# A boundary integral equation for the transmission eigenvalue problem for Maxwell equation 

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#### Abstract

We propose a new integral equation formulation to characterize and compute transmission eigenvalues in electromagnetic scattering. As opposed to the approach that was recently developed by Cakoni, Haddar and Meng (2015) which relies on a two-by-two system of boundary integral equations, our analysis is based on only one integral equation in terms of the electric-to-magnetic boundary trace operator that results in a simplification of the theory and in a considerable reduction of computational costs. We establish Fredholm properties of the integral operators and their analytic dependence on the wave number. Further, we use the numerical algorithm for analytic nonlinear eigenvalue problems that was recently proposed by Beyn (2012) for the numerical computation of the transmission eigenvalues via this new integral equation.


## KEYWORDS

boundary integral equations, inhomogeneous media, inverse scattering, transmission eigenvalues

## 1 | INTRODUCTION

The transmission eigenvalue problem for Maxwell's equation arises in scattering theory for time-harmonic electromagnetic waves in inhomogeneous media. If $n$ denotes the refractive index of an inhomogeneous medium with support $D \in \mathbb{R}^{3}$ in electromagnetic scattering, the transmission eigenvalue problem is formulated as finding $k \in \mathbb{C}$ for which the homogeneous problem

$$
\begin{equation*}
\operatorname{curl} \operatorname{curl} E-k^{2} n E=0 \quad \text { in } D, \tag{1}
\end{equation*}
$$

Dedicated to Erich Martensen on the occasion of his 90th birthday

$$
\begin{gather*}
\text { curl curl } E_{0}-k^{2} E_{0}=0 \quad \text { in } D,  \tag{2}\\
v \times E=v \times E_{0} \quad \text { on } \partial D,  \tag{3}\\
v \times \operatorname{curl} E=v \times \operatorname{curl} E_{0} \quad \text { on } \partial D \tag{4}
\end{gather*}
$$

has nontrivial solutions $E, E_{0} \in L^{2}(D)$. Here, we assume that $D$ is bounded and has a connected complement $\mathbb{R}^{3} \backslash D$ with sufficiently smooth boundary $\partial D$ and $v$ denotes the outward unit normal vector.

Transmission eigenvalues can be seen as the extension of the concept of resonant frequencies for impenetrable objects to the case of penetrable media. They are related to nonscattering frequencies. If $E=E^{i}+E^{s}$ is the total field for scattering of an incident field $E^{i}$ such that $E^{s}=0$ everywhere, then $E$ and $E_{0}=E^{i}$ solve (1)-(4). Conversely, if (1)-(4) has a nontrivial solution $E, E_{0}$, and $E_{0}$ can be extended outside $D$ as a solution to curlcurl $E_{0}-k^{2} E_{0}=0$, and this extension $E_{0}$ is considered as the incident field, then the corresponding scattered field is $E^{S}=0$.

The transmission eigenvalue problem is a nonlinear and non-self-adjoint eigenvalue problem that is not covered by the standard theory of eigenvalue problems for elliptic equations, and as such in recent years, its analysis has been an attractive subject of investigation. For existence of transmission eigenvalues for the Maxwell equations, we refer to Cakoni et $\mathrm{al}^{1,2}$ and to numerical computations via finite element methods to Monk and Sun. ${ }^{3}$
In this paper, we extend the boundary integral equation approach that we developed in Cakoni and Kress ${ }^{4}$ for the transmission eigenvalue problem for the Helmholtz equation in the case of a constant refractive index. Boundary integral equation methods were first used in the context of transmission eigenvalues for the Helmholtz problem by Cossonnière and Haddar. ${ }^{5,6}$ In their work, they used Green's representation formula to derive a system of two linear boundary integral equations that are equivalent to the transmission eigenvalue problem and depend nonlinearly on the eigenvalue parameter $k$. Using parts of the analysis in Cossonnière and Haddar, ${ }^{5,6}$ we were able to develop a new formulation that leads to only one linear boundary integral equation in terms of a Dirichlet-to-Neumann operator and used it also for numerical computations of transmission eigenvalues (see Cakoni and Kress ${ }^{4}$ ). The analysis in Cossonnière and Haddar ${ }^{5,6}$ was extended by Cakoni et $\mathrm{al}^{7}$ to the transmission eigenvalue problem for the Maxwell equations leading again to a system of two linear integral equations. It is the purpose of this paper to extend our approach from Cakoni and Kress ${ }^{4}$ to again obtain a formulation with only one integral equation.

Assuming that $n>0$ with $n \neq 1$ is constant, the main idea is to derive an integral equation from a characterization of the transmission eigenvalues in terms of the electric-to-magnetic boundary trace operator $\mathcal{A}_{k, n}$. For any field $E$ defined in $D$, throughout the paper, we denote by

$$
\gamma E:=v \times(E \times v)
$$

the tangential trace of $E$ on $\partial D$. Then, $\mathcal{A}_{k, n}$ is defined by

$$
\begin{equation*}
\mathcal{A}_{k, n}: c \mapsto \gamma \text { curl } E \tag{5}
\end{equation*}
$$

where $E$ is the unique solution to

$$
\begin{align*}
& \text { curl curl } E-k^{2} n E=0 \quad \text { in } D,  \tag{6}\\
& \qquad \vee E=c \quad \text { on } \partial D, \tag{7}
\end{align*}
$$

assuming that $k^{2}$ is not an eigenvalue for this problem. We further assume that $k^{2}$ is also not an eigenvalue for the case when $n=1$ and, for ease of notation, set $k_{n}:=k \sqrt{n}$ and write $\mathcal{A}_{k}=\mathcal{A}_{k, 1}$ and $\mathcal{A}_{k_{n}}=\mathcal{A}_{k, n}$. Then, $k$ is a transmission eigenvalue if and only if the kernel of the operator

$$
\begin{equation*}
A(k):=\mathcal{A}_{k}-\mathcal{A}_{k_{n}} \tag{8}
\end{equation*}
$$

is nontrivial. To get rid of the restriction on $k^{2}$ not to be an eigenvalue for (6)-(7), we will find it necessary to modify the boundary condition (7) into a nonlocal impedance condition to be specified later on. Before we do that, we need to discuss the appropriate trace spaces for solutions of the transmission eigenvalue problem and provide further preparations.

