Efficient algorithms for tensor scaling, quantum marginals, and moment polytopes



based on joint work with Peter Bürgisser, Ankit Garg, Rafael Oliveira, Michael Walter, Avi Wigderson

- Simple classical algorithm for tensor scaling
- · Important example of moment polytope problem
- Analysis solves nonconvex optimization problem arising in GIT
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• Problem statement and history

- Algorithm
- Analysis
- Conclusion and open problems
- More moment polytopes

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Problem statement and history

Space of *d*-tensors, denoted $\mathbb{C}^{n_1} \otimes \mathbb{C}^{n_2} \otimes \cdots \otimes \mathbb{C}^{n_d}$:

d-dimensional complex arrays of dimensions *n*₁,..., *n_d*; entries

 $X_{i_1,\ldots,i_d} \in \mathbb{C}$

for $i_j \in [n_j]$. Let $n = n_1 \dots n_d$.



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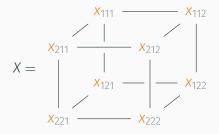


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• Let X be a *d*-tensor

• Consider *j*th slice in *i*th direction:

$$X_{\underbrace{* * \cdots * *}_{i-1}} j_{\underbrace{* * \cdots * *}_{d-i}}$$

it is a (*d* − 1)-tensor.

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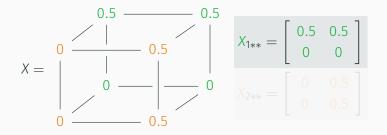
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Example:
$$n_1 = n_2 = n_3 = 2$$



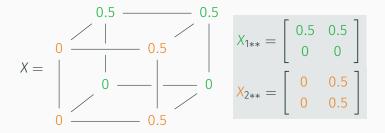
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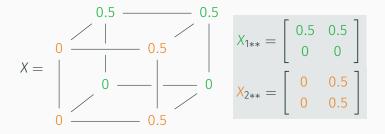
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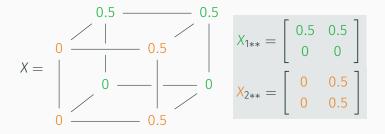
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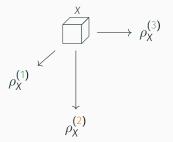


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Note: $\operatorname{Tr} \rho_X^{(i)} = ||X||^2!$

Interpretation

If Alice, Bob, and Carol each hold a qubit but the joint state is X, $\rho_X^{(1)}, \rho_X^{(2)}, \rho_X^{(3)}$ are the mixed states of their respective qubits.

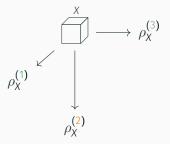


One body quantum marginal problem, *d* = 3: Can PSD matrices *A*, *B*, *C* arise as the marginals of some tensor *J*

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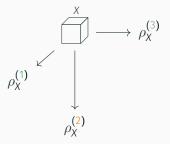
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If $\mathbb{X} \subset \mathbb{C}^{n_0} \otimes \cdots \otimes \mathbb{C}^{n_d}$ is a set of d + 1-tensors, let

$$\Delta(\mathbb{X}) = \left\{ \left(\mathsf{spec}(\rho_{\mathsf{Y}}^{(1)}) / \|\mathsf{Y}\|^2, \dots, \mathsf{spec}(\rho_{\mathsf{Y}}^{(d)}) / \|\mathsf{Y}\|^2 \right) : \mathsf{Y} \in \mathbb{X} \right\}$$

 $\Delta(\mathbb{X})$ is all the tuples of spectra of marginals of elements of \mathbb{X} , normalized to have trace one.

Quantum marginal problem, restatement: Input: $p = (p_1, p_2, p_3)$ list of sequences of nonnegative rea Output: Whether $p \in \Delta(\mathbb{C}^{n_0=1} \otimes \mathbb{C}^{n_1} \otimes \cdots \otimes \mathbb{C}^{n_d})$. If $\mathbb{X} \subset \mathbb{C}^{n_0} \otimes \cdots \otimes \mathbb{C}^{n_d}$ is a set of d+1-tensors, let

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More generally:

Given a tensor X, can we locally change basis to obtain specific marginals?

