$\Rightarrow \boxed{x = \pm \sqrt{3}, \pm \sqrt{2}} \text{ are fixed pts.}$$

$$f'(x) = 4x^3 - \frac{26}{36}x + 1$$

$$|f'(\sqrt{3})| = \frac{49}{84} < 1, \text{ so } \sqrt{3} \text{ is stable,}$$

$$|f'(-\sqrt{3})| = \frac{59}{84} > 1, \text{ so } -\sqrt{3} \text{ is not stable.}$$

$|f'(\gamma_2)| = \frac{41}{36} > 1$, so γ_2 is not stable.

$|f'(-\gamma_2)| = \frac{31}{36} < 1$. so $-\gamma_2$ is stable.

2)
(i) $f(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0)$
 $+ f_y(x_0, y_0)(y - y_0)$

$$f_x = \gamma_2 (x+4y)^{-\gamma_2} = \frac{1}{2\sqrt{x+4y}}$$

$$f_y = \gamma_2 (x+4y)^{-\gamma_2} \cdot 4 = \frac{2}{\sqrt{x+4y}}$$

$$f(x_0, y_0) = \sqrt{1+8} = 3$$

$$f_x(x_0, y_0) = \frac{1}{2\sqrt{9}} = \frac{1}{6}$$

$$f_y(x_0, y_0) = \frac{2}{\sqrt{9}} = \frac{2}{3}$$

$$g(x, y) = 3 + \frac{1}{6}(x-1) + \frac{2}{3}(y-2)$$

$$f(0.95, 1.02) = \sqrt{0.95 + 4 \cdot 1.02} = 2.428$$

$$\begin{aligned} g(0.95, 1.02) &= 3 + \frac{1}{6}(0.95-1) + \frac{2}{3}(1.02-2) \\ &= 2.338 \end{aligned}$$

(ii) $f(x, y, z) = x^3 y^4 z^5$ @ (1, 1, 1)

$$f_x = 3x^2 y^4 z^5$$

$$f_y = 4x^3 y^3 z^5$$

$$f_z = 5x^3 y^4 z^4$$

$$f(1,1,1) = 1$$

$$f_x(1,1,1) = 3$$

$$f_y(1,1,1) = 4$$

$$f_z(1,1,1) = 5$$

$$g(x,y,z) = 1 + 3(x-1) + 4(x-1) + 5(x-1).$$

$$f(1.01, 1.02, 0.99) = (1.01)^3 (1.02)^4 (0.99)^5$$

$$= 1.061$$

$$g(1.01, 1.02, 0.99) = 1 + 3(0.01) + 4(0.02) + 5(-0.01)$$

$$= 1.06$$

(iii) $f(x_1, x_2, x_3, x_4) = \sqrt{x_1 + x_2 + x_3 + x_4}$
@ (1, 1, 1, 1)

$$f_{x_1} = f_{x_2} = f_{x_3} = f_{x_4} \\ = Y_2 (x_1 + x_2 + x_3 + x_4)^{-Y_2} = \frac{1}{2\sqrt{x_1 + x_2 + x_3 + x_4}}$$

$$f(1, 1, 1, 1) = 2$$

$$f_x(1, 1, 1, 1) = \frac{1}{4}$$

$$g(x_1, x_2, x_3, x_4) = 2 + Y_4(x_1 - 1) + Y_4(x_2 - 1) \\ + Y_4(x_3 - 1) + Y_4(x_4 - 1)$$

$$f(1.01, 1.01, 0.99, 0.99) = \sqrt{4} = 2$$

$$g(1.01, 1.01, 0.99, 0.99) = 2 + \frac{0.1 + 0.1 - 0.1 - 0.1}{4} = 2$$

3) $(x, y) \rightarrow \left(\frac{x}{y+1}, \frac{y}{x+1} \right)$

$$J = \begin{pmatrix} f_{1x} & f_{1y} \\ f_{2x} & f_{2y} \end{pmatrix} = \begin{pmatrix} \frac{1}{y+1} & \frac{-x}{(y+1)^2} \\ \frac{y}{(x+1)^2} & \frac{1}{x+1} \end{pmatrix}$$

$$= \begin{pmatrix} y_2 & -\frac{1}{y} \\ -x_1 & y_2 \end{pmatrix}$$

$$4) (x, y, z) = (x+y+z, x^2+y^2+z^2, x^3+y^3+z^3)$$

$$J = \begin{pmatrix} f_{1x} & f_{1y} & f_{1z} \\ f_{2x} & f_{2y} & f_{2z} \\ f_{3x} & f_{3y} & f_{3z} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 & 1 \\ 2x & 2y & 2z \\ 3x^2 & 3y^2 & 3z^2 \end{pmatrix} = \boxed{\begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \\ 3 & 3 & 3 \end{pmatrix}}$$

5. We can linearize f and g

by writing

$$f(x, y) = f(x_0, y_0) + f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

$$g(x, y) = g(x_0, y_0) + g_x(x_0, y_0)(x - x_0) + g_y(x_0, y_0)(y - y_0).$$

Then, setting $f(x_0, y_0) = x_0$ and

$g(x_0, y_0) = y_0$, we get:

$$f(x, y) - x_0 = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0)$$

$$g(x, y) - y_0 = g_x(x_0, y_0)(x - x_0) + g_y(x_0, y_0)(y - y_0).$$

We can rewrite this as:

$$\begin{bmatrix} f(x, y) - x_0 \\ g(x, y) - y_0 \end{bmatrix} = \begin{pmatrix} f_x(x_0, y_0) & f_y(x_0, y_0) \\ g_x(x_0, y_0) & g_y(x_0, y_0) \end{pmatrix} \begin{bmatrix} x - x_0 \\ y - y_0 \end{bmatrix}$$

Going through this transformation
n times gives:

$$\begin{bmatrix} f(x_n, y_n) - x_0 \\ g(x_n, y_n) - y_0 \end{bmatrix} = \begin{bmatrix} f_x(x, y_0) & f_y(x_0, y_0) \\ g_x(x_0, y_0) & g_y(x_0, y_0) \end{bmatrix}^n \begin{bmatrix} x_n - x_0 \\ y_n - y_0 \end{bmatrix}.$$

We can diagonalize the Jacobian J

as $Q \lambda Q^{-1}$ where λ is the

diagonal matrix consisting of

eigenvalues of J . Then,

$$\begin{bmatrix} f(x_n, y_n) - x_0 \\ g(x_n, y_n) - y_0 \end{bmatrix} = (Q \lambda Q^{-1})^n \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}.$$

$$\text{Then, } (Q \lambda Q^{-1})^n = Q \lambda Q^{-1} Q \lambda Q^{-1} Q \lambda Q^{-1} Q \lambda \dots$$

$$= Q \lambda^n Q^{-1}.$$

Thus,

$$\begin{pmatrix} f(x_n, y_n) - x_0 \\ g(x_n, y_n) - y_0 \end{pmatrix} = Q X^n Q^{-1} \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}$$

and $f(x_n, y_n) - x_0 < x - x_0$

and $g(x_n, y_n) - y_0 < y - y_0$

only if each eigenvalue gets smaller as $n \rightarrow \infty$, i.e. they are less than 1.