## 2 | OPERATORS AND TRACE SPACES

To represent the electric-to-magnetic boundary trace operator in terms of integral operators, we need to introduce the single-layer potential $S_{k}$ defined by

$$
\begin{equation*}
\left(S_{k} \psi\right)(x):=2 \int_{\partial D} \psi(y) \Phi_{k}(x, y) d s(y), \quad x \in \mathbb{R}^{3} \backslash \partial D \tag{9}
\end{equation*}
$$

in terms of the fundamental solution

$$
\begin{equation*}
\Phi_{k}(x, y)=\frac{1}{4 \pi} \frac{e^{i k|x-y|}}{|x-y|}, \quad x \neq y . \tag{10}
\end{equation*}
$$

The factor 2 in the definition of $S_{k}$ later on avoids the occurrence of a factor $1 / 2$ in our representations of the operator $A(k)$. It is known (see, eg, McLean ${ }^{8, \text { Theorem }}{ }^{7.2}$ ) that if $\partial D$ is $C^{2,1}$-smooth, the linear operator $S_{k}: H^{s-\frac{1}{2}}(\partial D) \rightarrow H^{s+1}(D)$ is bounded for $-1 \leq s \leq 2$. We define the restriction of $S_{k}$ and of its normal derivative to the boundary $\partial D$ by

$$
\begin{gather*}
\left(S_{k} \psi\right)(x):=2 \int_{\partial D} \psi(y) \Phi(x, y) d s(y), \quad x \in \partial D,  \tag{11}\\
\left(K_{k}^{\prime} \psi\right)(x):=2 \int_{\partial D} \psi(y) \frac{\partial}{\partial v_{x}} \Phi(x, y) d s(y), \quad x \in \partial D . \tag{12}
\end{gather*}
$$

Then, by the trace theorem,

$$
\begin{align*}
& S_{k}: H^{s-\frac{1}{2}}(\partial D) \rightarrow H^{s+\frac{1}{2}}(\partial D),  \tag{13}\\
& K_{k}^{\prime}: H^{s-\frac{1}{2}}(\partial D) \rightarrow H^{s-\frac{1}{2}}(\partial D) \tag{14}
\end{align*}
$$

are bounded for $-1 \leq s \leq 2$.
To discuss the two basic electromagnetic boundary integral operators, we define the space

$$
H_{\mathrm{t}}^{s}(\partial D):=\left\{a \in H^{s}(\partial D): v \cdot a=0\right\}
$$

of tangential fields, and as in Colton and Kress, ${ }^{9, \text {, Chapter } 6}$ we introduce the operators

$$
\begin{equation*}
\left(M_{k} a\right)(x):=2 \int_{D} v(x) \times \operatorname{curl}_{x}\left\{\Phi_{k}(x, y) a(y)\right\} d s(y), \quad x \in \partial D \tag{15}
\end{equation*}
$$

and

$$
\begin{equation*}
\left(N_{k} a\right)(x):=2 \gamma \operatorname{curl} \operatorname{curl} \int_{D} \Phi_{k}(x, y) a(y) d s(y), \quad x \in \partial D . \tag{16}
\end{equation*}
$$

The definition of $N_{k}$ differs slightly from the one in Colton and Kress. ${ }^{9}$ The operator $M_{k}$ is a pseudo-differential operator of order -1 , it maps $H_{\mathrm{t}}^{s-\frac{1}{2}}(\partial D)$ compactly into itself, and $N_{k}$ is a pseudo-differential operator of order 1, it maps $H_{\mathrm{t}}^{s-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{s-\frac{3}{2}}(\partial D)$ for $0 \leq s \leq 2$ (see Colton and Kress ${ }^{9}$ ).
The solutions to the transmission eigenvalue problem belong to $L_{\text {curl }}^{2}(D)$, where

$$
L_{\operatorname{curl}^{2}}^{2}(D):=\left\{E \in L^{2}(D): \text { curl curl } E \in L^{2}(D), \operatorname{div} E=0\right\}
$$

is equipped with the norm

$$
\|E\|_{L_{\text {curr }}^{2}(D)}^{2}=\|E\|_{L^{2}(D)}^{2}+\| \text { curl curl } E \|_{L^{2}(D)}^{2} .
$$

Therefore, we need to discuss both their traces

$$
\gamma E \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \quad \text { and } \quad \gamma \operatorname{curl} E \in H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D) .
$$

For $E \in L_{\text {curl }}^{2}(D)$, in view of the second vector Green integral theorem (see Colton and Kress ${ }^{9}$, p. 190 ), its trace $\gamma E \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is defined by duality

$$
\langle\gamma E, f\rangle_{H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D), H_{\mathrm{t}}^{\frac{1}{2}}(\partial D)}=\int_{D}(E \cdot \operatorname{curl} \operatorname{curl} F-F \cdot \operatorname{curl} \operatorname{curl} E) d x,
$$

where $F \in H^{2}(D)$ is such that div $F=0$ in $D$ and $\nu \times \gamma F=0$ and $\gamma \operatorname{curl} F=-f$ on $\partial D$. Similarly, the trace $\gamma \operatorname{curl} E \in H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$ is defined

$$
\langle\gamma \operatorname{curl} E, f\rangle_{H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D), H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)}=\int_{D}(E \cdot \operatorname{curl} \operatorname{curl} F-F \cdot \operatorname{curl} \operatorname{curl} E) d x
$$

where $F \in H^{2}(D)$ is chosen such that $\operatorname{div} F=0$ in $D$ and $\nu \times \gamma F=f$ and $\gamma \operatorname{curl} F=0$ on $\partial D$.
For these definitions of the traces, we require a lifting result due to Haddar, ${ }^{10}$ which ensures that for given fields $a \in$ $H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$ and $b \in H_{\mathrm{t}}^{\frac{1}{2}}(\partial D)$, there exist $F \in H^{2}(D)$ such that $\operatorname{div} F=0$ in $D$ and $\nu \times \gamma F=a$ and $\gamma$ curl $F=b$ on $\partial D$. In Haddar, ${ }^{10}$ the existence of $G \in H^{2}(D)$ satisfying $v \times \gamma G=a$ and $\gamma$ curl $G=b$ on $\partial D$ is established. By the Helmholtz decomposition, we have $G=\operatorname{curl} A+\operatorname{grad} u$ with $A, u \in H^{3}(D)$. Then, with the unique harmonic function $v \in H^{3}(D)$ satisfying $v=u$ on $\partial D$, the field $F=\operatorname{curl} A+\operatorname{grad} v$ has the required properties.

Obviously, $S_{k} a$ satisfies the vector Helmholtz equation in $D$, and the operator curl $S_{k}: H^{-\frac{1}{2}}(\partial D) \rightarrow L_{\text {curl }}^{2}(D)$ is bounded.
By a duality argument, it is possible to extend the vector jump relations on $\partial D$ to the case of densities $a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$.
Lemma 2.1. The field $E=$ curl $S_{k} a$ with density $a \in H_{t^{-\frac{1}{2}}}(\partial D)$ has boundary traces

$$
\begin{equation*}
v \times \gamma E_{ \pm}=M_{k} a \mp a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \tag{17}
\end{equation*}
$$

and

$$
\begin{equation*}
\gamma \operatorname{curl} E=N_{k} a \in H^{-\frac{3}{2}}(\partial D) \tag{18}
\end{equation*}
$$

## 3 | VECTOR POTENTIAL THEORY REVISITED

Before we proceed with the closer investigation of the transmission eigenvalue problem, we provide a regularity property from vector potential theory that we will be use in our further analysis. This section follows Martensen ${ }^{11, ~ p . ~} 252$ and puts some classical facts on harmonic vector fields into a contemporary Sobolev space framework. R.K. was particularly pleased to work this out since he became familiar with the topic during his early times in mathematics almost 50 years ago as a PhD student and postdoctoral researcher with Erich Martensen in Darmstadt.

