

9-12-2013 → 9-13-2013

Berlin School of Math Berlin Lectures
 Introduction to Teichmüller theory
 lecture 1. Hyperbolic Geometry

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Let $\mathbb{H}^2 = \{z \in \mathbb{C} \mid y > 0, z = x+iy\}$ upper half plane

The Riemannian metric

$$\frac{ds^2}{h} = \frac{dx^2 + dy^2}{y^2} = \frac{|dz|^2}{y^2} \quad \text{on } \mathbb{H}^2$$

• Angles in $\frac{ds^2}{h}$ = angles in \mathbb{R} . conformal

• Length of $\gamma(t) = (x(t), y(t)) \quad t \in [a, b]$:

$$L(\gamma) = \int_a^b |\gamma'(t)|_{ds^2} dt$$

$$\gamma'(t) = (x'(t), y'(t))$$

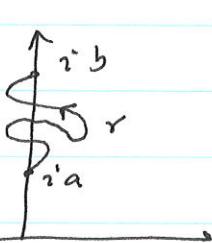
$$|\gamma'(t)|_{ds^2} = \sqrt{x'(t)^2 + y'(t)^2} / y(t) \geq \frac{|y'(t)|}{y(t)} \quad \underline{\text{equality iff } x' = 0}$$

$$\text{so} \quad L(\gamma) = \int_a^b \frac{\sqrt{x'(t)^2 + y'(t)^2}}{y(t)} dt$$

Lemma: The positive y -axis is a geodesic in (\mathbb{H}^2, ds^2) s.t.

$$d(i\alpha, i\beta) = \left| \ln \frac{\beta}{\alpha} \right|$$

Pf Say $\gamma(a) = i\alpha, \gamma(b) = i\beta \quad a < b \text{ real}, y(t) > 0,$



$$\begin{aligned} L(\gamma) &\geq \int_a^b \frac{\sqrt{y'(t)^2}}{y(t)} dt = \int_a^b \frac{|y'(t)|}{y(t)} dt \\ &\geq \left| \int_a^b \frac{y'(t)}{y(t)} dt \right| = \left| \ln y(t) \right|_a^b = \ln \frac{\beta}{\alpha} \end{aligned}$$

Equality holds iff $x'(t) = 0, y'(t) \geq 0$ i.e. $\gamma([a, b]) \subset y\text{-axis}$ & monotonic.

□

Lemma 2. $f(z) = \frac{az+b}{cz+d}$, $\begin{bmatrix} a & b \\ c & d \end{bmatrix} \in SL(2, \mathbb{R})$, $H \rightarrow H$ are isometries

Pf f is a composition of $z \mapsto z+b$, $z \mapsto \lambda z$ $\lambda \in \mathbb{R}$ and

$z \mapsto -\frac{1}{z} = \omega$. Obviously $f(z) = \lambda z + b \in Iso(\mathbb{H}^2)$. Now,

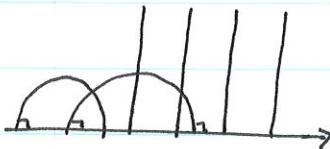
$$\text{for } \omega = -\frac{1}{z} \quad d\omega = \frac{1}{z^2} dz \Rightarrow \quad Im(\omega) = \frac{1}{2i} \left(\frac{1}{z} - \frac{1}{\bar{z}} \right)$$

$$\begin{aligned} \omega^*(ds^2) &= \frac{|d\omega|^2}{Im(\omega)^2} = \frac{\frac{1}{|z|^4} |dz|^2}{\left(\frac{1}{2i}\right)^2 \left(\frac{1}{z} + \frac{1}{\bar{z}}\right)^2} \\ &= \frac{\frac{1}{|z|^4} |dz|^2}{\frac{1}{|z|^4} \cdot \frac{1}{4} |\bar{z}-z|^2} = \frac{|dz|^2}{y^2} \end{aligned}$$

□

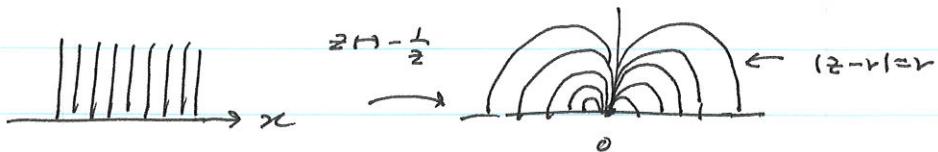
Corollary 3. All geodesics in H are, either $Re(z) = c$ or $|z-a|=r$

$$a, c \in \mathbb{R}$$



Pf. y -axis geodesic + $z \mapsto z+b$ iso $\Rightarrow Re(z)=c$ geod.

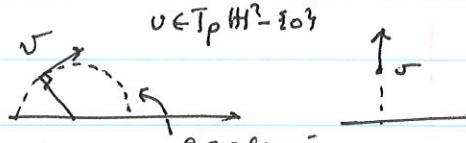
$Re(z)=c$ geodesic + $z \mapsto -\frac{1}{z}$ iso $\Rightarrow |z-r|=r$ geodesic



Now $z \mapsto z+b$ iso $\Rightarrow Re(z)=c + |z-a|=r$ geodesic

These are all geodesics: $v \in T_p \mathbb{H}^2 - \{0\}$

Geodesic determined by ONE tangent



□

Homework: Show that $\text{PSL}(2, \mathbb{R}) = \text{SL}(2, \mathbb{R}) / \pm \text{Id} \cong \text{Isd}(\mathbb{H}^2)$

hint: If $r \in \text{Isd}(\mathbb{H}^2)$, find $f \in \text{PSL}(2, \mathbb{R})$ s.t

$$(1) \quad f(i) = r(i)$$

$$(2) \quad f'(i) = r'(i).$$

Cross ratio: $a, b, c, d \in \widehat{\mathbb{C}}$ distinct define

$$(a, b, c, d) = \frac{a-c}{a-d} : \frac{b-c}{b-d}$$

We know $f \in \text{PSL}(2, \mathbb{C})$, Möbius

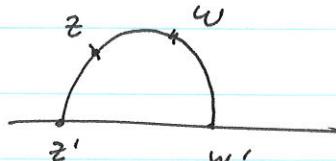
$$f(z) = \frac{az + \beta}{cz + \delta} \quad [a, \beta, \gamma, \delta] \in \text{SL}(2, \mathbb{C}) \Rightarrow$$

$$(f(a), f(b), f(c), f(d)) = (a, b, c, d)$$

$$a < b$$

$$\text{Also } d(ia, ib) = \ln\left(\frac{b}{a}\right) = \ln(ia, ib, \infty, 0) \quad (1)$$

Corollary 4: If $z, w \in \mathbb{H}$, then $d(z, w) = \ln(z, w, w', z')$.



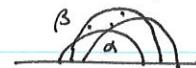
Pf: Let $f \in \text{PSL}(2, \mathbb{R})$ sending $f(z) = ia$, $f(w) = ib$, then
 $f(z') = \infty$, $f(w') = \infty$. done

$$d(z, w) = \frac{f \text{ isd}}{f \text{ linear}} d(ia, ib)$$

$$= \boxed{\ln(ia, ib, \infty, 0)} \\ \ln(z, w, w', z')$$

Hw Gauss-Bonnet: The area of a hyperbolic triangle Δ of angles α, β, γ is $\pi - \alpha - \beta - \gamma$

of angles α, β, γ is $\pi - \alpha - \beta - \gamma$



Hyperbolic Geometry \mathbb{H}^2

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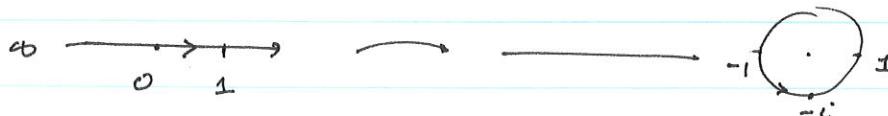
The ball model.

