

# Math 454 Lecture 10: 7/12/2017

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Reading these notes is worse in almost every way than reading sections 5.1 and 5.2 of Keller and Trotter, which you can find here:

[http://www.rellek.net/book/s\\_graphs\\_intro.html](http://www.rellek.net/book/s_graphs_intro.html).

I tried to write down things that aren't emphasized in that book.

## Contents

### 1 Basic graph definitions

Reading these notes worse in almost every way than reading sections 5.1 and 5.2 of Keller and Trotter. However, I will put a few things in that we covered.

**Definition 1.1.** A graph  $G = (V, E)$  is a pair of sets  $V$ , called the *vertex set*, and  $E$ , called the *edge set*.  $E$  is a set of 2-subsets of  $V$ . In other words, it is a collection of unordered pairs in  $V$ . The elements of the edge set (the unordered pairs) are called the *edges* of  $G$ . We say an edge  $e$  is *incident* to a vertex  $v$  if  $v \in e$ , and that  $v$  and  $w$  are *adjacent* if  $\{v, w\} \in E$  (there is an edge containing  $v$  and  $w$ ).

A graph with  $n$  vertices and  $m$  edges is said to be of *order*  $n$  and *size*  $m$ . That is, the order of a graph is the number of vertices, and the size is the number of edges.

**Example 1.**  $G = (\{a, b, c, d\}, \{\{a, b\}, \{c, d\}, \{a, b\}, \{c, d\}\})$  has vertex set

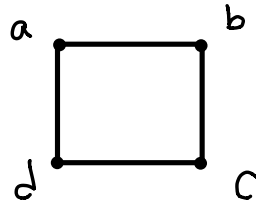
$$V = \{a, b, c, d\}$$

and edge set

$$E = \{\{a, b\}, \{b, c\}, \{c, d\}, \{d, a\}\}.$$

$\{ab\}$  is an edge of  $G$ . Commonly, this edge is denoted  $ab$ , and  $ba$  denotes the same edge.  $c$  is a vertex of  $G$ .  $da$  is incident to  $d$ , and the vertices  $a$  and  $d$  are adjacent.

Often we draw a graph where vertices are represented by points, and edges by lines going through the points corresponding to vertices they contain. The graph  $G$  just described could be drawn as follows:



**Definition 1.2.** Two graphs  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  are isomorphic if, informally,  $G_1$ 's vertex set can be relabeled with vertices of  $G_2$  so that the relabeled graph is equal to  $G_2$ . More precisely, there is a one-to-one and onto function  $f : V_1 \rightarrow V_2$  such that

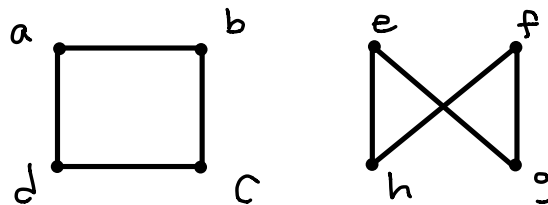
$$E_2 = \{f(v)f(w) : vw \in E_1\}.$$

Alternately,  $f(v)$  and  $f(w)$  are adjacent if and only if  $v$  and  $w$  are.

The a function  $f$  as above is called an *isomorphism*.

**Example 2.** The following graphs are isomorphic with an isomorphism  $f$  given by

$$f(a) = e, f(b) = g, f(c) = f, \text{ and } f(d) = h.$$

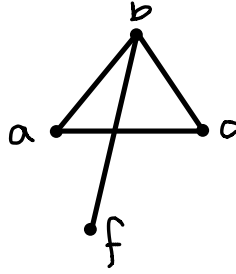


**Definition 1.3.** The *degree* of a vertex  $v$  in a graph  $G$ , which we will denote  $d(v)$ , is the number of edges incident to  $v$ , which is also the number of vertices adjacent to  $v$ .

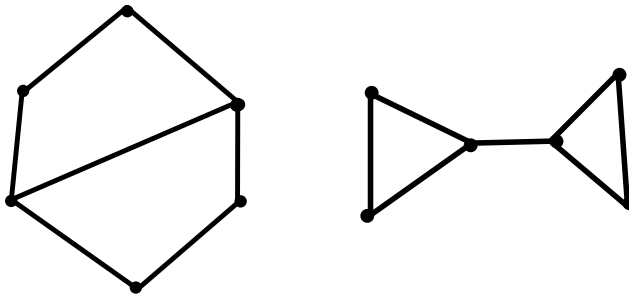
**Definition 1.4.** The *degree sequence* of a graph is a sequence of the degrees of the vertices of  $G$  in non-increasing order.