We consider a d + 1 tensor $X \in \mathbb{C}^{n_0} \otimes \mathbb{C}^{n_1} \otimes \cdots \otimes \mathbb{C}^{n_d}$, and let $G := \operatorname{GL}_{n_1} \times \cdots \times \operatorname{GL}_{n_d}$.

 $g \cdot X := (I_{n_0} \otimes g_1 \otimes g_2 \otimes \cdots \otimes g_d) X.$

 $G \cdot X$ denotes the orbit of X, and $\overline{G \cdot X}$ the orbit closure.

Question: TENSORSCALING(X, p)

Input: $p = (p_1, \dots, p_d),$ X a tensor in $\mathbb{C}^{n_0} \otimes \mathbb{C}^{n_1} \otimes \dots \otimes \mathbb{C}^{n_d}$ Dutput: whether $p \in \Delta(\overline{G \cdot X}).$

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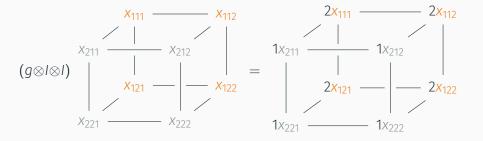
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E.g. if
$$g = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$
 then



Amazing fact: $\Delta(\mathbb{C}^{n_0} \otimes \cdots \otimes \mathbb{C}^{n_d})$ and $\Delta(\overline{G \cdot X})$ are convex polytopes!

More generally: Holds if X is a variety and $G \cdot X \subset X$. Then $\Delta(X)$ is called the *moment polytope* for the action of G on X. **The groups can also be more general.**

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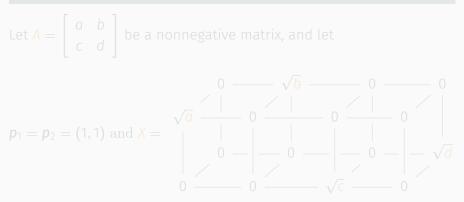
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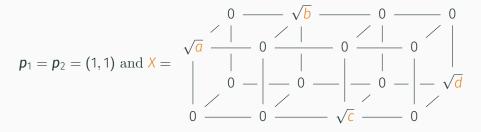


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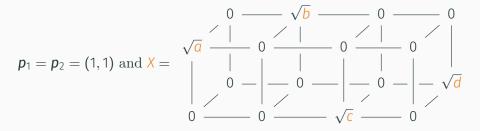


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- noncommutative rational identity testing
- Forster's radial isotropic position
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Tensor scaling:

Approximate tensor scaling: TENSORSCALING(X, p, ε) Input: Tensor X, tuple $p, \varepsilon > 0$ Output: If either output g such that for all $i \in [d]$

 $\|\operatorname{spec}(\rho_{g.\mathbf{X}}^{(i)}) - \boldsymbol{p}_i\|_1 \leq \varepsilon,$

or correctly output that $p \notin \Delta(\overline{G \cdot X})$.

MATRIXSCALING(A, r, c):

- [Sinkhorn '64]: simple $poly(1/\varepsilon)$ algorithm when r = c = 1
- [Linial, Samorodnitsky, Wigderson '98]: poly log(1/ ε) for any r, cOPERATORSCALING(X, p_1, p_2): The d = 2 case of TENSORSCALING
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Theorem (BFGOWW '18)

There is a randomized $poly(\langle X \rangle + \langle p \rangle, 1/\varepsilon)$ -time algorithm for TENSORSCALING(X, p, ε) with success probability 1/2.

The algorithm requires

$$O\left(dn^2\frac{\langle X\rangle + \langle \lambda\rangle + \log dn}{\varepsilon}\right)$$

iterations, each dominated by computing a Cholesky decomposition of some $n_i \times n_i$ matrix.

Convention: $p = \lambda/k$ for λ integral and $k = \sum \lambda_j^{(1)}$

Theorem (BFGOWW '18)

If for all i,

$$\|\operatorname{spec}(\rho_{g\cdot X}^{(i)}) - p^{(i)}\|_{1} \le \exp(-O(n_{1} + \dots + n_{d})\log k \max n_{i}),$$

then $p \in \Delta(G \cdot X).$

Unfortunately, doesn't result in poly time algorithm! Need poly(log($1/\varepsilon$)).