Note: $f(z) = (z, a, b, c)$ Möbius

$$= \frac{z-b}{z-c} : \frac{a-b}{a-c} \quad \text{seems} \quad \begin{matrix} b \mapsto 0 \\ c \mapsto \infty \\ a \mapsto 1 \end{matrix}$$

$$\underline{\text{So}} \quad f(z) = (z, 1, i, -1) = \frac{z-i}{z+i} : \frac{1-i}{2} \quad \infty \mapsto$$

Eg $\varphi(z) = \frac{z-i}{z+i} : \begin{matrix} i \mapsto 0 \\ -i \mapsto \infty \\ 0 \mapsto -1 \\ \infty \mapsto 1 \end{matrix}$ and $1 \mapsto -i$



$$\varphi: (\mathbb{H}) = \mathbb{D} = \{ |z| < 1 \}$$

The metric on \mathbb{D} making φ isometry: $\frac{4(dx^2+dy^2)}{(1-x^2-y^2)^2} = \frac{4|dz|^2}{(1-|z|^2)^2}$

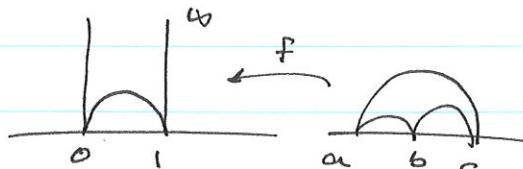
Isometries: Möbius transf. preserving \mathbb{D} : $z \mapsto e^{i\theta} \frac{z-a}{az-1}$

Geodesics: lines and circles $\perp \partial\mathbb{D}$



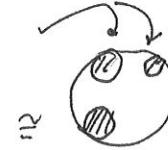
Eg Any two ideal triangles in \mathbb{H} are isometric: all isometric to

$(0, 1, \infty)$ due to $f(z) = (z, a, b, c)$. $a, b, c \in \mathbb{R}$ cross ratio



(order)

horoballs Euclidean disks tangent to x -axis
or $\text{Im}(z) \geq -1$



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Lecture 2 Hyperbolic Structures on Surfaces

Uniformization theorem Σ surface, connected, $X(\Sigma) < 0$, then \exists Riemannian

metric g on Σ , $\exists: u: \Sigma \rightarrow \mathbb{R}$ s.t.

$(\Sigma, e^u g)$ is a complete hyperbolic metric.

(Gaussian curvature = -1).

\Rightarrow We should study hyperbolic metrics on surfaces & organize them.

Def 1. A hyperbolic structure on surface Σ : special collection of charts $\{\phi_i: U_i \rightarrow \mathbb{H}^2\}_{i \in I}$ s.t.

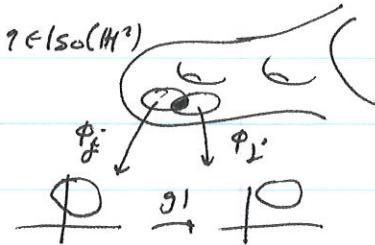
$$(1) \quad \Sigma = \bigcup_i U_i$$

$$(2) \quad \phi_i: U_i \rightarrow \mathbb{H}^2 \text{ is continuous}$$

$$(3) \quad \phi_i \circ \phi_j^{-1} = g|_{\phi_i(U_i \cap U_j)}, \quad g \in \text{Isom}(\mathbb{H}^2)$$

The structure is complete if

each geodesic extends to ∞ .



Geodesics, also in $(\Sigma, g) \Leftrightarrow$ using charts

Eg 2. (\mathbb{H}^2, ds^2) complete hyperbolic $d(i\alpha, i\beta) \rightarrow +\infty \quad t \rightarrow +\infty \text{ or } t \rightarrow \underline{0}^+$

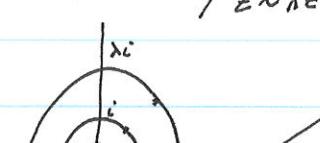
Eg 3. $\gamma(z) = \lambda z, \lambda > 1$ acts on \mathbb{H}^2 generates a group

$\mathbb{H} = \langle \gamma^* \rangle$, the quotient space

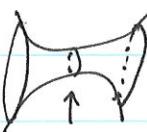
Eg 3' $\mathbb{H}/\langle z \mapsto \lambda z \rangle$ cusp $\mathbb{H}/\langle z \mapsto \lambda z \rangle =$ a hyperbolic annulus



cusp



$\mathbb{H}/\langle z \mapsto \lambda z \rangle$



a hyperbolic annulus

length of the shortest geod [boxed]

non-isometric

$\Rightarrow \exists$ many distinct hyperbolic structures in $S^1 \times \mathbb{R}$.

Eg 4. $\Gamma(2) = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in \text{SL}(2, \mathbb{Z}) \mid \begin{bmatrix} a & b \\ c & d \end{bmatrix} \equiv \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \pmod{2} \right\} / \pm \text{id}$

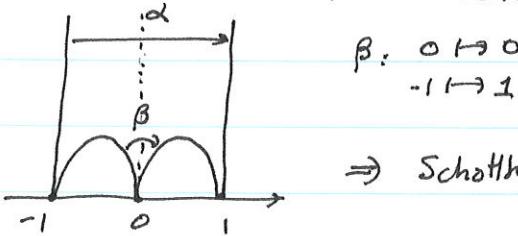
L 2

$P(2)$ acts on H^2 freely properly discontinuously w/ quotient

$$\frac{H^2}{P(2)} \cong \text{metric double of an ideal triangle} \cong \mathbb{C} - \{\infty\}$$

Sketch:

$P(2)$ generated by $\alpha(z) = z + 2 \Leftrightarrow \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$ and
 $\beta(z) = \frac{z}{2z+1} \Leftrightarrow \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$.



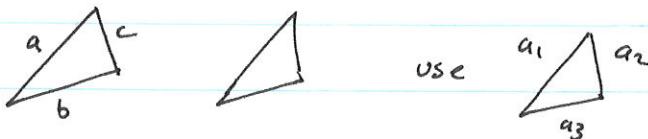
\Rightarrow Schottky group \Rightarrow result.

equivalence classes

What is Teichmuller theory?: space of all hyperbolic metrics on Σ .

$M(\Delta) =$

Eg 5. Let $M(\Delta) =$ space of all triangles in \mathbb{E}^2 modulo isometries



Q. Is $M(\Delta) = \{(a, b, c) \in \mathbb{R}_{>0}^3 \mid a+b>c, b+c>a, c+a>b\}$?

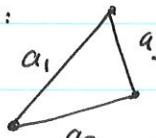
ANS: IS NO. $M(\Delta) = \{(a_1, a_2, a_3) \in \mathbb{R}_{>0}^3 \mid a_i + a_j > a_k\}$.

In fact $M(\Delta)$ is the "moduli" space (Riemann)

$T(\Delta) =$ space of all labelled triags in \mathbb{E}^2 modulo isometries preserving labelling

$T(\Delta) =$ Teichmuller space:

so Space $\{(a_1, a_2, a_3) \in \mathbb{R}_{>0}^3 \mid a_i + a_j > a_k\}$ ← what we know first second third

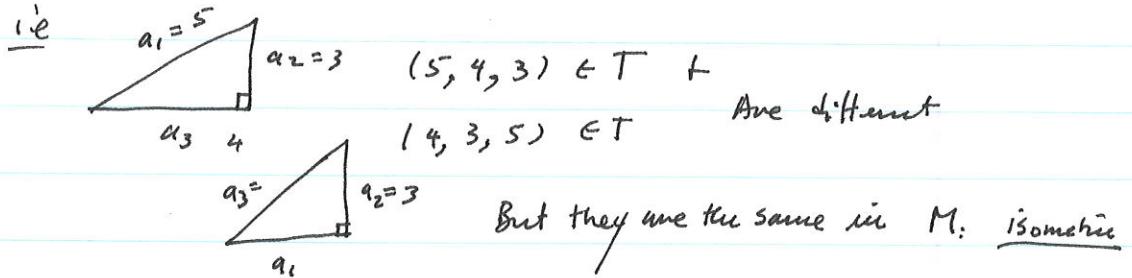


marked triags (verts edges v_1, v_2, v_3)
Modulo isometries fixing midline

L3. Topological Triangulations

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$$M = T / S_3 \quad S_3 \text{ the permutation group}$$



The ultimate goal: (Riemann's moduli space)

$$\text{Mod}(\Sigma) = \{ (\Sigma, d) \mid d \text{ complete hyperbolic metric on } \Sigma \} / \text{isometry}$$

finite area

Very difficult to study.

Teichmüller space

$$\begin{aligned} T(\Sigma) &= \{ (\Sigma, d) \mid (\Sigma, d) \xrightarrow{\tau} (\Sigma, d') \text{ if } \exists \text{ isometry } \tau \cong \text{id} \} \\ &= \{ (\Sigma, d) \mid d \sim \text{isometry homotopic to id.} \} \end{aligned}$$

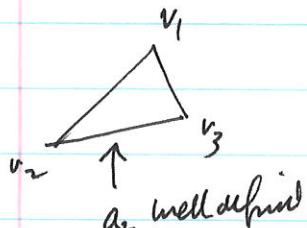
Why $T(\Sigma)$?: Just like $T(\Delta)$: we can define the length of a loop (edge). The lengths of the 2nd edge functions do not make sense in $M(\Delta)$!

