## Due: Thursday, October 27, 2016

Solve the below problems concerning ordinary differential equations. A (possibly improper) subset of them will be graded. All calculations should be done analytically, unless marked with an (M). (M) problems require the use of MAT-LAB. ES denotes the online lecture notes.

- 1. (20 points) (ES, p.142, #1) Problem 1 in the ODE5 section of the notes (end of chapter 2).
- 2. (20 points) (ES, p.142, #3) Problem 3 in the ODE5 section of the notes (end of chapter 2).
- 3. (20 points) (ES, p.142, #4) Problem 4 in the ODE5 section of the notes (end of chapter 2). Note:
  - (a) See the previous problem for an introduction to vital dynamics.
  - (b) Your answers to the existence of steady states and stability will depend on parameter values. Thus, you should state cases for the different parameter regimes.
- 4. (20 points) (ES, p.143, #6) Problem 6 in the ODE5 section of the notes (end of chapter 2). Note:
  - (a) You will need to compute a Jacobian matrix for this  $3 \times 3$  system. You **cannot** use the trace-determinant diagram used for  $2 \times 2$  systems (it no longer applies). Thus, you must find the eigenvalues, and examine them directly to determine stability.
  - (b) As in the previous problem, your answers to the existence of steady states and stability will depend on parameter values.
- 5. (20 points) (M) Consider the SIRS model

$$\frac{dS}{dt} = -0.003SI + 0.5(1000 - S - I)$$
$$\frac{dI}{dt} = 0.003SI - I.$$

Note that this set of equations corresponds to parameter values  $N = 1000, \beta = 0.003, \nu = 1, \gamma = 0.5$ . Use MATLAB to numerically solve the above system of ODEs on the time interval [0, 20], with initial conditions S(0) = 999, I(0) = 1. Please **don't** hand-in a list of numeric values for the solutions; simply plot the curves S(t), I(t), R(t) = N - S(t) - I(t) on the same set of axes. That is, you should plot S vs. t, I vs. t, and R vs. t on one plot. You may use the following MATLAB code as a template; note that like last time, it is not complete. It is fairly well-commented, with some comments containing hints.

```
%Constants defined for SIRS model
beta=;
nu=;
gamma=;
N=;
%Define the initial conditions
S0=;
I0=;
t0=0;
tF=20;
initials=[S0,I0];
Now solve the ode and plot the trajectories from t=0 to t=20 (arbitrary)
[T,SI]=ode45(@rhsHw6No1,[t0 tF],initials,[],beta,gamma,nu,N);
S=SI(:,1); %S population is first column of SI
I=;
            %I population is second column of SI
R=;
           %R is the "leftover" population from N (which is constant).
            %Note that you can be naive here, even if the dimensions...
           %...don't seem to make sense.
%Plot the solutions
figure(1)
plot(T,S,'-b','LineWidth',2); %Plot of susceptibles
hold on;
plot(,'--r','LineWidth',2); %Plot of infected
plot(,'-.k','LineWidth',2); %Plot of recovered
legend('S(t)','I(t)','R(t)');
xlabel('t');
ylabel('number of individuals');
title('SIRS model dynamics');
```

You must also define the vector field (i.e. the RHS of the ODE) in a separate m-file, entitled rhsHw6No1.m. The skeleton for that file is below. Note that you must fill-in the second component for it to run.

```
function dSIdt=rhsHw6Nol(t,SI,beta,gamma,nu,N)
S=SI(1) % corresponds to susceptible
```

```
I=SI(2) % corresponds to infected
%The first entry corresponds to the equation for dS/dt, while the ...
% ... second is for dI/dt
dSdt = -beta*S.*I+gamma*(N-S-I);
dIdt = ;
dSIdt=[dSdt;dIdt];
end
```