For $m=0,1, \ldots$, we introduce the spaces of divergence free vector fields

$$
H^{m, 0}(D):=\left\{F \in H^{m}(D): \operatorname{div} F=0\right\}
$$

Then, for $m=0,1$, given $F \in H^{m, 0}(D)$, we define a harmonic function $u \in H^{m+1}(D)$ as the single-layer potential

$$
\begin{equation*}
u(x):=\int_{\partial D} \Phi_{0}(x, y) v(y) \cdot F(y) d s(y), \quad x \in D \tag{19}
\end{equation*}
$$

and a harmonic function $v \in H_{\mathrm{loc}}^{m+1}\left(\mathbb{R}^{3} \backslash \bar{D}\right)$ as the unique solution to the exterior Neumann problem

$$
\begin{equation*}
\frac{\partial v}{\partial v}=\frac{\partial u}{\partial v} \quad \text { on } \partial D \tag{20}
\end{equation*}
$$

vanishing at infinity. Then, we consider the field

$$
\begin{equation*}
A(x):=\int_{D} \Phi_{0}(x, y) F(y) d y+\int_{\partial D} \Phi_{0}(x, y)[u(y)-v(y)] v(y) d s(y) \tag{21}
\end{equation*}
$$

for $x \in D$ and the operator $V: F \mapsto A$.

Lemma 3.1. The operator $V$ is bounded from $H^{m, 0}(D)$ into $H^{m+2,0}(D)$.

Proof. The mapping of $F$ into the volume potential in (21) is bounded from $H^{m}(D)$ into $H^{m+2}(D)$. By the trace theorem, the mapping of $F$ into the potential $u$ is bounded from $H^{m}(D)$ into $H^{m+1}(D)$, and the mapping of $u$ into the boundary trace of $v$ is bounded from $H^{m+1}(D)$ into $H^{m+\frac{1}{2}}(\partial D)$. Finally, the mapping from $\left(\left.u\right|_{\partial D}-\left.v\right|_{\partial D}\right)$ to the single-layer potential in (21) is bounded from $H^{m+\frac{1}{2}}(\partial D)$ into $H^{m+2}$. Hence, the boundedness of $V$ from $H^{m}(D)$ into $H^{m+2}(D)$ follows.

It remains to show that $\operatorname{div} A=0$ in $D$. Taking the divergence in (21), interchanging differentiation and integration and using $\operatorname{div} F=0$ yields

$$
\operatorname{div} A(x)=-\int_{D} \operatorname{div}_{y}\left[\Phi_{0}(x, y) F(y)\right] d y-\int_{\partial D}[u(y)-v(y)] \frac{\partial \Phi_{0}(x, y)}{\partial v(y)} d s(y)
$$

for $x \in D$. By the Gauss divergence theorem and (19), it follows

$$
\operatorname{div} A(x)=-u(x)-\int_{\partial D}[u(y)-v(y)] \frac{\partial \Phi_{0}(x, y)}{\partial v(y)} d s(y), \quad x \in D
$$

Finally, the boundary condition (20) and Green's integral formula for harmonic functions imply div $A=0$ in $D$.
Assume now that we are given fields $F \in H^{m, 0}(D)$ and $g \in H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$. Then, the field $H_{0}=\operatorname{curl} V(F) \in H^{m+1,0}(D)$ satisfies

$$
\operatorname{curl} H_{0}=F, \quad \operatorname{div} H_{0}=0 \quad \text { in } D
$$

because of curl $H_{0}=$ curl curl $A=-\Delta A+\operatorname{grad} \operatorname{div} A=F$. Now, we consider the Neumann problem for a harmonic function $w \in H^{m+2}(D)$ with boundary condition

$$
\begin{equation*}
\frac{\partial w}{\partial \nu}=v \cdot H_{0}+\operatorname{Div} g \quad \text { on } \partial D \tag{22}
\end{equation*}
$$

and normalization $\int_{\partial D} w d s=0$. Note that the right hand side in (22) belongs to $H^{m+\frac{1}{2}}(\partial D)$, and in view of the Gauss divergence theorem, it satisfies the solvability condition

$$
\int_{\partial D}\left[v \cdot H_{0}+\operatorname{Div} g\right] d s=0
$$

Then,

$$
H:=H_{0}-\operatorname{grad} w
$$

satisfies

$$
\operatorname{curl} H=F, \quad \operatorname{div} H=0 \quad \text { in } D
$$

and the boundary condition

$$
\begin{equation*}
\nu \cdot H=-\operatorname{Div} g \quad \text { on } \partial D \tag{23}
\end{equation*}
$$

The mapping $\left(H_{0}, g\right) \mapsto w$ is bounded from $H^{m+1}(D) \times H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$ into $H^{m+2}(D)$. Therefore, in turn, the mapping $(F, g) \mapsto H$ is bounded from $H^{m}(D) \times H_{t}^{m+\frac{3}{2}}(\partial D)$ into $H^{m+1}(D)$.

The field $E_{0}=$ curl $V(H) \in H^{m+2,0}(D)$ in turn now satisfies

$$
\operatorname{curl} E_{0}=H, \quad \operatorname{div} E_{0}=0 \quad \text { in } D .
$$

The mapping $H \rightarrow E_{0}$ is bounded from $H^{m+1,0}(D)$ into $H^{m+2,0}(D)$. We consider the Dirichlet boundary value problem for a harmonic field $E_{1}$, that is, curl $E_{1}=0$ and $\operatorname{div} E_{1}=0$ in $D$ with tangential component

$$
v \times E_{1}=v \times E_{0}-g \quad \text { on } \partial D
$$

From (23) and curl $E_{0}=0$, we observe that

$$
\begin{equation*}
\operatorname{Div}\left[\nu \times E_{0}-g\right]=0 \tag{24}
\end{equation*}
$$

We seek the solution in the form

$$
E_{1}(x)=\operatorname{curl} \int_{\partial D} \Phi_{0}(x, y) a(y) d s(y), \quad x \in D
$$

with density $a \in H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$. The boundary condition is satisfied provided $a$ solves the integral equation

$$
\begin{equation*}
M_{0} a-a=2 \nu \times E_{0}-2 g \tag{25}
\end{equation*}
$$

For a simply connected domain $D$, the operator $M_{0}-I$ is injective in the Hölder space $C_{\mathrm{t}}^{0, \alpha}(\partial D)$ (see Colton and Kress ${ }^{12, \text { Theorem 5.4 }}$ ). Using the Fredholm alternative in dual systems, it can be seen that $M_{0}-I$ is also injective in $H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$ (see Kress ${ }^{13, \text {, Theorem }}{ }^{4.20}$ ). By the Riesz theory, injectivity of $M_{0}-I$ now implies bijectivity with a bounded inverse $\left(M_{0}-I\right)^{-1}$. We refrain from presenting the technical details required to show solvability of (25) by using the quotient space with respect to the kernel of $M-I$ in the case of multiply connected domains $D$.

Taking the surface divergence of (25) leads to the homogeneous equation (see Colton and Kress ${ }^{9}$, Theorem 6.17)

$$
K_{0}^{\prime} \operatorname{Div} a+\operatorname{Div} a=0
$$

From this, it follows that the single-layer potential with density Diva is constant in $D$ (see Kress ${ }^{13,}$ Theorem 6.21 ). Therefore, we have

$$
\operatorname{curl} E_{1}(x)=\operatorname{grad} \operatorname{div} \int_{\partial D} \Phi_{0}(x, \cdot) a d s=\operatorname{grad} \int_{\partial D} \Phi_{0}(x, \cdot) \operatorname{Div} a d s=0
$$

for $x \in D$. Because of the boundedness of $\left(M_{0}-I\right)^{-1}$ on $H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$, the mapping taking $\left(E_{0}, g\right)$ into $E_{1}$ is bounded from $H^{m+2,0}(D) \times H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$ into $H^{m+2,0}(D)$.