So \forall loop $\alpha \subset \Sigma$

def: $T(\Sigma) \rightarrow \mathbb{R} \quad (\Sigma, d) \mapsto$ length of the shortest path $\alpha' \subseteq \alpha$ in d .

Why $\text{Teich}(\Delta)$?: We can talk about the i -th edge lengths

$$\text{ai}: \text{Teich}(\Delta) \rightarrow \mathbb{R}_{>0}$$



No such function in $\text{Mod}(\Delta)$? $\rightarrow \min\{a_1, a_2, a_3\}$

Only the minimal length.

\uparrow α
Not smooth

Σ orientable

①

$d = \text{complete Riemannian metric}$
Ratio area

Main goal Σ topological surface w/ complete hyperbolic structure

$$\text{mod}(\Sigma) = \{(\Sigma, d) \mid d \text{ complete hyperbolic metric}\}$$

What is the space? dim? connected? Topology? Geometry?

$$T(\Sigma) = \{(\Sigma, d) \mid d \text{ --- } \text{isometry homotopic to id}\}$$

$$\text{ie } (\Sigma, d) \underset{\text{Teich}}{\sim} (\Sigma, d') \text{ if } \exists \text{ iso } h: (\Sigma, d) \rightarrow (\Sigma, d') \text{ s.t. } h \approx \text{id}$$

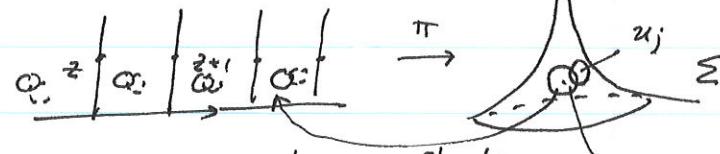
$$\text{so } \text{mod}(\Sigma) = T(\Sigma) / MCG(\Sigma)$$

$$\text{MCG} = \{\text{orientations preserving homeo}\} / \{h \mid h \approx \text{id}\}$$

This plays the role of choice of marking S_3 for Δ .

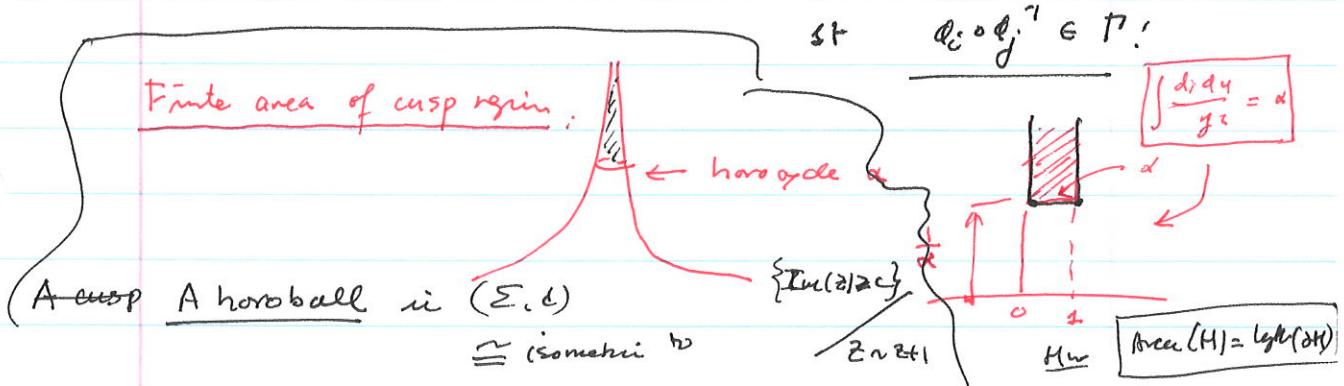
Key fact: Each loop $\alpha \subset \Sigma$ lengths $\ell_\alpha: T(\Sigma) \rightarrow \mathbb{R}$ $\beta \approx \alpha$
 $\ell_\alpha \downarrow_{\text{d}} \rightarrow \text{length of the start}$

(2) May one winds about hyperbolic st. on H/Γ_0 $r \in \text{Isom}(H)$
 How to see the charts?

Ex. $\Sigma = H/\Gamma_0$ 

$$\phi_i = (\pi|v_i)^{-1}, \phi_j = (\pi|v_j)^{-1}, \phi_i \circ \phi_j^{-1} \in \langle r \rangle$$

More generally, H/Γ_0 has charts $\{(u_i, \phi_i) \mid i \in I\}$



$$S_g \boxed{\text{closed surface}} \quad V = \{v_1, \dots, v_n\} \subset S \quad \Sigma = S_g - V \cong \Sigma_{g,n}$$

~~orientable~~ oriented

$$\chi(\Sigma) < 0$$

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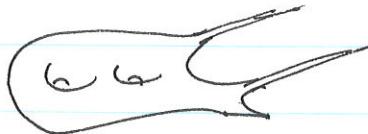
L3 Topological Triangulations

cupola torus case

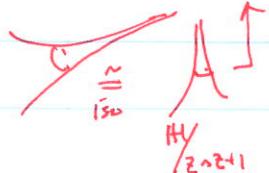
- Q. How to construct cell $\underline{\text{hyperbolic}}$ structures on Σ which is non-closed? w/ $\chi(\Sigma) < 0$.? Known fake area \Rightarrow cusp end!

$$\Sigma = \Sigma_g - \{v_1, \dots, v_n\} \quad n \geq 1$$

$$\chi(\Sigma) < 0 \Leftrightarrow g=0, n \geq 3.$$



$$V = \{v_1, \dots, v_n\}$$



Ans Use triangulations

oriented



2-Dimensional triangulations.

Take a finite collection of disjoint triangles $\Delta_1, \dots, \Delta_k$, identifying pairs of edges in $\sqcup \Delta_i$ by orientation reversing homeomorphisms,

The quotient space $S = \sqcup \Delta_i / \sim$ is a compact surface w/
oriented

a triangulation T : simplices in $T \leftrightarrow$ quotient of simplices in $\sqcup \Delta_i$.

Let V, E be the sets of vertices and edges respectively in T .
 $V(T)$ $E(T)$

We say T an ideal realization of $S - V$.

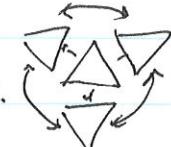
Eg



dome of a tiger, or

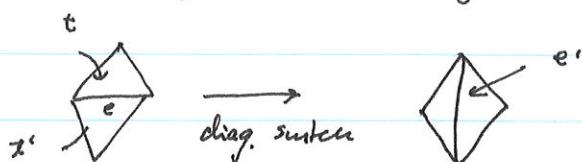


(tetra).



Def Diagonal switch: If $e \in E$ is adjacent to two triangles

t, t' , then



$T \rightarrow T'$ by replacing e by the other diagonal in $t \cup t'$.

$$V(T) = V(T')$$

Thus If T, T' two triangulations of S with the same set of vertices

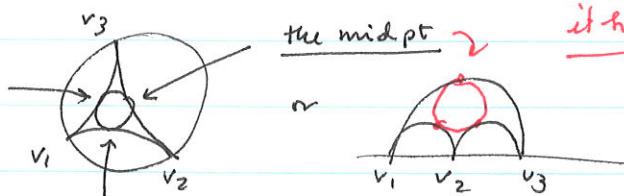
then \mathcal{T} and \mathcal{T}' are related by a sequence of diagonal switches.

Each $\Sigma = \Sigma_{g,n}$ 2-2g-ncg has an ideal metric (u20)

- Q Suppose (Σ, \mathcal{T}) ideal triangulated surface, How to use \mathcal{T} to produce all hyperbolic metrics on Σ ?

Thurston's work

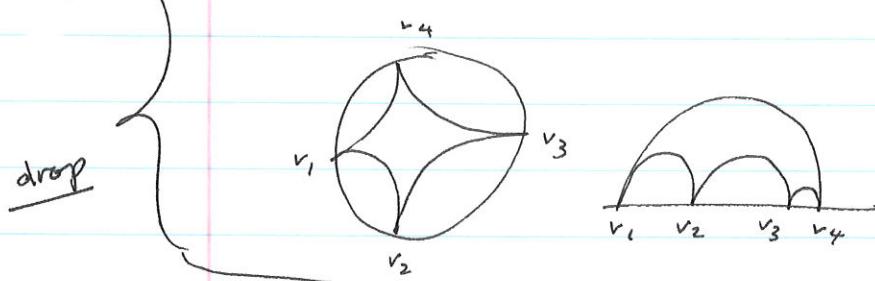
ideal triangle: convex hull of 3 points $v_1, v_2, v_3 \in \partial \mathbb{H}^2$



it has 3 mid pts

ANY two of them
are isometric
 $f(z) = (z, v_1, v_2, v_3)$

ideal quadrilateral: convex hull of 4 points $v_1, v_2, v_3, v_4 \in \partial \mathbb{H}^2$



Not all are isometric
since the cross ratio

(v_1, v_2, v_3, v_4) is an isometry invariant.