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Algorithm

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Input: X, p with integer coordinates, ε . **Output:** Y = g · X s.t. $\|\operatorname{spec}(\rho_Y^{(i)}) - p^{(i)}\|_1 \le \varepsilon$, or OUTSIDE POLYTOPE

• Choose g_0 with i.i.d integer coordinates in [K], set

 $\mathbf{Y} = g_0 \cdot \mathbf{X} / \|g_0 \cdot \mathbf{X}\|.$

- Repeat *T* times:
 - If done, output Y.
 - Else, scale in single factor to FIX the worst marginal of Y. (ignoring damage done to other marginals!)
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• Choose g_0 with i.i.d integer coordinates in [K], set

 $\mathbf{Y} = g_0 \cdot \mathbf{X} / \|g_0 \cdot X\|.$

- Repeat *T* times:
 - If done, output Y.
 - Else, scale in single factor to FIX the worst marginal of Y. (ignoring damage done to other marginals!)
- Output OUTSIDE POLYTOPE

Theorem

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Theorem

Scaling II

 $g = (g_1, I, \ldots, I)$ scales the flattening:

$$\begin{bmatrix} -(g \cdot Y)_{1*\cdots} - \\ \vdots \\ -(g \cdot Y)_{n_1*\cdots} - \end{bmatrix} = g_1 \begin{bmatrix} -Y_{1*\cdots} - \\ \vdots \\ -X_{n_1*\cdots} - \end{bmatrix}$$

In particular,

$$\rho_{g,Y}^{(1)} = g_1 \begin{bmatrix} -Y_{1*\cdots} - \\ \vdots \\ -X_{n_1*\cdots} - \end{bmatrix} \begin{pmatrix} g_1 \begin{bmatrix} -Y_{1*\cdots} - \\ \vdots \\ -X_{n_1*\cdots} - \end{bmatrix} \end{pmatrix}^{\dagger} = g_1 \rho_Y^{(1)} g_1^{\dagger}$$

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Easy to fix i^{th} marginal: choose g_i such that $g_i \rho_{\mathbf{Y}}^{(i)} g_i^{\dagger} = \text{diag}(\mathbf{p}^{(i)})$. WARNING: not every choice works. Correct way:

 $g_i = \sqrt{\operatorname{diag}(p^{(i)})} L,$

L lower triangular Cholesky factor $L^{\dagger}L = \rho_{Y}^{-1}$.

Remark:

It is maintained that $g \cdot Y$ is a unit vector the entire time.

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Analysis

• The randomization step: Success = nonvanishing of a potential function on $g_0 \cdot X$

If potential function nonvanishing, is in fact bounded below by

 $poly(\langle X \rangle + \langle p \rangle)$

• The triangular scaling steps: the potential function decreases by $\Omega(\varepsilon^2)$ each step provided marginals are ε -far from targets • The randomization step: Success = nonvanishing of a potential function on $g_0 \cdot X$ If potential function nonvanishing, is in fact bounded below by

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Description of the potential functions

First define a modified determinant.

Definition

If **b** is a lower triangular matrix and α a sequence of real numbers, define

$$\chi_{\alpha}(b) = \prod_{i=1}^{m} b_{ii}^{\alpha_i}.$$

Throughout the iterations, keep track of the following function:

$$f_{p,Y}(g) := \log \frac{\|g \cdot Y\|^2}{|\chi_p(g)|^2}$$

where $\chi_p(g) = \prod_{i=1}^d \chi_{p^{(i)}}(g_i)$.

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Triangular scaling steps

Lemma (Change in potential function)

Let g(t) be the scaling in the t^{th} step. If for some i,

$$\left\| \rho_{g(t),\mathbf{Y}}^{(i)} - \mathsf{diag}(\boldsymbol{p}_{\uparrow}^{(i)}) \right\|_{Tr} > \varepsilon,$$

then $f_{p,Y}(g(t+1)) \leq f_{p,Y}(g(t)) - \Omega(\varepsilon^2)$.