Then,

$$
\begin{equation*}
E:=E_{0}-E_{1} \in H^{m+2,0}(D) \tag{26}
\end{equation*}
$$

satisfies

$$
\begin{equation*}
\text { curl curl } E=F, \quad \operatorname{div} E=0 \quad \text { in } D \tag{27}
\end{equation*}
$$

and the boundary condition

$$
\begin{equation*}
\nu \times E=g \quad \text { on } \partial D \tag{28}
\end{equation*}
$$

The total mapping $(F, g) \mapsto E$ from $H^{m, 0}(D) \times H_{\mathrm{t}}^{m+\frac{3}{2}}(\partial D)$ into $H^{m+2,0}(D)$ is bounded. Using the vector Green integral theorem, it can be shown that the solution $E \in H^{m+2,0}(D)$ to (27)-(28) is unique.

We can summarize this into the following theorem (compare Theorem 1.3 in Taylor ${ }^{14, ~ p . ~ 305}$ ).
Theorem 3.2. The unique solution $E \in H^{m, 0}(D)$ of curl curl $E=F$ satisfying $v \times E=g$ on $\partial D$ with $F \in H^{m, 0}(D)$ and $g \in H_{t}^{m+\frac{3}{2}}(\partial D)$ belongs to $H^{m+2,0}(D)$, and the linear mapping taking $(F, g)$ into $E$ is bounded from $H^{m, 0}(D) \times H_{t}^{m+\frac{3}{2}}(\partial D)$ into $H^{m+2,0}(D)$ for $m=0,1$.
We require a further regularity result that we base on the vector Green formula for divergence free vector fields

$$
\begin{align*}
E(x)= & \int_{D} \Phi_{0}(x, \cdot) \operatorname{curl} \operatorname{curl} E d y+\operatorname{grad} \int_{\partial D} \Phi_{0}(x, \cdot) v \cdot E d s-\operatorname{curl} \int_{\partial D} \Phi_{0}(x, \cdot) v \times E d s  \tag{29}\\
& -\int_{\partial D} \Phi_{0}(x, \cdot) v \times \operatorname{curl} E d s
\end{align*}
$$

for $x \in D$. This representation formula can be viewed as a limit of the Stratton-Chu formula for Maxwell's equations and a proof for smooth functions can be found, for example, in Kress. ${ }^{15}$ It can be seen to be valid for $E \in L_{\text {curl }}^{2}(D)$ with the boundary values interpreted in the sense of the traces $\gamma E \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ and $\gamma \operatorname{curl} E \in H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$ as introduced in the previous section. Since for divergence free $E \in L_{\text {curl }^{2}}^{2}(D)$, we have $\Delta E \in L^{2}(D)$, the trace $v \cdot E \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ also is well defined (see Cakoni and Kress ${ }^{4}$ ). We will use (29) to establish the following regularity properties.
Theorem 3.3. For each $E \in L_{\text {curl }^{2}}^{2}(D)$, we can estimate

$$
\begin{equation*}
\|\gamma \operatorname{curl} E\|_{H^{-\frac{3}{2}}(\partial D)} \leq C\left[\|\nu \times \gamma E\|_{H^{-\frac{1}{2}}(\partial D)}+\|\operatorname{curl} \operatorname{curl} E\|_{L^{2}(D)}\right] \tag{30}
\end{equation*}
$$

for some $C>0$ depending only on $D$.

Proof. We introduce the volume potential

$$
W(x):=2 \int_{D} \Phi_{0}(x, \cdot) \operatorname{curl} \operatorname{curl} E d y, \quad x \in D,
$$

and, with the aid of Lemma 2.1, take the trace of the curl in (29) to obtain the integral equation

$$
\begin{equation*}
a+M_{0} a=\gamma \operatorname{curl} W-v \times N_{0}(\nu \times E) \tag{31}
\end{equation*}
$$

for $a:=v \times \gamma \operatorname{curl} E$. Analogous to $M_{0}-I$, for a simply connected domain $D$, the operator $M_{0}+I$ is injective in the Hölder space $C_{\mathrm{t}}^{0, \alpha}(\partial D)$. Arguing as in the proof of the previous theorem, we obtain solvability of (31) in $H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$ with a bounded inverse $\left(I+M_{0}\right)^{-1}$. Then, in view of the boundedness of the volume potential from $L^{2}(D)$ into $H^{2}(D)$ and the boundedness of $N_{0}$ from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$, estimating the right-hand side of (31), we complete the proof.

Lemma 3.4. Each $E \in L_{\text {curl }^{2}}^{2}(D)$ with trace $\gamma E \in H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$ on $\partial D$ is in $H^{2,0}(D)$.
Proof. For given $E \in L_{\text {curr }^{2}}^{2}(D)$, denote by $\tilde{E} \in H^{2,0}(D)$, the unique solution of curl $\operatorname{curl} \tilde{E}=\operatorname{curl} \operatorname{curl} E$ in $D$ with $\nu \times \gamma \tilde{E}=\nu \times E$ on $\partial D$ from Theorem 3.2 and consider the difference $E_{0}=E-\tilde{E}$. Then, by the definition of the trace $\gamma E_{0}$, we have that $\int_{D} E_{0} \cdot$ curl $\operatorname{curl} F d x=0$ for any $F \in H^{2,0}(D)$ with $\gamma F=0$ on $\partial D$. Inserting the unique solution $F \in H^{2,0}(D)$ of curl curl $F=\bar{E}_{0}$ with $\gamma F=0$ on $\partial D$ gives $E_{0}=0$, that is, $E=\tilde{E} \in H^{2,0}(D)$.

## 4 | A NONLOCAL IMPEDANCE CONDITION

Now, we are ready to consider the impedance problem

$$
\begin{equation*}
\operatorname{curl} \operatorname{curl} E-k^{2} n E=0 \quad \text { in } D \tag{32}
\end{equation*}
$$

with the nonlocal boundary condition

$$
\begin{equation*}
v \times E-i \eta \gamma S_{0}^{3} \gamma \operatorname{curl} E=c \quad \text { on } \partial D \tag{33}
\end{equation*}
$$

for $E \in L_{\text {curl }}^{2}(D)$ where $c \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is given. Here, $S_{0}$ is the single-layer operator for the Laplace case, and $\eta \geq 0$ is a parameter that we introduce to include the perfect conductor boundary condition as the special case $\eta=0$. The nonlocal boundary condition has no physical meaning but helps us to circumvent some regularity issues. For this reason, the analysis presented below remains valid after replacing the compact operator $S_{0}$ by any positive definite pseudo-differential operator of order -1 .