A marked ideal quad δ ~~is a marked quadrilateral~~

= union of two ideal triangles
along an edge e.

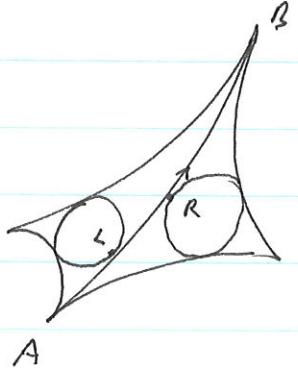


Every surface is oriented

Def. Thurston's shear coordinate $d(\delta)$ of an oriented marked ideal quad δ is the real number $d(\delta) =$ signed distance from L to R along the diagonal.

L3. Thurston's Shear Coordinate

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orientate $e: A \rightarrow B: L \rightarrow R$

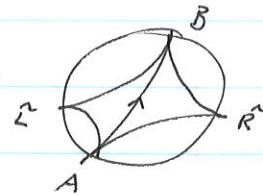
so $d(\delta) = R-L$ computed along e

Note independent of the choice of orientations on e
(depending only on the orientations of δ !)

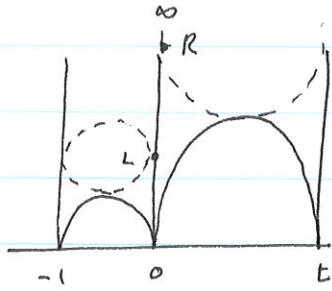
Lemma 1. suppose $\delta = [A, \tilde{R}, B, \tilde{L}]$ as shown

then

$$d(\delta) = \ln[-(A, B, \tilde{R}, \tilde{L})]$$



Proof May assume after a Möbius transf $A=0, B=\infty, \tilde{R}=t, \tilde{L}=-1$



$$(A, B, \tilde{R}, \tilde{L}) = (0, \infty, t, -1)$$

$$= \frac{0-t}{0+1} : \frac{\infty-t}{\infty-1} = -t$$

$$L = i \quad R = it$$

$$\text{so } d(\delta) = \boxed{\ln(t)}$$

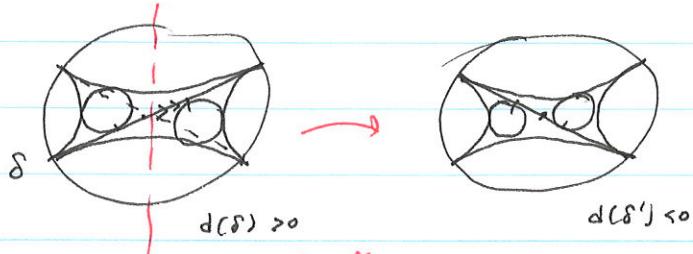
□

Lemma 2. Suppose δ' is obtained from δ by a diagonal switch $\Rightarrow d(\delta') = -d(\delta)$

$$\text{switch } \Rightarrow d(\delta') = -d(\delta)$$

Pf Follows from the basic property of cross ratio. Or

a geometric proof:



$$|d(\delta)| = |d(\delta')|$$

hyperbolic reflection
 $(x,y) \mapsto (-x,y)$

iso

□

L4 The shear coordinate of Thurston

Assume $\Sigma = \Sigma_g - \{v_1, \dots, v_n\}$ no 1, $\chi(\Sigma) < 0$

(Σ, \mathcal{T}) ideal triangulation

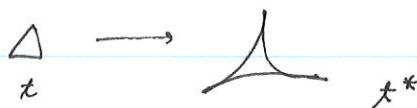


Fixed | \mathcal{T}

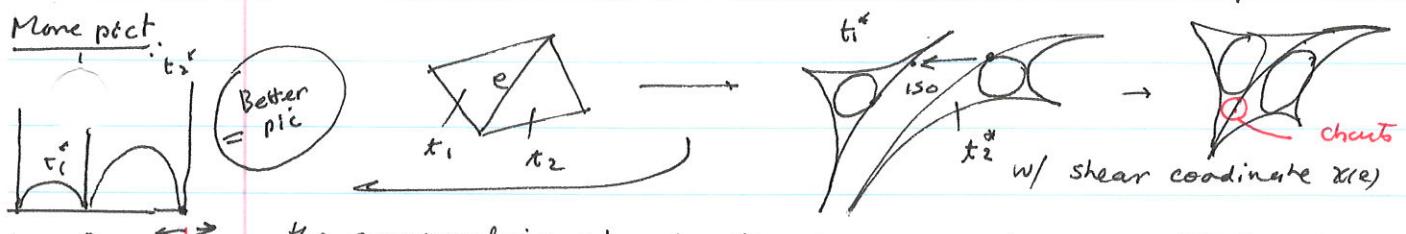
For each $x \in \mathbb{R}^{E(\mathcal{T})}$ i.e. $x: E(\mathcal{T}) \rightarrow \mathbb{R}$, one produce a

(possibly unique) hyperbolic structure $\pi(x)$ on Σ as follows

(1) replace each triangle $\Delta \in \mathcal{T}$ by an ideal hyperbolic triangle



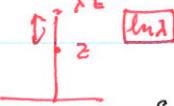
(2) each edge $e \in E(\mathcal{T})$ with $x(e)$ assigned, glue isometrically $t_1^* t_2^*$



the corresponding edge by the isometry s.t. the resulting shear coordinate at e is $x(e)$. There is a unique way to glue.

infinite geodesic

$$L = \{ \text{Re}(z_1 z_2) = 0 \}$$



finite area

translations

$$f_\alpha(z) = z, L \rightarrow L$$

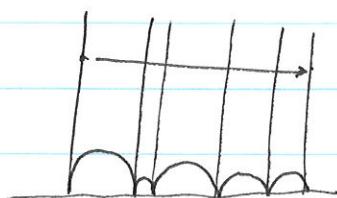
$$d(z, f_\alpha(z)) = \text{dist}$$

Lemma

$\pi(x)$ is a complete metric $\Leftrightarrow \forall v \in V = \{v_1, \dots, v_n\}$

$$\sum_{e \ni v} x(e) = 0 \quad \xrightarrow{\text{cusp end}}$$

Proof At v_i say put it at ∞



glued isometrically

$$\Leftrightarrow \sum_{e \ni v} x(e) = 0$$

to produce a cusp end to be complete

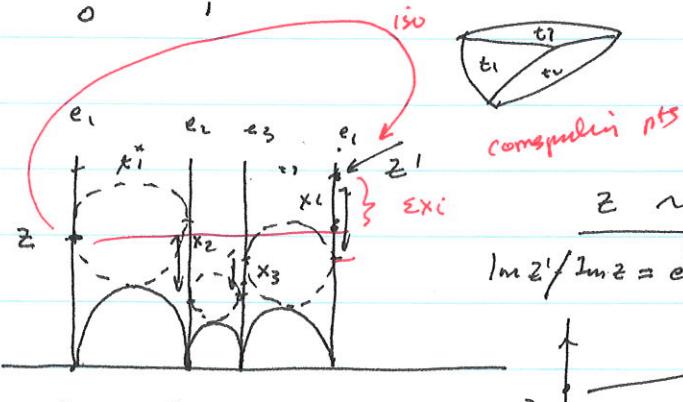


\Leftarrow done

pf sketch. Topology at v

Geometry:

z' at height

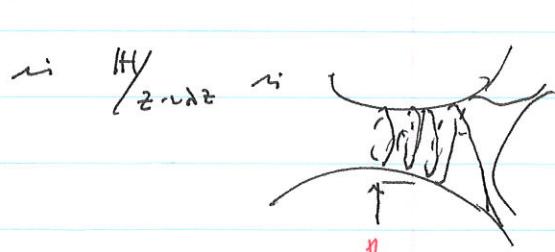
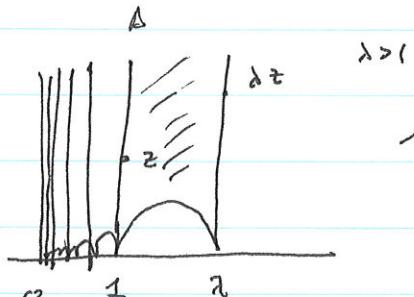


$$\frac{z \sim z'}{\ln z' / \ln z = e^{x_1 + x_2 + \dots + x_l}}$$

by tree construction

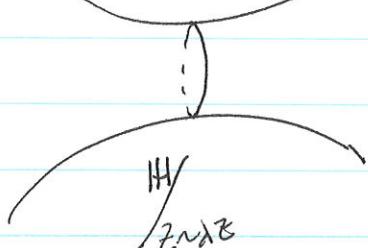
must be horizontal hyperboli
in order to produce cusp
 $\Rightarrow \sum k_i = 0$