**Example 3.** The following graph has degrees  $d(a) = 2, d(b) = 3, d(c) = 2, d(f) = 1$ , and has degree sequence

$$(3, 2, 2, 1) :$$



**Example 4.** As we saw in class, two non-isomorphic graphs can have the same degree sequence, such as the following two graphs.



**Theorem 1.1** (Handshake Lemma/First Theorem of Graph Theory). *If  $G = (V, E)$  is a graph then*

$$\sum_{v \in V} d(v) = 2|E|.$$

*In particular, the sum of the degree sequence is even.*

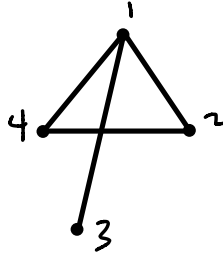
## 2 Adjacency Matrix

**Definition 2.1.** The *adjacency matrix* of a graph  $G = (\{1, \dots, n\}, E)$  is a  $n \times n$  matrix  $A$  with entries in  $\{0, 1\}$  satisfying

$$A_{ij} = \begin{cases} 1 & : ij \in E \\ 0 & : ij \notin E. \end{cases}$$

There is a distinction between *the* adjacency matrix and *an* adjacency matrix: *an* adjacency matrix of  $G$  is *the* adjacency matrix of some graph isomorphic to  $G$ . This amounts to picking an ordering of the vertices of  $G$ .

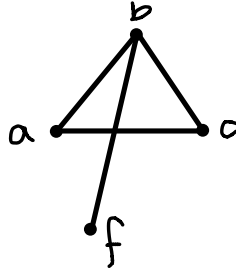
**Example 5.** *The adjacency matrix of*



is

$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \end{bmatrix}.$$

An adjacency matrix of



is

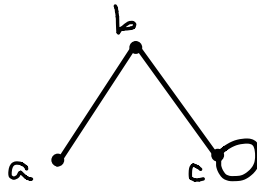
$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}.$$

(this just has rows 2 and 3 swapped and columns 2 and 3 swapped from the previous matrix).

### 3 Variants of graphs

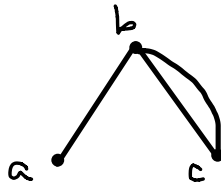
**Definition 3.1.** A *looped graph*, or a graph with self loops, is a graph where  $E$  is also allowed to contain sets of size 1 indicating that a vertex has a “loop”, or is adjacent to itself.

**Example 6** (A looped graph). The following represents the looped graph  $G = (\{a, b, c\}, \{\{a, b\}, \{b, c\}, \{c\}\})$ :



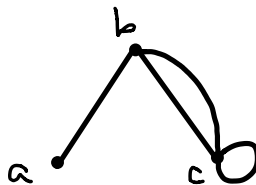
**Definition 3.2.** A *multigraph*  $G = (V, E)$  consists of a set  $V$ , called the *vertex set*, and a **multiset**  $E$ , called the *edge set*.  $E$  is a multiset set of 2-subsets of  $V$ . In other words, it is a collection of unordered pairs in  $V$  where each unordered pair can occur any number of times.

**Example 7** (A multigraph). The following represents the multigraph  $G = (\{a, b, c\}, \{\{a, b\}, 2 \cdot \{b, c\})$ :



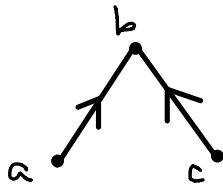
You can probably guess what a looped multigraph is.

**Example 8** (A looped multigraph). The following represents the looped multigraph  $G = (\{a, b, c\}, \{\{a, b\}, 2 \cdot \{b, c\}, \{c\})$ :



**Definition 3.3.** A *directed graph*  $G = (V, A)$ , or *digraph*, is a pair of sets  $V$ , called the *vertex set*, and  $A$ , called the *arc set*.  $A$  is a set of **ordered pairs** of distinct elements of  $V$ . The ordered pairs in  $A$  are called *arcs*.

**Example 9** (A digraph). Digraphs are often drawn with arrows on the edges. The arc  $(a, b)$  is drawn as an arrow from  $a$  to  $b$ . The following represents the digraph  $G = (\{a, b, c\}, \{(a, b), (b, c)\})$ :



I won't define *looped digraph*, *multidigraph*, or *looped multidigraph*, but you can guess what they are.