Theorem 4.1. The impedance boundary value problem (32)-(33) has a unique solution.
Proof. To show uniqueness, assume that $E$ solves the impedance problem for $c=0$. From the homogeneous boundary condition (33) and the fact that $\gamma S_{0}^{3}: H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$, we observe that

$$
\nu \times E=\operatorname{in} \gamma S_{0}^{3} \gamma \operatorname{curl} E \in H_{\mathrm{t}}^{\frac{3}{2}}(\partial D) .
$$

Therefore, by Theorem 3.2 with $m=0$ in combination with Lemma 3.4, we have $E \in H^{2}(D)$. Then from the first vector Green integral theorem (see Colton and Kress ${ }^{9, \text { p. }}{ }^{190}$ ), using the positive definiteness of $S_{0}$, we obtain that

$$
\int_{D}\left\{|\operatorname{curl} E|^{2}-k^{2}|E|^{2}\right\} d x=i \int_{\partial D} \gamma S_{0}^{\frac{3}{2}} \gamma \operatorname{curl} E \cdot \gamma S_{0}^{\frac{3}{2}} \gamma \operatorname{curl} \bar{E} d s
$$

whence $\gamma$ curl $E=0$ on $\partial D$ follows. Then, the boundary condition (33) implies $v \times E=0$ on $\partial D$ and from the Stratton-Chu formula (see Colton and Kress ${ }^{9}$ ), we deduce that $E=0$ in $D$.

We seek the solution in the form

$$
\begin{equation*}
E=\operatorname{curl} S_{k} a \tag{34}
\end{equation*}
$$

with density $a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$. Clearly, $E$ satisfies the differential equation (32) and belongs to $L_{\text {curl }}{ }^{2}(D)$. In view of (17) and (18), the boundary condition (33) is satisfied provided $a$ solves the integral equation

$$
\begin{equation*}
\left(-I+M_{k}-i \eta \gamma S_{0}^{3} N_{k}\right) a=2 c . \tag{35}
\end{equation*}
$$

Injectivity of

$$
Q_{k}:=-I+M_{k}-i \eta \gamma S_{0}^{3} N_{k}
$$

is a consequence of the uniqueness for the impedance problem, which implies that $E$ defined by (34) for a solution $a$ of $Q_{k} a=0$ vanishes $E=0$ in $D$. Then, (18) yields $\nu \times E_{+}=0$ on $\partial D$ and from this uniqueness for the perfect conductor exterior boundary value problem implies that $E=0$ in $\mathbb{R}^{3} \backslash D$. Finally, from this and (17), we obtain $a=0$. As noted above, $M_{k}: H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is compact and $N_{k}: H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$ is bounded. As consequence of the latter, $\gamma S_{0}^{3} N_{k}: H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$ is bounded and therefore $\gamma S_{0}^{3} N_{k}: H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is compact. By the Riesz theory, injectivity of $Q_{k}$ implies bijectivity and boundedness of $Q_{k}^{-1}$.

We will also need the impedance boundary value problem for purely imaginary $k=i$ and $\eta=i$. In this case, we have the boundary condition

$$
\begin{equation*}
\nu \times E+\gamma S_{0}^{3} \gamma \operatorname{curl} E=c \quad \text { on } \partial D \tag{36}
\end{equation*}
$$

and obtain uniqueness and existence along the same lines.
The solution to the nonlocal impedance problem defines an impedance-to-magnetic boundary trace operator by

$$
\begin{equation*}
\mathcal{B}_{k, n}: c \mapsto \gamma \operatorname{curl} E \tag{37}
\end{equation*}
$$

where $E$ is the unique solution to (32)-(33). We set $k_{n}:=k \sqrt{n}$ and write $\mathcal{B}_{k}=\mathcal{B}_{k, 1}$ and $\mathcal{B}_{k_{n}}=\mathcal{B}_{k, n}$. Obviously, $k$ is a transmission eigenvalue if and only if the kernel of the operator

$$
\begin{equation*}
B(k, \eta):=\mathcal{B}_{k}-\mathcal{B}_{k_{n}} \tag{38}
\end{equation*}
$$

is nontrivial. From the proof of Theorem 4.1, we observe that

$$
\mathcal{B}_{k}=N_{k} Q_{k}^{-1}
$$

and the difference of this operators corresponding to $k$ and $k_{n}$ is given by

$$
B(k, \eta)=N_{k} Q_{k}^{-1}-N_{k_{n}} Q_{k_{n}}^{-1}
$$

## 5 | THE TRANSMISSION EIGENVALUE PROBLEM

We now are ready for our investigation of the transmission eigenvalue problem.
Lemma 5.1. The linear operators

$$
\begin{equation*}
a \mapsto \operatorname{curl} S_{k} Q_{k}^{-1} a-\operatorname{curl} S_{k_{n}} Q_{k_{n}}^{-1} a \tag{39}
\end{equation*}
$$

from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H^{2}(D)$ and $B(k, \eta): H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{\frac{1}{2}}(\partial D)$ are bounded.

Proof. By definition, $B(k) a$ is the tangential trace on the boundary $\partial D$ of the curl of

$$
E:=\operatorname{curl} S_{k} Q_{k}^{-1} a-\operatorname{curl} S_{k_{n}} Q_{k_{n}}^{-1} a, \quad a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)
$$

By Lemma 2.1, we have $\gamma$ curl $E=N_{k} Q_{k}^{-1} a-N_{k_{n}} Q_{k_{n}}^{-1} a$ with the mapping $a \rightarrow \gamma \operatorname{curl} E$ bounded form $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{-\frac{3}{2}}(\partial D)$. From

$$
\begin{equation*}
\operatorname{curl} \operatorname{curl} E=k^{2} \operatorname{curl} S_{k} Q_{k}^{-1} a-k_{n}^{2} \operatorname{curl} S_{k_{n}} Q_{k_{n}}^{-1} a \tag{40}
\end{equation*}
$$

we observe that $E \in L_{\text {curl }}^{2}(D)$ and, clearly, $E$ satisfies the boundary condition

$$
\begin{equation*}
\nu \times E-i \eta \gamma S_{0}^{3} \gamma \operatorname{curl} E=0 \quad \text { on } \partial D \tag{41}
\end{equation*}
$$

whence $v \times \gamma E \in H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$ follows with the mapping $a \rightarrow \nu \times E$ bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$. Therefore, from Lemma 3.4 and Theorem 3.2 with $m=0$, the statement of the theorem follows.

Theorem 5.2. Let $\kappa>0$ and $\kappa_{n}:=\kappa \sqrt{n}$. Then,

$$
\left(\kappa_{n}^{2}-\kappa^{2}\right) B(i \kappa, i): H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{\frac{1}{2}}(\partial D)
$$

is coercive, ie,

$$
\left.\left(\kappa_{n}^{2}-\kappa^{2}\right)\langle B(i \kappa, i) a, a\rangle_{H_{\mathrm{t}}^{2}}^{\frac{1}{2}}(\partial D), H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)\right) \geq C\|a\|_{H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)}^{2}
$$

for all $a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ and some $C>0$.

Proof. For $E \in H^{2}(D)$ with $\operatorname{div} E=0$, we transform

$$
\bar{E} \cdot\left(\operatorname{curl} \operatorname{curl}+\kappa^{2}\right)\left(\operatorname{curl} \operatorname{curl}+\kappa_{n}^{2}\right) E-\operatorname{curl} \operatorname{curl} \bar{E} \cdot \operatorname{curl} \operatorname{curl} E-\left(\kappa^{2}+\kappa_{n}^{2}\right) \operatorname{curl} \bar{E} \cdot \operatorname{curl} E-\kappa^{2} \kappa_{n}^{2} \bar{E} \cdot E
$$ $=-\bar{E} \cdot \Delta \operatorname{curl} \operatorname{curl} E+\Delta \bar{E} \cdot \operatorname{curl} \operatorname{curl} E-\left(\kappa^{2}+\kappa_{n}^{2}\right) \operatorname{div}[\bar{E} \times \operatorname{curl} E]$.