Eg. The image
of a branch

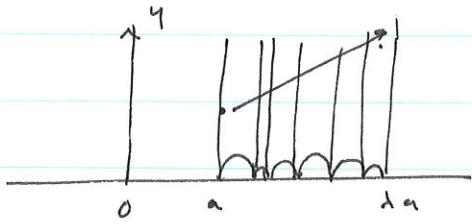


π quini- age of A
spiral

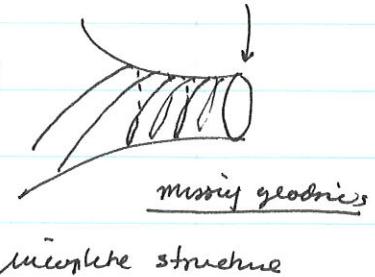
incomplete stretch



Note if $\sum_{e \in V} x(e) \neq 0$, the gluing is



\Rightarrow the infinity



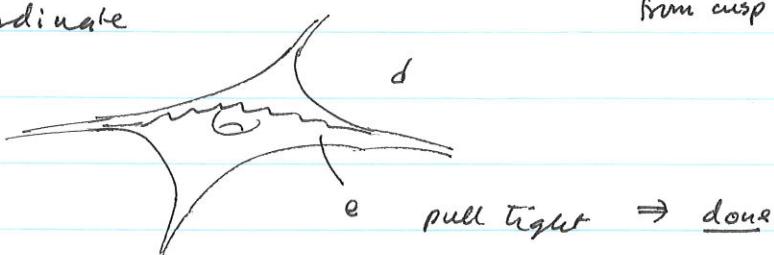
Let $R_p^E = \{x \in R^E \mid \forall v \in V \quad \sum_{e \in v} x(e) = 0\}$ (linear subspace)

Thm (Thurston) The map $\Phi: R_p^E \rightarrow T(\Sigma) \quad x \mapsto [\pi(x)]$
is a homeomorphism. $\Phi(x)$ has shear coordinate x w.r.t. \mathcal{T} .
(1-1 and onto map.)

Proof Φ is onto: If $[d] \in T(\Sigma)$ + \mathcal{T} ideal triangulation \mathcal{T}

We can isotope \mathcal{T} to be a geodesic triangulation of (Σ, d)
where all edges are infinite simple geodesics $\Rightarrow x =$ shear
coordinate

from cusp to cusp

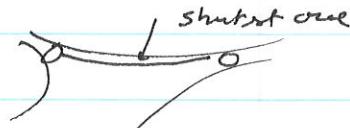
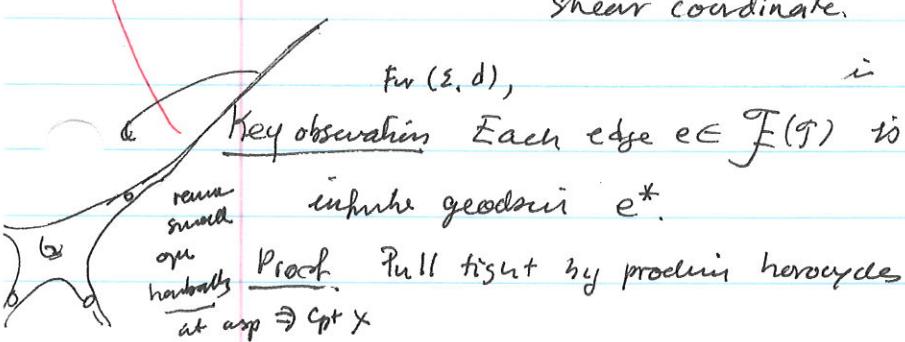


" Φ is 1-1:" if $\phi(x) = \phi(x')$ \Rightarrow they have the same
shear coordinate. How to see it?

For (Σ, d) ,

$\in (\Sigma, d)$

Key observation: Each edge $e \in \mathcal{F}(\mathcal{T})$ is homotopic to a unique
infinite geodesic e^* .



Proof. Pull tight by producing horocycles

□

Φ is 1-1: \exists an isometry

$$h: (\Sigma, \phi(x)) \rightarrow (\Sigma, \phi(x'))$$

$$\Rightarrow h(\mathcal{T}_x) = \mathcal{T}_{x'} \quad (\circ)$$

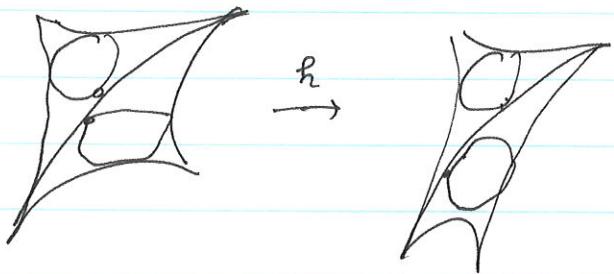
$\mathcal{T}_x, \mathcal{T}_{x'}$ geodesic completeness in $d(x) \times d(x') \text{ metric}$

$$h(e) \simeq e$$

$$h \simeq id$$

\Downarrow ϕ is identity

proven



most precise
tree distance

The point is that $T_{x'}$ is unique!

Why is the geodesic e^* unique:

Two homotopic geodesics

\exists a map $f: I \times I$

homotopy

geod

$y \ni e_1, e_2$ homotop

cusp

cut

$\Rightarrow \exists$ a right
angled square

in H

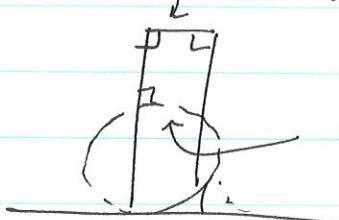
lifted in tree form
con

horocycle

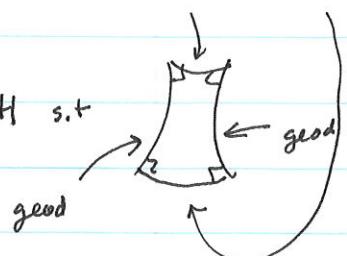
impossible

horocycle

unusual cover



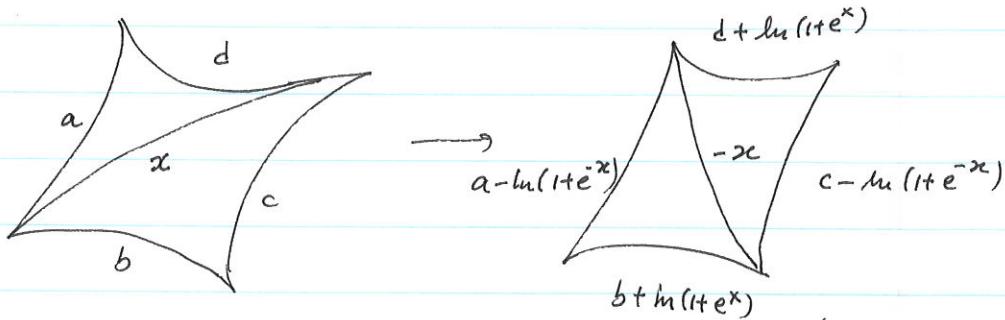
$\Rightarrow \exists$ a right-angled quadrilateral $Q \subset H$ s.t.



skip it for now

Thm If $\mathcal{T}, \mathcal{T}'$ two triangulations related by a diagonal switch,
then the transition function $\Phi_{\mathcal{T}}^{-1}, \Phi_{\mathcal{T}'} : \mathbb{R}_p^{E(\mathcal{T})} \rightarrow \mathbb{R}_p^{E(\mathcal{T}')}$
takes the following form.