Let

 $B := \{g : g_i \text{ lower triangular } \}.$

Corollary: if $\inf_{g \in B} f_{p,Y}(b) = -C$, then the number of iterations is at most

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Consider

 $f_{p,Y}(g(t+1)) - f_{p,Y}(g(t))$

At each step, $||g(t) \cdot X||$ is 1, so this is

 $-\log |\chi_p(g(t+1))|^2 + \log |\chi_p(g(t))|^2$

Recall that only the *i*th factor changed was multiplied by $\sqrt{\text{diag}(p^{(i)})}$, so the above is

$$-\sum_{j=1}^{n_i} p_j^{(i)} \log \left(p_j^{(i)} |L_{jj}|^2 \right).$$

However, $\sum_j |L_{jj}|^{-2} \le \|L^{-1}\|_F = \operatorname{Tr}
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A polynomial *P* on $\mathbb{C}^{n_1} \otimes \cdots \otimes \mathbb{C}^{n_d}$ is a highest weight^{**} of weight λ if

 $P(g \cdot X) = \chi_{\lambda}(g)P(X)$

for all $g \in B$. That is, p is a common eigenvector of the action of the lower triangular matrices on the polynomials. **Really this is a lowest weight of $-\lambda$ A polynomial *P* on $\mathbb{C}^{n_1} \otimes \cdots \otimes \mathbb{C}^{n_d}$ is a highest weight^{**} of weight λ if

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$$f_{p,Y}(g) \geq \frac{1}{k} \log \frac{|P(Y)|^2}{\|P\|^2}.$$

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Thus, highest weights that do not vanish on Y give us lower bounds!

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Theorem (Ness-Mumford '84, Brion '87)

 $p \in \Delta(X) \cap \mathbb{Q}$ if and only if some there is some integer ℓ such that $\lambda = \ell p$ is integral and some highest weight P_{λ} does not vanish on $\overline{G \cdot X}$.

Further, (Derksen '01), if ℓp is integral we may take $k = (\ell d \max n_i)^{(d \max n_i^2)}$; Thus in randomization step we may take $K = 2(\ell d \max n_i)^{(d \max n_i^2)}$ to obtain a nonvanishing highest weight with probability 1/2.

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The space of highest weights of weight λ are spanned by polynomials with integer coefficients and $||P|| \le n^k$.

Suppose the largest entry of $g_0 \cdot X$ is M.

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Corollary
If a highest weight of \lambda doesn't vanish on g_0 \cdot X, then
\inf_{g \in B} f_{p,Y}(g) \ge -2 \log n - \log ||g_0 \cdot X||^2 \ge -3 \log n - \log M
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Corollary

The algorithm runs in $O((\log n + \log M)/\varepsilon^2) = O(d \max n_i(\langle X \rangle + \langle p \rangle + \log d \max n_i)/\varepsilon^2)$ steps

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- Obtain poly log(1/ ε) run time!
- Solve the optimization problem for other group actions (in progress).
- Develop separation oracles for moment polytopes.

Thank you!

Moment polytopes

Suppose G acts linearly on a vector space V and the inner product $\langle -, - \rangle$ is invariant under the unitaries $K = U(n_1) \times \cdots \times U(n_d)$. Definition The map $\mu : V \to \operatorname{Herm}_{n_1} \times \cdots \times \operatorname{Herm}_{n_d}$ given by $\mu : X \mapsto \nabla_{A=0} \log \|e^A \cdot X\|$

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$$\Delta(\mathsf{X}) = \left\{ (\operatorname{spec}(\mu^{(1)}(\mathsf{Y})), \dots, \operatorname{spec}(\mu^{(d)}(\mathsf{Y})) : \mathsf{Y} \in \overline{\mathsf{G} \cdot \mathsf{X}} \right\}.$$

Amazingly, $\Delta(X)$ is not only a polytope but encodes the rep. theory of polynomials on $\overline{G \cdot X}$!

G acts on a polynomial p on V by $g \cdot p(x) = p(g^{-1} \cdot x)$.

Theorem (Mumford '84, Brion '87)

$$\Delta(X) \cap \mathbb{Q} = \{ \boldsymbol{\lambda}/k : V_{G,\lambda} \subset R_k(\overline{G \cdot X}) \}$$

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