From this, by the vector Green theorem (see Colton and Kress ${ }^{9, p}{ }^{190}$ ) and the Gauss divergence theorem, we obtain

$$
\begin{align*}
& \int_{D} \bar{E} \cdot\left(\operatorname{curl} \operatorname{curl}+\kappa^{2}\right)\left(\operatorname{curl} \operatorname{curl}+\kappa_{n}^{2}\right) E d x-\int_{D}\left[|\operatorname{curl} \operatorname{curl} E|^{2}+\left(\kappa^{2}+\kappa_{n}^{2}\right)|\operatorname{curl} E|^{2}+\kappa^{2} \kappa_{n}^{2}|E|^{2}\right] d x  \tag{42}\\
= & \int_{\partial D}\left\{\nu \times \operatorname{curl} \bar{E} \cdot \operatorname{curl} \operatorname{curl} E-v \times \bar{E} \cdot\left[\operatorname{curl} \Delta E+\left(\kappa^{2}+\kappa_{n}^{2}\right) \operatorname{curl} E\right]\right\} d s .
\end{align*}
$$

Now, for $a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$, we define

$$
E:=\operatorname{curl} S_{i \kappa} Q_{i \kappa}^{-1} a-\operatorname{curl} S_{i \kappa_{n}} Q_{i K_{n}}^{-1} a .
$$

By the preceding Lemma 5.1 we have that $E \in H^{2}(D)$. Then, we find

$$
\begin{equation*}
\left(\text { curl curl }+\kappa^{2}\right)\left(\operatorname{curl} \operatorname{curl}+\kappa_{n}^{2}\right) E=0 \tag{43}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{curl} \operatorname{curl} E=-\kappa^{2} \operatorname{curl}_{i \kappa} Q_{i \kappa}^{-1} a+\kappa_{n}^{2} \operatorname{curl}_{i \kappa_{n}} Q_{i \kappa_{n}}^{-1} a . \tag{44}
\end{equation*}
$$

Therefore, we have the boundary conditions

$$
\begin{equation*}
\nu \times E+\gamma S_{0}^{3} \gamma \operatorname{curl} E=0, \quad \gamma \operatorname{curl} E=B(i \kappa, i) a \quad \text { on } \partial D \tag{45}
\end{equation*}
$$

and

$$
\begin{equation*}
\nu \times \operatorname{curl} \operatorname{curl} E+\gamma S_{0}^{3} \gamma \operatorname{curl} \text { curl curl } E=-\left(\kappa^{2}-\kappa_{n}^{2}\right) a \quad \text { on } \partial D . \tag{46}
\end{equation*}
$$

We use them to obtain that

$$
\begin{aligned}
& \nu \times \operatorname{curl} \bar{E} \cdot \operatorname{curl} \operatorname{curl} E-\nu \times \bar{E} \cdot\left[\operatorname{curl} \Delta E+\left(\kappa^{2}+\kappa_{n}^{2}\right) \operatorname{curl} E\right. \\
& =\left(\kappa^{2}-\kappa_{n}^{2}\right) a \cdot \overline{B(i \kappa, i) a}+\gamma \operatorname{curl} \bar{E} \cdot \gamma S_{0}^{3} \gamma \operatorname{curl} \operatorname{curl} \operatorname{curl} E \\
& \quad-\gamma S_{0}^{3} \gamma \operatorname{curl} \bar{E} \cdot \gamma \operatorname{curl} \operatorname{curl} \operatorname{curl} E+\left(\kappa^{2}+\kappa_{n}^{2}\right) \gamma S_{0}^{3} \gamma \operatorname{curl} \bar{E} \cdot \gamma \operatorname{curl} E
\end{aligned}
$$

on $\partial D$. From this and (42) and (45), using the self adjointness of $S_{0}$, it follows that

$$
\begin{aligned}
& -\int_{D}\left[|\operatorname{curl} \operatorname{curl} E|^{2}+\left(\kappa^{2}+\kappa_{n}^{2}\right)|\operatorname{curl} E|^{2}+\kappa^{2} \kappa_{n}^{2}|E|^{2}\right] d x \\
= & \int_{\partial D}\left[\left(\kappa^{2}-\kappa_{n}^{2}\right) a \overline{B(i \kappa, i) a}+\left(\kappa^{2}+\kappa_{n}^{2}\right) \gamma S_{0}^{\frac{3}{2}} \gamma \operatorname{curl} \bar{E} \cdot \gamma S_{0}^{\frac{3}{2}} \gamma \operatorname{curl} E\right] d s,
\end{aligned}
$$

whence

$$
\begin{equation*}
\left(\kappa_{n}^{2}-\kappa^{2}\right) \int_{\partial D} a \overline{B(i \kappa, i) a} d s \geq \int_{D}\left[|\operatorname{curl} \operatorname{curl} E|^{2}+\kappa^{2} \kappa_{n}^{2}|E|^{2}\right] d x \tag{47}
\end{equation*}
$$

follows.
Straightforward computation show that

$$
\left[\text { curl curl] }{ }^{2} E=F(E)\right.
$$

where

$$
F(E):=\left(\kappa^{2}+\kappa_{n}^{2}\right) \operatorname{curl} \operatorname{curl} E-\kappa^{2} \kappa_{n}^{2} E .
$$

From this and (46), applying Theorem 3.3 to curl curl $E$ and using the trace theorem and the boundedness of $S_{0}$, we obtain

$$
\begin{equation*}
\|a\|_{H^{-\frac{1}{2}(\partial D)}} \leq c \int_{D}\left[|\operatorname{curl} \operatorname{curl} E|^{2}+\kappa^{2} \kappa_{n}^{2}|E|^{2}\right] d x . \tag{48}
\end{equation*}
$$

Combining (47) and (48) completes the proof.

Theorem 5.3. The operator

$$
B(k, \eta)+\frac{k^{2}-k_{n}^{2}}{|k|^{2}-\left|k_{n}\right|^{2}} B(i|k|, i): H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)
$$

is compact.

Proof. For $a \in H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$, we define

$$
E_{0}:=\operatorname{curl} S_{k} Q_{k}^{-1} a-\operatorname{curl} S_{k_{n}} Q_{k_{n}}^{-1} a
$$

and

$$
E_{i}:=\operatorname{curl} S_{i|k|} Q_{i|k|}^{-1} a-\operatorname{curl} S_{i\left|k_{n}\right|} Q_{i \mid k_{n}}^{-1} a
$$

and let

$$
E:=E_{0}+\frac{k^{2}-k_{n}^{2}}{|k|^{2}-\left|k_{n}\right|^{2}} E_{i} .
$$

Then, $E \in H^{2}(D)$ by Lemma 5.1 and $E$ satisfies the boundary conditions (see Equation 45)

$$
\begin{equation*}
v \times E+\gamma S_{0}^{3} \gamma \operatorname{curl} E=(i+1) \gamma S_{0}^{3} \gamma \operatorname{curl} E_{0} \tag{49}
\end{equation*}
$$

and

$$
\begin{equation*}
\nu \times \text { curl curl } E+\gamma S_{0}^{3} \gamma \text { curl curl curl } E=(i+1) \gamma S_{0}^{3} \gamma \text { curl curl curl } E_{0} \tag{50}
\end{equation*}
$$