real analytic

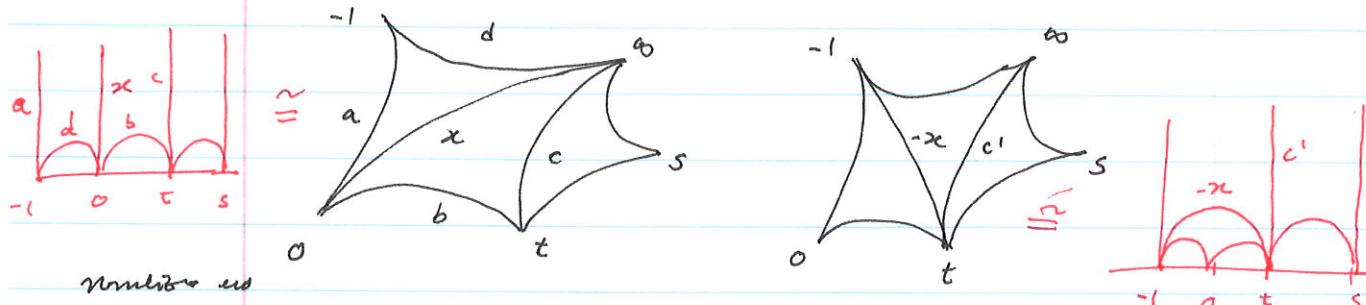


all other places remain the same. (Right-hand oriented)

Proof Follows from the basic cross ratio rule. \square

We may assume the end points are:

$$s > t > 0$$



Hence: $x = \ln t$

$$c = \ln(-1)(t, \infty, s, 0) = \ln\left(\frac{t-s}{t-0}\right)(-1) = \ln\left(\frac{s-t}{t}\right)$$

$$c' = \ln\left[-1(t, \infty, s, -1)\right] = \ln(-1)\frac{t-s}{t+1} = \ln\frac{s-t}{(t+1)}$$

$$= \ln\left(\frac{s-t}{t}\right) + \ln\left(\frac{t}{t+1}\right) = c - \ln\left(1 + \frac{1}{t}\right) = c - \ln(1 + e^{-x})$$

\square

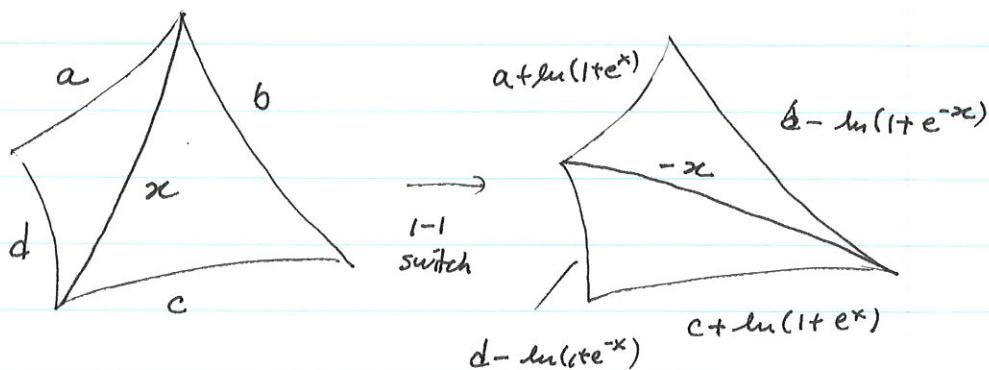
RM: Basic rule: Right "shoulder" Add $\ln(1+e^x)$, left: - $\ln(1+e^{-x})$

corollary $\Rightarrow \mathcal{T}(E)$ is a real analytic and differs $R^{\frac{6g-6+2n}{2}}$.

$$= x - \ln(1 + e^x)$$

L5. Penner's & length coordinates, Poisson Structures. Continue.

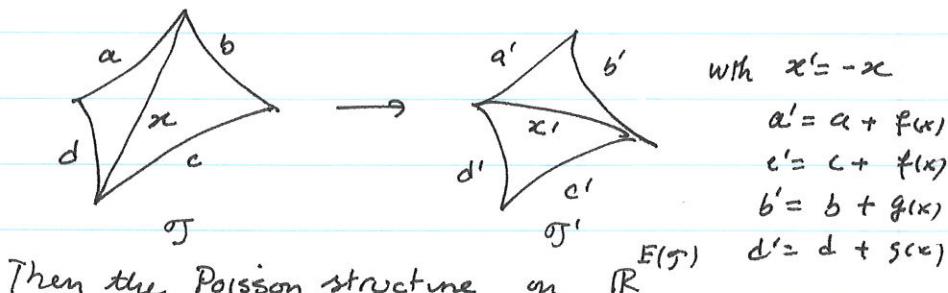
Summary the change of coordinate formula for Thurston shear coord.



Any property invariant under the coordinate change is an invariant of the Teichmller space.

(HW) Thm. Suppose $f(t)$, $g(t)$ smooth sat $f(t) + g(t) = x$

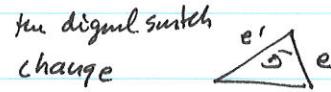
and a coordinate change rule:



Then the Poisson structure on $\mathbb{R}^{E(\mathcal{T})}$

$$\sum_{\substack{e \in \Delta \\ e \rightarrow e'}} \frac{\partial}{\partial x_e} \wedge \frac{\partial}{\partial x_{e'}}$$

is invariant under coordinate change



where $e \rightarrow e'$ means $\exists \Delta \in \mathcal{T}^{(2)}$ adjoint to both e & e'
 + $e \rightarrow e'$ in the orientation of Δ .

($\Rightarrow T(\Sigma)$ is naturally a symplectic mfd)

Homework
Just do it

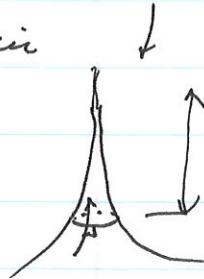
Recall

$d \rightarrow$ complete finite area hyperbolic

A horoball $H \subset (\Sigma, d)$ is a subsurface

isometric to

$$\{Im(z) \geq \frac{1}{(e^{-z} + 1)}\}$$



Fact: (Σ, d) compact. ~~every surface of~~ ~~near each v_i .~~

horoballs form neighborhoods of singularity of Σ

- $\text{Area}(H) = \text{length}(\partial H)$ (Homework)



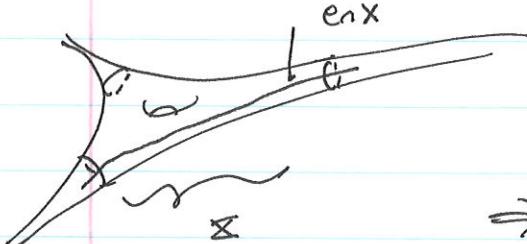
- (Σ, d) take H_1, \dots, H_n disjoint horospheres about v_i .

$X = \Sigma - \bigcup_i H_i$ is a compact surface w/ ∂X

horocycles.

Key lemma (Σ, d) , \mathcal{T} ideal hyperbolic $\forall e \in E(\mathcal{T}) \rightarrow$
homotopic to a unique geodesic e^* in d .

Pf existence Form X + pull tight $e \cap X$



Let α be path in X

st ① $\alpha \cong e \cap X$ rel(∂X)

② α has the shortest length

$\Rightarrow \alpha$ geod. + $\alpha \perp \partial X$ (X cpt)

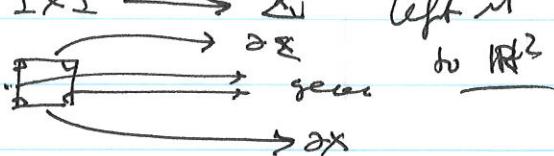
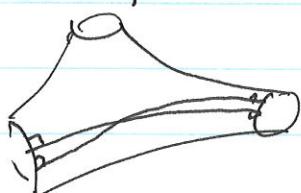
$\Rightarrow \alpha$ extends to a geodesic e^*

going to the cusp

Uniqueness if $\exists e_1^* \cong e_2^*$ homotopic geodesics

both go into cusps v_i to $v_j \Rightarrow e_1^* \cap X \cong e_2^* \cap X$ rel(∂X)

$\Rightarrow \exists f: I \times I \rightarrow X$ left \cong



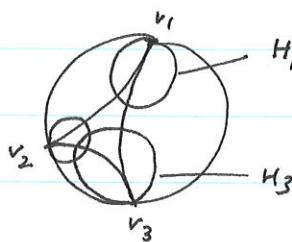
Penner's theory of Decorated Hyperbolic

- 15 -

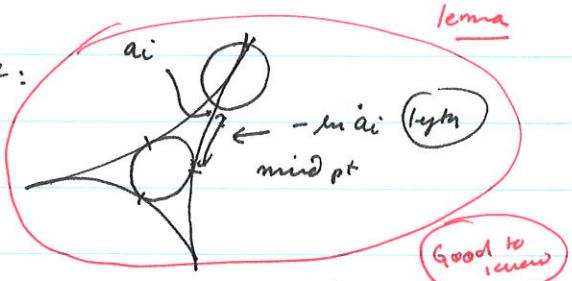
L5 Penner's λ -coordinate

A decorated ideal triangle τ : ideal triangle w/ vertices $v_1, v_2, v_3 \in \partial \mathbb{H}^2$

s.t each v_i is associated with a horoball H_i at v_i .

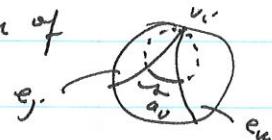


picture:

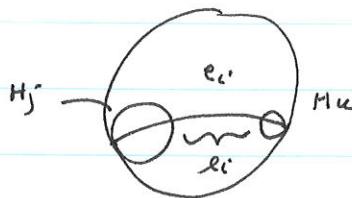


Let the edges of τ be e_1, e_2, e_3 (infinite geodesic) e_i opposite to v_i .

Then the angle a_i of τ at v_i is: the length of

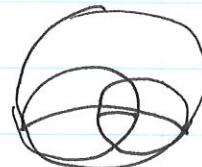


The length l_i of τ at e_i . $l_i \in \mathbb{R}$



$$l_i = \text{length}_{\geq 0}$$

$$H_j \cap H_n = \emptyset$$



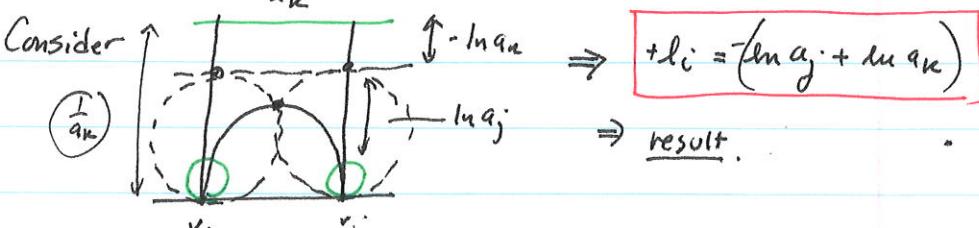
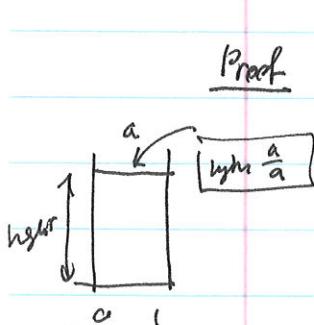
$$-l_i = \text{length}_n.$$

Penner $L_i = e^{\frac{1}{2}l_i} \in \mathbb{R}_{>0}$ the ~~λ~~ -length of e_i

Lemma (1) $a_i = e^{\frac{1}{2}(l_i - l_j - l_n)} = \frac{l_i}{l_j l_n}$ $\mu a_i = \frac{1}{2}(\ln l_i - \ln l_j - \ln l_n)$

(2) $-\mu a_i = \text{dist } H_i \text{ to mid pt}$

(3) $\forall l_1, l_2, l_3 \in \mathbb{R}$, \exists decorated ideal tetra of lengths l_1, l_2, l_3 (HW)



(2) The angles $a_i, a_j, a_k \in \mathbb{R}_{>0}$ can be arbitrary real numbers as shown above \Rightarrow result.

□

A decorated hyperbolic metric (d, w) on Σ :

d - complete finite area hyperbolic on Σ .

w : each cusp is assigned a horoball H_i ,
centered at the cusp.

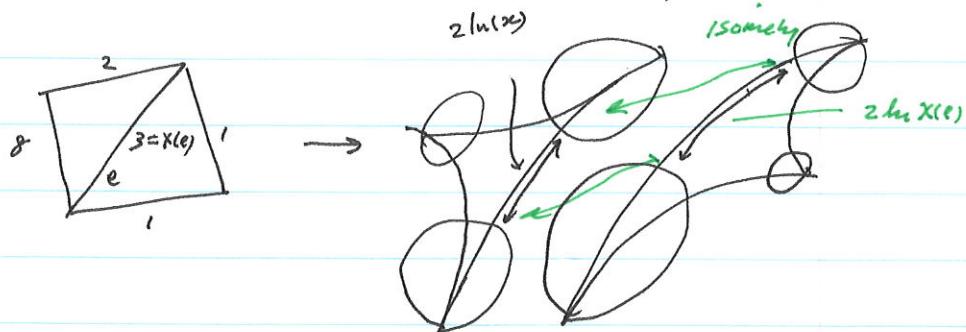


$w = (w_1, \dots, w_n) \in \mathbb{R}_{>0}^n$. w_i = length of ∂H_i

$T_D = \{[(d, w)] \mid (d, w) \text{ decorated metric on } \Sigma\} / \begin{matrix} \text{Isometry} \cong \text{id} \\ \text{preserving horoballs} \end{matrix}$

$$= T(\Sigma) \times \mathbb{R}_{>0}^n$$

Now fix a \mathcal{T} of Σ . For any $x \in \mathbb{R}_{>0}^{E(\mathcal{T})}$ one constructs
a decorated metric $\varphi(x) \in T_D$ as follows:



Make each $\Delta \in \mathcal{T}^{(2)}$ a decorated ideal tetra of λ -length $x(e)$.

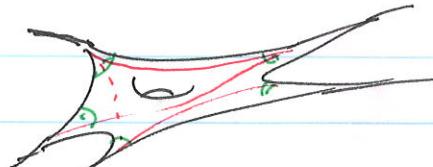
Now glue these (them) isometrically along edges ignoring decorations

\Rightarrow complete hyperbolic metric of finite area (d, w)

The horoballs \rightarrow gluing of the portion of the horoballs.

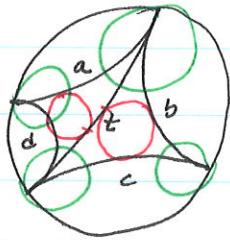
Thm (Penner) $\Phi_{\mathcal{T}}: \mathbb{R}^E \longrightarrow T_D(\Sigma): x \mapsto \varphi(x)$ is
a homeomorphism.

Proof Onto: pull \mathcal{T} tight. 1-1 definition.



Relationship between shear and λ -coordinate.

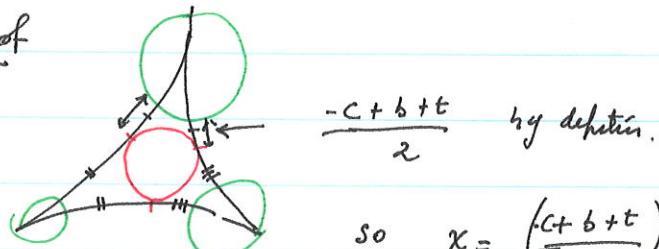
Lemma: Consider $a, b, c, d, t \in \mathbb{R}$ the length coord.



then the shear coordinate x at e

$$x = \frac{(a+c+b+d)}{2} - \frac{(b+d-a-c)}{2}$$

Proof



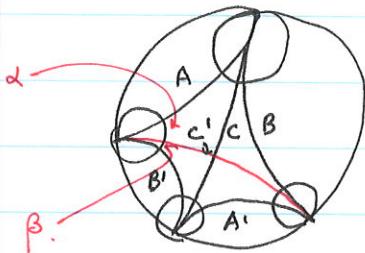
From Ptolemy
→ shear

$$\text{so } x = \left(\frac{c+b+t}{2} \right) - \left(\frac{-d+a+c}{2} \right) = \frac{1}{2}(b+d-a-c)$$

□

Corollary. (Penner's Ptolemy). Let A, A', B, B', C, C' be the λ -lengths of decorated ideal quad. Then

$$CC' = AA' + BB'$$



Proof Let α, β be the angles as shown

By the cosine law:

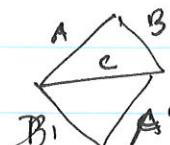
$$\alpha = \frac{B}{AC}, \quad \beta = \frac{A'}{B'C'}$$

$$\text{But } \alpha + \beta = \frac{C}{AB} \Rightarrow$$

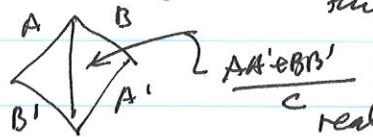
$$\frac{B}{AC} + \frac{A'}{B'C'} = \frac{C}{AB} \Leftrightarrow AA' + BB' = CC'$$

$\hat{\Phi}_g \circ \hat{\Phi}_{g'}^{-1} \square$

\Rightarrow the change of conductive formula $\hat{\Phi}_g \circ \hat{\Phi}_{g'}^{-1}$: even better than λ -lengths