on $\partial D$. Furthermore, it is straightforward to check that

$$
\begin{equation*}
\left[\text { curl curl] }{ }^{2} E=F\left(E_{0}, E_{i}\right),\right. \tag{51}
\end{equation*}
$$

where

$$
\begin{equation*}
F\left(E_{0}, E_{i}\right):=-k^{2} k_{n}^{2} E_{0}-\left(k^{2}+k_{n}^{2}\right) \operatorname{curl} \operatorname{curl} E_{0}-\frac{k^{2}-k_{n}^{2}}{|k|^{2}-\left|k_{n}\right|^{2}}\left[|k|^{2}\left|k_{n}\right|^{2} E_{i}-\left(|k|^{2}+\left|k_{n}\right|^{2}\right) \operatorname{curl} \operatorname{curl} E_{i}\right] \tag{52}
\end{equation*}
$$

belongs to $L^{2}(D)$ by Lemma 5.1 and the map $a \mapsto F$ is bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $L^{2}(D)$.
From (44), we see that the mappings taking $a$ into $\gamma S_{0}^{3} \gamma \operatorname{curl}^{3} E$ and into $\gamma S_{0}^{3} \gamma \operatorname{curl}^{3} E_{0}$ are bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$. Therefore, applying Theorem 3.2 with $m=0$, together with Lemma 3.4, for curl curl $E$, we obtain that curl curl $E \in H^{2}(D)$ with the mapping $a \mapsto \operatorname{curl} \operatorname{curl} E$ bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H^{2}(D)$. By Lemma 5.1, the mappings taking $a$ into $\gamma S_{0}^{3} \gamma$ curl $E$ and into $\gamma S_{0}^{3} \gamma$ curl $E_{0}$ are bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H_{\mathrm{t}}^{\frac{5}{2}}(\partial D)$. Therefore, applying Theorem 3.2 now for $E$ (with $m=1$ and curl curl $E \in H^{1}(D)$ ) then in turn shows that $E \in H^{3}(D)$ with the mapping $a \mapsto E$ being bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H^{3}(D)$. Therefore, the mapping $a \mapsto \gamma \operatorname{curl} E$ is bounded from $H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ into $H^{\frac{3}{2}}(\partial D)$. Now, noting that

$$
\gamma \operatorname{curl} E=B(k, \eta)+\frac{k^{2}-k_{n}^{2}}{|k|^{2}-\left|k_{n}\right|^{2}} B(i|k|, i),
$$

the statement of the theorem follows from the compact embedding of $H_{\mathrm{t}}^{\frac{3}{2}}(\partial D)$ into $H_{\mathrm{t}}^{\frac{1}{2}}(\partial D)$.
In summary, Theorems 5.2 and 5.3 imply the following result, from which in particular, we can reestablish the well known discreteness (see for example, Cakoni et al ${ }^{1}$ ) of the transmission eigenvalues for the special case of a constant refractive index. Analyticity in the theorem follows from the analyticity of the kernels of the integral operators with respect to the wave number $k$.
Theorem 5.4. $B(k ; \eta): H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \quad \rightarrow \quad H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is a Fredholm operator with index zero and analytic in $\{k \in \mathbb{C}: \operatorname{Re}(k)>0$ and $\operatorname{Im}(k) \geq 0\}$.
Let us denote by $\mathbb{E}$ the set of all positive $k$ such that $k^{2}$ or $k_{n}^{2}$ is a Maxwell eigenvalue for a perfect conductor $D$. Then, $A(k)$ is defined for $k \in \mathbb{C} \backslash \mathbb{E}$. Then, setting $\eta=0$, Theorem 5.4 contains the following result as a special case.

Corollary 5.5. $A(k): H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D) \rightarrow H_{\mathrm{t}}^{-\frac{1}{2}}(\partial D)$ is a Fredholm operator with index zero and analytic in $\mathbb{C} \backslash \mathbb{E}$.

## 6 | NUMERICAL EXAMPLES

In this final section, we will illustrate the use of our integral equation formulation for the numerical computation of electromagnetic interior transmission eigenvalues. Analytically derived transmission eigenvalues for a ball due to Monk and Sun ${ }^{3}$ and numerical results by Kleefeld ${ }^{16}$ based on a boundary element collocation method for a two-by-two boundary integral equation formulation are used as benchmarks.

In our case, the nonlinear operator $B(k, \eta)$ given by (38) is discretized using the spectrally accurate method that was proposed by Ganesh and Hawkins ${ }^{17}$ for solving the magnetic field integral equation and extended to the electric field integral equation by Le Louër. ${ }^{18}$ We then apply Beyn algorithm ${ }^{19}$ for the solution of nonlinear eigenvalue problems for large-sized matrices that are analytic with respect to the eigenvalue parameter.

The spectral method is based on a spherical parametrization of the simply connected boundary $\partial D$ so that the integral operators are transported onto the unit sphere $\mathbb{S}^{2}$ by means of the bicontinuous invertible Piola transform of the boundary

 parametrized versions of the integral operators $M_{k}$ and $N_{k}$ both defined on $H_{\mathrm{t}}^{-\frac{1}{2}}\left(\mathbb{S}^{2}\right)$ are then projected onto the space of dimension $m=2\left(n_{s p h}+1\right)^{2}-2$ spanned by the orthonormal tangential vector spherical harmonics

$$
\frac{1}{\sqrt{\ell(\ell+1)}} \nabla_{\mathbb{S}_{2}} Y_{\ell, j} \quad \text { and } \quad \frac{1}{\sqrt{\ell(\ell+1)}} \operatorname{curl}_{\mathbb{S}_{2}} Y_{\ell, j}, \quad 1 \leq \ell \leq n_{s p h}, \quad|j| \leq \ell
$$

of degree less than or equal to $n_{s p h}$ (see Colton and Kress ${ }^{9, \text { Equation }}{ }^{(6.60)}$ ). Here, in the numerical examples, we chose $n_{\text {sph }}=$ 20 , that is, $m=882$.

We recall that the single-layer operator $S_{0}$ used in the analysis of the two previous sections can be replaced by any positive definite compact operator of order -1 . As alternative, we chose the operator given by

$$
\Lambda=\operatorname{Curl}_{\mathbb{S}^{2}}\left(-\Delta_{\mathbb{S}^{2}}\right)^{-\frac{3}{2}} \operatorname{Curl}_{\mathbb{S}^{2}}-\nabla_{\mathbb{S}^{2}}\left(-\Delta_{\mathbb{S}^{2}}\right)^{-\frac{3}{2}} \operatorname{Div}_{\mathbb{S}^{2}}
$$

in terms of the surface curl and divergence. Its discretization is given by the diagonal matrix

$$
\Lambda_{m}=\left(\begin{array}{cc}
D_{m} & 0 \\
0 & D_{m}
\end{array}\right) \text { with } D_{m}=\operatorname{diag}(\underbrace{\frac{1}{\sqrt{\ell(\ell+1)}}, \ldots, \frac{1}{\sqrt{\ell(\ell+1)}}}_{(2 \ell+1) \text { times }})_{1 \leq \ell \leq n_{s p h}}
$$

and, as compared to $S_{0}$, it reduces the computational costs of the $m \times m$ matrix setup of the operator $B(k, \eta)$ in Beyn's algorithm.