\rightarrow



$\frac{AA' + BB'}{CC'} \text{ real analytic}$

Using a convex variational principle R-Guo + myself proved

the following thus which generalizes Penner's previous work

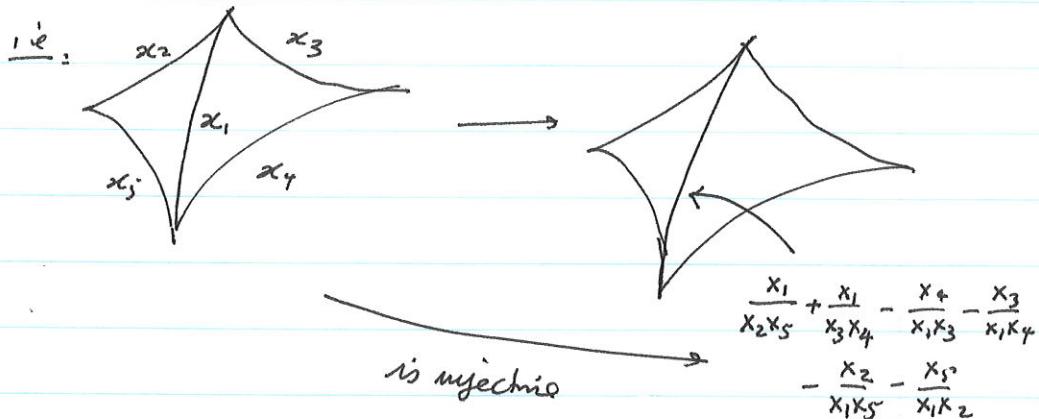
(Guo-L)

Thm For each $x \in \mathbb{R}^{E(\mathcal{T})}$, let $\psi_0(x) \in \mathbb{R}^E$ be:



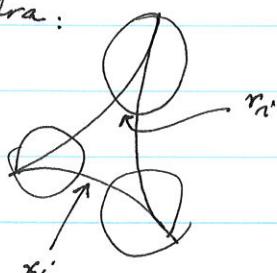
$$\psi_0(x)(e) = a + a' - b - b' - c - c' \\ (\text{curvature})$$

Then the map: $x \mapsto \psi_0(x)$ is a smooth embedding.



May skip to the last page

Proof We study the function from $x_i \rightarrow r_i$ of decorated ideal tetrahedra:



Known,

$$r_i = e^{\frac{1}{2}(x_i - x_j - x_k)}$$

Let $t_i = \frac{1}{2}x_i$ for simplicity

$$\text{so } r_i = e^{t_i - t_j - t_k}$$

$$\text{let } y_i = r_j + r_k - r_i = e^{t_j - t_k - t_i} + e^{t_k - t_i - t_j} - e^{t_i - t_j - t_k}$$

$$\text{Lemma (1)} \quad \frac{\partial y_i}{\partial t_j} = -e^{t_j - t_k - t_i} - e^{t_k - t_i - t_j} - e^{t_i - t_j - t_k}$$

$$= (-1) e^{-t_i - t_j - t_k} \left[e^{2t_j} + e^{2t_i} + e^{2t_k} \right]$$

$$(2) \quad \frac{\partial y_i}{\partial t_j} = e^{t_j - t_i - t_k} - e^{t_k - t_i - t_j} + e^{t_i - t_j - t_k}$$

$$= \left[e^{-t_i - t_j - t_k} \right] \left[e^{2t_i} + e^{2t_j} - e^{2t_k} \right]$$

As a consequence, $\frac{\partial y_i}{\partial t_j} = \frac{\partial y_j}{\partial t_i}$. Furthermore the

matrix $\begin{bmatrix} \frac{\partial y_i}{\partial t_j} \end{bmatrix}_{3 \times 3} = (-1) e^{-t_i - t_j - t_k} \begin{bmatrix} s_1 + s_2 + s_3 & s_1 + s_2 - s_3 & s_1 + s_3 - s_2 \\ s_1 + s_2 - s_3 & s_1 + s_2 + s_3 & s_2 + s_3 - s_1 \\ s_1 + s_3 - s_2 & s_2 + s_3 - s_1 & s_1 + s_2 + s_3 \end{bmatrix}$

is strictly negative definite.

Pf (1) (2) follows. Note: $s_1, s_2, s_3 > 0$

We claim that Note diagonally dominated matrix. But

$$s_1 + s_2 + s_3 > |s_1 + s_2 - s_3| + |s_1 + s_3 - s_2| \quad \text{etc}$$

It is still positive definite

Say $s_1 \geq s_2 \geq s_3$, then the want case is

if $s_1 + s_2 + s_3 \geq (s_1 + s_2 - s_3) + |s_1 + s_3 - s_2|$ (Not true)

$= \{ s_1 + s_2 - s_3 + s_2 + s_3 - s_1 = 2s_2 \}$

$s_2 + s_3 \geq s_1$

Let us assume $s_1 \geq s_2 \geq s_3$ so the want case

$$s_1 + s_2 + s_3 \geq |s_2 + s_3 - s_1| + |s_1 + s_3 - s_2| ?$$

$\det_{ij} > 0$
2x2 principle > 0

Also if $\det_{ij} \geq 0$

$$\begin{bmatrix} s_1, s_2, s_3 \geq 0 & \Rightarrow ? \\ s_1 + s_2 + s_3 \end{bmatrix}$$

Why is the determinant positive?

$$\text{the determinant } A = s_1 + s_2 + s_3 \Rightarrow$$

$$\begin{bmatrix} A & A - 2s_3 & A - 2s_2 \\ A - 2s_3 & A & A - 2s_1 \\ A - 2s_2 & A - 2s_1 & A \end{bmatrix}$$

First \Leftrightarrow the determinant $\neq 0$ since $\left[\frac{\partial y_i}{\partial t_j} \right]$ is unimodular

We can solve t_j 's from y_1, y_2, y_3 .

Next, For the set of all possible t 's is connected space.

Thus, ~~also~~ the det $\left[\frac{\partial y_i}{\partial t_j} \right]$ does not change signs

Now for the very specific one: $s_1 = s_2 = s_3 = 1$ It is alt ≥ 0

□

Corollary: \exists a strictly convex function $F(x) \triangleq x \in \mathbb{R}^E$

$$\nabla F = \psi(x)$$

\Rightarrow the result.

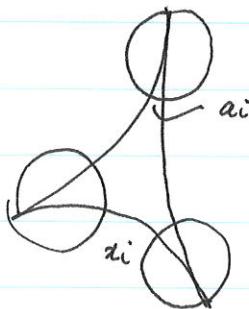
(Guo-L)

A Variational principle consider decorated ideal triangle of lengths

$x_1, x_2, x_3 \in \mathbb{R}$ and angles a_1, a_2, a_3

$$\text{Let } y_i = -(a_j + a_k) + a_c \quad \{c_i\}_{i=1}^3$$

$$= y_i(x)$$



Then $A = \left[\frac{\partial y_i}{\partial x_j} \right]_{3 \times 3}$ is symmetric and positive definite

$$\text{HW direct check: } q_i = e^{\frac{i}{2}(x_c - x_j - \lambda u)}.$$

Corollary. \exists a strictly convex function $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ s.t.

$$\nabla f(x) = (y_1, y_2, y_3)$$

$$f(x) = \int_0^x \left(\sum_{i=1}^3 y_i dx_i \right)$$

$$\text{A symmetric } \Leftrightarrow d(\sum y_i dx_i) = 0$$

A negative def. \Leftrightarrow Hessian of $f = A < 0$

$\Rightarrow f$ strictly concave.

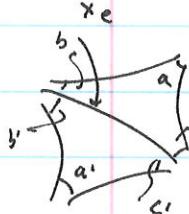
Now if $x \in \mathbb{R}^E$, define $w(x) : \mathbb{R}^E \rightarrow \mathbb{R}$ by

(strictly concave)

$$W(n) = \sum_{\substack{x_i \in \Delta^{x_n} \in F(\mathcal{T}) \\ x_j}} G(x_0, x_j, x_n)$$

$\forall c \in E$

$$\frac{\partial W(x)}{\partial x_e} = a + a' - b - b' - c - c' = \Phi_o(x_e) \text{ due to } \Phi_o - \text{available}$$



$$\nabla w = \bar{A}_0$$

But Lemma $S \subset \mathbb{R}^N$ open ~~closed~~ ^{Convex} $W: S \rightarrow \mathbb{R}$

$$\Rightarrow \exists w(x) : \mathbb{R}^{\mathbb{N}} \rightarrow \mathbb{R}^E \quad \sim \text{def}$$