For the contour integral in Beyn's method (see Cakoni and Kress ${ }^{4}$ and Beyn ${ }^{19}$ ), we chose ellipses

$$
\partial \Omega=\left\{\frac{k_{\max }+k_{\min }}{2}+\frac{k_{\max }-k_{\min }}{2} \cos t+i \beta \sin t: t \in[0,2 \pi]\right\}
$$

and used 128 quadrature points in the composite trapezoidal rule. Here, $\left(k_{\min }, k_{\max }\right)$ is the interval in which we are searching for the transmission eigenvalues and $\beta=0.01$ corresponds to the minor axis of the ellipse that is chosen rather small. The tolerance in Beyn's algorithm is chosen $10^{-12}$. We consider only the case $n>1$, the transmission eigenvalues for $n<1$ can be computed directly by the relation $k(1 / n)=\sqrt{n} k(n)$ (see also Cakoni and Kress ${ }^{4}$ ).

In the first example, we tested the proposed method for domains with known real interior transmission eigenvalues and consider the unit ball and a peanut shaped domain with the parametrization

$$
z(\theta, \phi)=\frac{3 \sqrt{\cos ^{2} \theta+0.25 \sin ^{2} \theta}}{2} e(\theta, \phi)
$$

where

$$
e(\theta, \phi)=(\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta) .
$$



As refractive index, we chose both $n=4$ and $n=16$. From Table 1, it can be seen that the eigenvalues and their multiplicities as given in the brackets coincide with those in Monk and Sun ${ }^{3}$ for $n=16$ and in Kleefeld ${ }^{16}$ for $n=4$.
In the next example, we consider transmission eigenvalues for ellipsoids

$$
z(\theta, \phi)=(\sin \theta \cos \phi, \sin \theta \sin \phi, C \cos \theta)
$$

for various choices for the axis $C$ (see Figure 1).
According to Theorem 2.5 in Monk and Sun, ${ }^{3}$ the first transmission eigenvalue $k_{1, D}$ for a domain $D$ lies in the interval

$$
\begin{equation*}
\frac{k_{1, n}}{r_{2}} \leq k_{1, D} \leq \frac{k_{1, n}}{r_{1}} \tag{53}
\end{equation*}
$$

where $k_{1}$ is the smallest transmission eigenvalue for the unit ball and a given refractive index $n$; $r_{1}$ is the radius of the largest ball $B_{r_{1}}$ such that $B_{r_{1}} \subset D$, and $r_{2}$ is the radius of the smallest ball $B_{r_{2}}$ such that $D \subset B_{r_{2}}$. Hence, the transmission eigenvalues for a unit ball computed in Table 1 can be used for choosing the interval ( $k_{\text {min }}, k_{\text {max }}$ ) in Beyn's algorithm.

TABLE 1 Benchmark interior
transmission eigenvalues

| $\mathbf{n}=\mathbf{1 6}$ | $\mathbf{n}=\mathbf{4}$ |  |
| :--- | :--- | :--- |
| Unit Ball | Unit Ball | Peanut |
| $1.1654[3]$ | $3.1415[3]$ | $2.9966[2]$ |
| $1.4608[3]$ | $3.4928[5]$ | $3.0393[2]$ |
| $1.4751[5]$ | $3.5928[3]$ | $3.3624[1]$ |
| $1.7640[5]$ | $3.6924[5]$ | $3.4172[1]$ |
| $1.7774[7]$ | $3.9026[7]$ | $3.5150[1]$ |



FIGURE 1 Ellipsoids [Colour figure can be viewed at wileyonlinelibrary.com]


FIGURE 2 Bean-shaped domains [Colour figure can be viewed at wileyonlinelibrary.com]

TABLE 2 Transmission eigenvalues for ellipsoids

| $\mathbf{n}=\mathbf{4}$ |  |  |  | $\mathbf{n}=\mathbf{1 6}$ |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\boldsymbol{C = 0 . 8}$ | $\boldsymbol{C}=\mathbf{0 . 5}$ | $\boldsymbol{C}=\mathbf{0 . 3}$ |  | $\boldsymbol{C}=\mathbf{0 . 8}$ | $\boldsymbol{C}=\mathbf{0 . 5}$ | $\boldsymbol{C}=\mathbf{0 . 3}$ |
| $3.3364[1]$ | $4.2885[1]$ | $5.8344[1]$ |  | $1.2340[1]$ | $1.5009[1]$ | $2.1395[1]$ |
| $3.4080[2]$ | $4.3422[1]$ | $5.8593[2]$ |  | $1.2989[2]$ | $1.7311[2]$ | $2.2301[2]$ |
| $3.7002[2]$ | $4.3836[2]$ | $6.0630[2]$ | $1.5222[2]$ | $1.8272[2]$ | $2.4517[2]$ |  |
| $3.7553[1]$ | $4.4479[2]$ | $6.2544[2]$ | $1.5472[1]$ | $1.9483[1]$ | $2.7021[2]$ |  |
| $3.7687[2]$ | $4.5405[2]$ | $6.5506[2]$ | $1.5778[2]$ | $2.0042[2]$ | $2.8619[2]$ |  |

TABLE 3 Transmission eigenvalues for bean-shaped domain

| $\mathrm{n}=4$ |  |  | $\mathrm{n}=16$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\epsilon=0.1$ | $\epsilon=0.2$ | $\epsilon=0.3$ | $\epsilon=0.1$ | $\epsilon=0.2$ | $\epsilon=0.3$ |
| 3.6204 [1] | 3.7326 [1] | 4.2940 [1] | 1.4010 [1] | 1.4726 [1] | 1.5729 [1] |
| 3.6483 [1] | 3.8266 [1] | 4.3705 [1] | 1.4106 [1] | 1.5022 [1] | 1.5843 [1] |
| 3.8692 [1] | 3.9356 [1] | 4.9770 [1] | 1.4407 [1] | 1.5030 [1] | 1.6219 [1] |
| 3.9110 [1] | 3.9407 [1] | 5.1771 [1] | 1.6206 [1] | 1.6591 [1] | 1.7295 [1] |
| 4.0046 [1] | 4.1786 [1] | 5.7341 [1] | 1.6300 [1] | 1.6997 [1] | 1.7948 [1] |

In the last example, we present transmission eigenvalues for bean-shaped domains with parametrization

$$
z(\theta, \phi)=(a(\theta) \sin \theta \cos \phi, a(\theta) \sin \theta \sin \phi-\epsilon \cos (\pi \cos \theta), \cos \theta)
$$

where $a(\theta)=\sqrt{0.64(1-\epsilon \cos (\pi \cos \theta))}$ and $\epsilon>0$ (see Figure 2).
Tables 2 and 3 illustrate the dependence of the eigenvalues on the refractive index and the geometry, ie, a smaller refractive index or squeezing the domain both lead to an increase of the transmission eigenvalues in agreement with (53).

The imaginary part of all computed eigenvalues is less than $10^{-8}$ except for the bean-shaped domain with $\epsilon=0.3$, where the imaginary part is less than $10^{-6}$. This is due to the concave shape of the domain, the accuracy can be increased by increasing the discretization parameters $n_{\text {sph }}$.

Analogous to the two dimensional case, ${ }^{4}$ the computational cost of the proposed method is about only one-half of that for the two-by-two systems presented in Cakoni et al ${ }^{7}$ and Kleefeld. ${ }^{16}$ This is significant because of the large dimension of the matrices and the vector valued equations.

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